

POSITIVE PERIODIC SOLUTIONS OF INFINITE DELAY FUNCTIONAL DIFFERENTIAL EQUATIONS

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Abstract

In this paper, we employ a fixed point theorem on a cone to study the existence of positive periodic solutions for the following higher-dimensional functional differential equation:

$$\dot{x}(t) + A(t)x(t) = f(t, x_t), \quad t \in \mathbb{R}.$$

Some existence results of multiplicity positive periodic solutions are obtained.

1. Introduction

Recently, by employing Krasnosel'skii fixed point theorem [5] on a cone, Jiang and Wei [4] have investigated the existence of one positive

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periodic solution for functional differential equations of the form

$$\dot{x}(t) = A(t)x(t) + f(t, x_t),$$

where $A(t) = \text{diag}[a_1(t), a_2(t), \dots, a_n(t)]$, $a_j \in C(\mathbb{R}, \mathbb{R})$ is ω -periodic, $f : \mathbb{R} \times BC \rightarrow \mathbb{R}^n$, and $\omega > 0$ is a constant. In this paper, we are concerned with the following functional differential equation:

$$\dot{x}(t) + A(t)x(t) = f(t, x_t), \quad t \in \mathbb{R}, \quad (1)$$

in which $A(t) = \text{diag}[a_1(t), a_2(t), \dots, a_n(t)]$, $a_j \in C(\mathbb{R}, \mathbb{R})$ is ω -periodic, $j = 1, 2, \dots, n$. $f(t, x_t)$ is a function defined on $\mathbb{R} \times BC$, and $f(t, x_t)$ is ω -periodic whenever x is ω -periodic, where BC denotes the Banach space of bounded continuous functions $\phi : \mathbb{R} \rightarrow \mathbb{R}^n$ with the norm $\|\phi\| = \sum_{j=1}^n \sup_{\theta \in \mathbb{R}} |\phi^j(\theta)|$, where $\phi = (\phi^1, \phi^2, \dots, \phi^n)^T$. If $x \in BC$, then $x_t \in BC$ for any $t \in \mathbb{R}$ is defined by $x_t(\theta) = x(t + \theta)$ for $\theta \in \mathbb{R}$. And $\omega > 0$ is a constant.

System (1) was extensively investigated in literature as bio-mathematics models. It contains many bio-mathematics models of delay differential equations or systems, such as the periodic logistic equation with several delays [7]

$$\dot{y}(t) = y(t) \left[a(t) - \sum_{i=1}^n b_i(t)y(t - \tau_i(t)) \right]$$

and the periodic distributed delay Lotka-Volterra competition system [8]

$$\frac{du_i(t)}{dt} = u_i(t) \left[r_i(t) - a_{ii}u_i(t) - \sum_{\substack{j=1 \\ j \neq i}}^n a_{ij} \int_{-T_{ij}}^0 K_{ij}(s)u_j(t+s)ds \right], \quad i = 1, 2, \dots, n.$$

For more information about the applications of system (1) to a variety of population models, we refer to the reader to [2, 3, 6, 10] and the references cited therein. Our purpose of this paper is to study the existence of multiplicity positive periodic solutions of (1) by utilizing a fixed point theorem [1] on a cone.

For convenience, we need to introduce a few notations. Let $\mathbb{R} = (-\infty, +\infty)$, $\mathbb{R}_+ = [0, +\infty)$, and $\mathbb{R}_- = (-\infty, 0]$, respectively. For each $x = (x^1, x^2, \dots, x^n)^T \in \mathbb{R}^n$, the norm of x is defined as $|x| = \sum_{j=1}^n |x^j|$. $\mathbb{R}_+^n = \{(x^1, x^2, \dots, x^n)^T \in \mathbb{R}^n : x^j \geq 0, j = 1, 2, \dots, n\}$. We say that x is *positive* when $x \in \mathbb{R}_+^n$. $BC(\mathbb{X}, \mathbb{Y})$ denotes the set of bounded continuous functions $\phi : \mathbb{X} \rightarrow \mathbb{Y}$.

2. Main Results

The objective of this section is to derive sufficient conditions for two existence results of twin positive periodic solutions of (1). It follows from (1) that

$$x(t) = \int_t^{t+\omega} g(t, s) f(s, x_s) ds, \quad (2)$$

where

$$f(s, x_s) = (f_1(s, x_s), f_2(s, x_s), \dots, f_n(s, x_s))^T$$

and

$$g(t, s) = \text{diag}[g_1(t, s), g_2(t, s), \dots, g_n(t, s)], g_j(t, s) = \frac{\exp\left(\int_t^s a_j(v) dv\right)}{\exp\left(\int_0^\omega a_j(v) dv\right) - 1} \quad (3)$$

for $(t, s) \in \mathbb{R}^2$, $j = 1, 2, \dots, n$.

In what follows, we always assume that

$$(H_1) \quad \int_0^\omega a_j(s) ds \neq 0 \text{ for } j = 1, 2, \dots, n.$$

$$(H_2) \quad f_j(t, \phi_t) \int_0^\omega a_j(s) ds \geq 0 \text{ for all } (t, \phi) \in \mathbb{R} \times BC(\mathbb{R}, \mathbb{R}_+^n), j = 1, 2, \dots, n.$$

$$(H_3) \quad f(t, x_t) \text{ is a continuous function of } t \text{ for each } x \in BC(\mathbb{R}, \mathbb{R}_+^n).$$

(H₄) For any $L > 0$ and $\varepsilon > 0$, there exists $\delta > 0$ such that for $\phi, \psi \in BC$, $\|\phi\| \leq L$, $\|\psi\| \leq L$, and $\|\phi - \psi\| < \delta$ for $s \in [0, \omega]$ imply

$$|f(s, \phi_s) - f(s, \psi_s)| < \varepsilon.$$

Clearly, the denominator in $g_j(t, s)$ is not zero since (H_1) . Note further that

$$p_j := \frac{\exp\left(\int_0^\omega |a_j(v)| dv\right)}{\left|\exp\left(\int_0^\omega a_j(v) dv\right) - 1\right|} \leq |g_j(t, s)| \leq \frac{\exp\left(\int_0^\omega |a_j(v)| dv\right)}{\left|\exp\left(\int_0^\omega a_j(v) dv\right) - 1\right|} =: q_j, \quad (4)$$

for all $s \in [t, t + \omega]$, $j = 1, 2, \dots, n$. And we let $p := \min_{1 \leq j \leq n} p_j$, $q := \max_{1 \leq j \leq n} q_j$.

It is easy to see that $g(t, s) = g(t + \omega, s + \omega)$ for all $(t, s) \in \mathbb{R}^2$ and by (H_2) ,

$$g_j(t, s)f_j(u, \phi_u) \geq 0, \quad j = 1, 2, \dots, n, \quad (5)$$

for $(t, s) \in \mathbb{R}^2$ and $(u, \phi) \in \mathbb{R} \times BC(\mathbb{R}, \mathbb{R}_+^n)$. It is not difficult to verify that any ω -periodic function $x(t)$ that satisfies (2) is also an ω -periodic solution of (1).

Next, we introduce the concerned definition and fixed point theorem that we need in this paper.

Definition. Let \mathbb{X} be a Banach space and K be a closed, nonempty subset of \mathbb{X} . K is a cone if

- (i) $\alpha u + \beta v \in K$ for all $u, v \in K$ and all $\alpha, \beta \geq 0$;
- (ii) $u, -u \in K$ imply $u = 0$.

Theorem A [9]. Let K be a cone in a Banach space E and Ω_1, Ω_2 be two bounded open sets in E such that $0 \in \Omega_1$ and $\overline{\Omega_1} \subset \Omega_2$. Let $T : K \cap (\overline{\Omega_2} \setminus \Omega_1) \rightarrow K$ be completely continuous operator. If

(c₁) there exists $u_0 \in K \setminus \{0\}$ such that $u - Tu \neq \lambda u_0$, $u \in K \cap \partial\Omega_2$, $\lambda \geq 0$; $Tu \neq \mu u$, $u \in K \cap \partial\Omega_1$, $\mu \geq 1$, or

(c₂) there exists $u_0 \in K \setminus \{0\}$ such that $u - Tu \neq \lambda u_0$, $u \in K \cap \partial\Omega_1$, $\lambda \geq 0$; $Tu \neq \mu u$, $u \in K \cap \partial\Omega_2$, $\mu \geq 1$,

then T has at least one fixed point in $K \cap (\overline{\Omega_2} \setminus \Omega_1)$.

Let \mathbb{X} be the set

$$\mathbb{X} = \{x \in C(\mathbb{R}, \mathbb{R}^n) : x(t + \omega) = x(t), t \in \mathbb{R}\}$$

with the linear structure as well as the norm

$$\|x\| = \sum_{j=1}^n |x^j|_0, \quad |x^j|_0 = \sup_{t \in [0, \omega]} |x^j(t)|, \quad j = 1, 2, \dots, n,$$

where $x = (x^1, x^2, \dots, x^n)^T \in \mathbb{R}^n$. Then \mathbb{X} is a Banach space. Define

$$\sigma := \min \left\{ \exp \left(-2 \int_0^\omega |a_j(s)| ds \right), j = 1, 2, \dots, n \right\}$$

and

$$K = \{x \in \mathbb{X} : x^j(t) \geq \sigma |x^j|_0, x = (x^1, x^2, \dots, x^n)^T, t \in [0, \omega]\},$$

one may readily verify that K is a cone in \mathbb{X} .

Now, we define an operator $\Phi : K \rightarrow K$ as

$$(\Phi x)(t) = \int_t^{t+\omega} g(t, s) f(s, x_s) ds$$

for $x \in K$, $t \in \mathbb{R}$, where $g(t, s)$ is defined as that in (3), and $(\Phi x) = (\Phi_1 x, \Phi_2 x, \dots, \Phi_n x)^T$. It is easy to see that a function $x \in \mathbb{X}$ is a solution of (1) if and only if x is a fixed point of the operator equation $x = \Phi x$ in \mathbb{X} .

Lemma 1. *The mapping Φ maps K into K .*

Proof. For any $x \in K$ and $t \in [0, \omega]$, it follows from (H_2) that $(\Phi x)(t)$ is continuous in t and

$$\begin{aligned} (\Phi x)(t + \omega) &= \int_{t+\omega}^{t+2\omega} g(t + \omega, s) f(s, x_s) ds \\ &= \int_t^{t+\omega} g(t + \omega, v + \omega) f(v + \omega, x_{v+\omega}) dv \\ &= \int_t^{t+\omega} g(t, v) f(v, x_v) dv = (\Phi x)(t). \end{aligned}$$

Hence, $(\Phi x) \in \mathbb{X}$. And for $x \in K$, we find

$$|\Phi_j x|_0 \leq q_j \int_0^\omega |f_j(s, x_s)| ds$$

and

$$(\Phi_j x)(t) \geq p_j \int_0^\omega |f_j(s, x_s)| ds \geq \frac{p_j}{q_j} |\Phi_j x|_0 \geq \sigma |\Phi_j x|_0$$

for $t \in [0, \omega]$, $j = 1, 2, \dots, n$. Therefore, $(\Phi x) \in K$. This completes the proof of Lemma 1.

Lemma 2. Suppose (H_1) – (H_4) hold. Let η be a positive number, $\Omega = \{x \in \mathbb{X} : \|x\| < \eta\}$. Then $\Phi : K \cap \overline{\Omega} \rightarrow K$ is completely continuous.

By the continuity of $f(t, x_t)$ and Arzela-Ascoli (Royden [11, p. 169]) theorem, we can easily give the proof of Lemma 2 and we omit it here. The reader can refer to [9].

Theorem 1. Suppose (H_1) – (H_4) hold and there are positive constants r_1, r_2 and r_3 with $r_1 < r_3 < r_2$ such that

$$(H_5) \quad \inf_{\phi \in K, \|\phi\|=r_1} \int_0^\omega |f(s, \phi_s)| ds > \frac{r_1}{p}, \quad \inf_{\phi \in K, \|\phi\|=r_2} \int_0^\omega |f(s, \phi_s)| ds > \frac{r_2}{p};$$

$$(H_6) \quad \sup_{\phi \in K, \|\phi\|=r_3} \int_0^\omega |f(s, \phi_s)| ds < \frac{r_3}{q},$$

where $p := \min_{1 \leq j \leq n} p_j$, $q := \max_{1 \leq j \leq n} q_j$, and p_i, q_i are defined in (4). Then system (1) has at least two positive periodic solutions.

Proof. Let $\Omega_1 = \{u \in \mathbb{X} : \|u\| < r_1\}$. Then for any $u \in K \cap \partial\Omega_1$, we have $u - \Phi u \neq \lambda u_0$, $u_0 \in K \setminus \{0\}$, $\lambda \geq 0$. For the sake of contradiction, we choose $u_0 = (1, 1, \dots, 1)^T \in \mathbb{R}^n$, then $u_0 \in K \setminus \{0\}$. Suppose that there exists $\bar{u} \in K \cap \partial\Omega_1$ such that $\bar{u} - \Phi \bar{u} = \lambda_0 u_0$ for some $\lambda_0 \geq 0$. Then, we have

$$\bar{u}^j(t) = (\Phi_j \bar{u})(t) + \lambda_0, \quad j = 1, 2, \dots, n.$$

From this, the definition of Φ , (4) and (5) it follows that

$$\begin{aligned} |\bar{u}^j|_0 &= \left| \int_0^\omega g_j(t, s) f_j(s, \bar{u}_s) ds + \lambda_0 \right| = \int_0^\omega g_j(t, s) f_j(s, \bar{u}_s) ds + \lambda_0 \\ &\geq p_j \int_0^\omega |f_j(s, \bar{u}_s)| ds + \lambda_0 \geq p \int_0^\omega |f_j(s, \bar{u}_s)| ds + \lambda_0 \\ &\geq p \int_0^\omega |f_j(s, \bar{u}_s)| ds. \end{aligned}$$

Hence, we have

$$r_1 = \|\bar{u}\| \geq p \int_0^\omega |f(s, \bar{u}_s)| ds,$$

which contradicts the first inequality in assumption (H_5) . Therefore, we derive that

$$u - \Phi u \neq \lambda u_0, \forall u_0 \in K \setminus \{0\}, \lambda \geq 0. \quad (6)$$

Let $\Omega_2 = \{u \in \mathbb{X} : \|u\| < r_2\}$. Then for any $u \in K \cap \partial\Omega_2$, applying the second inequality in (H_5) , similarly to the proof of (6), we have $u - \Phi u \neq \lambda u_0$, $u_0 \in K \setminus \{0\}$, $\lambda \geq 0$.

On the other hand, let $\Omega_3 = \{u \in \mathbb{X} : \|u\| < r_3\}$. Then for any $u \in K \cap \partial\Omega_3$, from the definition of Φ , (4) and (5), we have

$$|\Phi_j u|_0 \leq q_j \int_0^\omega |f_j(s, u_s)| ds \leq q \int_0^\omega |f_j(s, u_s)| ds,$$

hence, in view of (H_6) , one has

$$\|\Phi u\| \leq q \int_0^\omega |f(s, u_s)| ds < r_3,$$

that is,

$$\|\Phi u\| < \|u\|, \forall u \in K \cap \partial\Omega_3.$$

Therefore,

$$\Phi u \neq \mu u, \forall u \in K \cap \partial\Omega_3, \mu \geq 1. \quad (7)$$

It is clear that $\Omega_1 \subset \Omega_3 \subset \Omega_2$, by Theorem A, we can conclude that Φ has two fixed points $u_1 \in K \cap (\overline{\Omega_3} \setminus \Omega_1)$ and $u_2 \in K \cap (\overline{\Omega_2} \setminus \Omega_3)$ with $r_1 < \|u_1\| < r_3$, $r_3 < \|u_2\| < r_2$. Therefore, $u_1(t)$ and $u_2(t)$ are positive periodic solutions of system (1). The proof is complete.

Theorem 2. Suppose (H_1) – (H_4) hold and there are positive constants R_1 , R_2 and R_3 with $R_1 < R_3 < R_2$ such that

$$(H_7) \quad \sup_{\phi \in K, \|\phi\|=R_1} \int_0^\omega |f(s, \phi_s)| ds < \frac{R_1}{q}, \quad \sup_{\phi \in K, \|\phi\|=R_2} \int_0^\omega |f(s, \phi_s)| ds < \frac{R_2}{q};$$

$$(H_8) \quad \inf_{\phi \in K, \|\phi\|=R_3} \int_0^\omega |f(s, \phi_s)| ds > \frac{R_3}{p},$$

where $p := \min_{1 \leq j \leq n} p_j$, $q := \max_{1 \leq j \leq n} q_j$, and p_i, q_i are defined in (4). Then

system (1) has at least two positive periodic solutions.

Proof. By condition (H_7) , from the proof of Theorem 1, we know that

$$\Phi u \neq \mu u, \quad \forall u \in K \cap \partial\Omega_4, \mu \geq 1,$$

$$\Phi u \neq \mu u, \quad \forall u \in K \cap \partial\Omega_5, \mu \geq 1,$$

where $\Omega_4 = \{\phi \in \mathbb{X} : \|\phi\| < R_1\}$, $\Omega_5 = \{\phi \in \mathbb{X} : \|\phi\| < R_2\}$.

From condition (H_8) , let $\Omega_6 = \{\phi \in \mathbb{X} : \|\phi\| < R_3\}$, for any $u \in K \cap \partial\Omega_6$, it is similar to the proof of (6), we have

$$u - \Phi u \neq \lambda u_0, \quad \forall u_0 \in K \setminus \{0\}, \lambda \geq 0.$$

It is clear that $\Omega_4 \subset \Omega_6 \subset \Omega_5$, by Theorem A, we can conclude that Φ has two fixed points $u_3 \in K \cap (\overline{\Omega_6} \setminus \Omega_4)$ and $u_4 \in K \cap (\overline{\Omega_5} \setminus \Omega_6)$ with $R_1 < \|u_3\| < R_3$, $R_3 < \|u_4\| < R_2$. Therefore, $u_3(t)$ and $u_4(t)$ are positive periodic solutions of system (1). The proof is complete.

Using the same method of this paper, one can show that

Theorem 3. Suppose that (H_1) – (H_4) hold. If (H_5) , (H_6) hold or (H_7) , (H_8) hold, then the systems

$$x'(t) - A(t)x(t) = -f(t, x_t),$$

$$x'(t) - A(t)x(t) = f(t, x_t),$$

and

$$x'(t) + A(t)x(t) = -f(t, x_t)$$

have at least two positive ω -periodic solutions, respectively.

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