# NEW OSCILLATION CRITERIA FOR SYSTEM OF DIFFERENCE EQUATIONS 

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#### Abstract

In this paper, we provide sufficient conditions for the oscillation of every solution of the systems of difference equations $$
\Delta y_{n}+\sum_{i=1}^{m} P_{i} y_{n-k_{i}}=0, \quad n=0,1,2, \ldots,
$$ where $P_{i} \in \mathbb{R}^{r \times r}$ and $k_{i} \in \mathbb{Z}$ for $i=1,2, \ldots, m$. The conditions are given in terms of the eigenvalues of the $P_{i}$ matrix for $i=1,2, \ldots, m$.


## 1. Introduction

The concept of the oscillatory behaviour of solutions of difference equations has been extensively investigated, see $[1,5]$ and the references
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cited therein. In [5], Ladas established the theorems for the oscillatory behaviour of all solutions for the following difference equations:

$$
\Delta y_{n}+p y_{n-k}=0, \quad n=0,1,2, \ldots
$$

and

$$
\Delta y_{n}+\sum_{i=1}^{m} p_{i} y_{n-k_{i}}=0, \quad n=0,1,2, \ldots
$$

where $p_{i} \in \mathbb{R}$ and $k_{i} \in \mathbb{Z}$ for $i=1,2, \ldots, m$.
In [1], Chuanxi et al. obtained the oscillatory behaviour of all solutions of linear autonomous system of difference equations

$$
\Delta y_{n}+P y_{n-k}=0, \quad n=0,1,2, \ldots
$$

where $P \in \mathbb{R}^{r \times r}$ and $k \in \mathbb{Z}$. Furthermore, they obtained sufficient conditions for the oscillation of all solutions of the system of difference equations

$$
\begin{equation*}
\Delta y_{n}+\sum_{i=1}^{m} P_{i} y_{n-k_{i}}=0, n=0,1,2, \ldots \tag{1.1}
\end{equation*}
$$

by using logarithmic norm of $P$ which is denoted by $\mu(P)$ and defined by

$$
\mu(P)=\max _{\|\xi\|=1}(P \xi, \xi),
$$

where $($, $)$ is an inner product in $\mathbb{R}^{r}$ and $\|\xi\|=(\xi, \xi) \frac{1}{2}, \quad P_{i} \in \mathbb{R}^{r \times r}$ and $k_{i} \in \mathbb{Z}$ for $i=1,2, \ldots, m$.

In the present paper, we obtain sufficient conditions for the oscillation of all solutions of equation (1.1) without using logarithmic norm. Our result improves the known results in [1] and [5]. We believe that the results of this paper are more useful than the results of [1]. Because, in [1], to obtain the oscillatory results of equation (1.1), are required, the calculations of eigenvalues, eigenvectors and logarithmic norms of the matrices $P_{i}$ for $i=1,2, \ldots, m$.

By a solution of equation (1.1), we mean a sequence $\left\{y_{n}\right\}$ of vectors in $\mathbb{R}^{r}$ for $n=0,1,2, \ldots$ which satisfies equation (1.1). A sequence of real numbers $\left\{y_{n}\right\}$ is said to oscillate if the terms $y_{n}$ are not eventually positive or eventually negative. Let $\left\{y_{n}\right\}$ be a solution of equation (1.1) with $y_{n}=$ $\left[y_{n}^{1}, y_{n}^{2}, \ldots, y_{n}^{r}\right]^{T}$ for $n=0,1,2, \ldots$. We say that the solution $\left\{y_{n}\right\}$ oscillates componentwise or simply oscillates if each component $\left\{y_{n}^{i}\right\}$ oscillates. Otherwise the solution is called nonoscillatory.

Let

$$
k=\max \left\{0, k_{1}, k_{2}, \ldots, k_{m}\right\} \quad \text { and } \quad l=\max \left\{1,-k_{1},-k_{2}, \ldots,-k_{m}\right\} .
$$

Then equation (1.1) can be written in the form

$$
\begin{equation*}
\Delta y_{n}+\sum_{j=-k}^{l} Q_{j} y_{n+j}=0, \quad n=0,1,2, \ldots \tag{1.2}
\end{equation*}
$$

Then equation (1.2) is a difference equation of order $(k+l)$. If $k \geq 0$ and $l=1$, then we say that equation (1.2) is a delay difference equation. When $k=0$ and $l \geq 2$, equation (1.2) is called an advanced difference equation. When $k \geq 1$ and $l \geq 2$, then equation (1.2) is of the mixed type.

For the purpose of existence and uniqueness of solutions, we should assume that

$$
\left.\begin{array}{l}
\text { if } l=1 \text {, then } \operatorname{det}\left(Q_{1}+I\right) \neq 0  \tag{1.3}\\
\text { if } k=0 \text { and } l \geq 2 \text {, then } \operatorname{det} Q_{l} \neq 0
\end{array}\right\} \text {. }
$$

Let $a_{-k}, \ldots, a_{l-1}$ be $(k+l)$ given vectors in $\mathbb{R}^{r}$. Then under assumption (1.3), equation (1.2) has a unique solution $\left\{y_{n}\right\}$ which satisfies the initial conditions

$$
y_{i}=a_{i}, \quad i=-k, \ldots, l-1 .
$$

We need the following lemma, which is proved in [3].

Lemma 1.1. Assume that $Q_{1}, Q_{2}, \ldots, Q_{k} \in \mathbb{R}^{r \times r}$ and suppose that condition (1.3) is satisfied. Then the following statements are equivalent:
(a) Every solution of equation (1.2) oscillates componentwise.
(b) The characteristic equation of (1.2),

$$
\begin{equation*}
\operatorname{det}\left[\gamma I-I+\sum_{j=-k}^{l} \gamma^{j} Q_{j}\right]=0 \tag{1.4}
\end{equation*}
$$

has no positive roots.

## 2. Sufficient Conditions for Oscillation of (1.1)

In this section, we obtain sufficient conditions for the oscillation of all solutions of the linear equation with the matrix coefficients of $P_{1}, P_{2}, \ldots, P_{m}$,

$$
\Delta y_{n}+\sum_{i=1}^{m} P_{i} y_{n-k i}=0, \quad n=0,1,2, \ldots
$$

The conditions will be given in terms of the $k_{i}$ and eigenvalues of the matrices $P_{i}$ for each $i=1,2, \ldots, m$.

Throughout this paper, we will use the convention that $0^{0}=1$.
Theorem 2.1. Let $P_{i} \in R^{r \times r}, k_{i} \in\{0,1,2, \ldots\}$ or $k_{i} \in\{\ldots,-3,-2,-1\}$ for $i=1,2, \ldots, m$. Suppose that condition (1.3) is satisfied. Then every solution of equation (1.1) oscillates (componentwise) provided that

$$
\begin{equation*}
\lambda\left(\sum_{i=1}^{m} P_{i} \frac{\left(k_{i}+1\right)^{k_{i}+1}}{k_{i}^{k_{i}}}\right)>1, \tag{2.1}
\end{equation*}
$$

where $\lambda(P)$ denotes for any real eigenvalues of $P$.
Proof. If $k_{i}=k$ for all $i=1,2, \ldots, m$, then every solution of equation (1.1) oscillates if and only if

$$
\lambda\left(\sum_{i=1}^{m} P_{i}\right)>\frac{k^{k}}{(k+1)^{k+1}},
$$

which is given in [1]. Thus, we assume to the case when $k_{i} \neq k$ for all $i=1,2, \ldots, m$. First, assume that $k_{i} \in\{0,1,2, \ldots\}$ for $i=1,2, \ldots, m$. Assume, for the sake of contradiction, that characteristic equation of equation (1.1),

$$
\begin{equation*}
\operatorname{det}\left[(\gamma-1) I+\sum_{i=1}^{m} P_{i} \gamma^{-k_{i}}\right]=0 \tag{2.2}
\end{equation*}
$$

has a $\gamma_{0}$ positive root. If $\gamma_{0} \in(1, \infty)$, then equation (2.2) becomes

$$
\operatorname{det}\left[I+\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(\gamma_{0}-1\right)}\right]=0
$$

and

$$
\operatorname{det}\left[I-\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right]=0 .
$$

Hence we say that all eigenvalues of the matrix $\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}$ are one. That is

$$
\lambda\left(\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right)=1
$$

But, by condition (2.1), this is impossible, indeed we observe that for $i=$ $1,2, \ldots, m$,

$$
\lim _{\gamma_{0} \rightarrow \infty} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}=-\infty \quad \text { and } \quad \lim _{\gamma_{0} \rightarrow 1^{+}} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}=0,
$$

then from (2.1), we have

$$
\lambda\left(\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right)<0 .
$$

If $\gamma_{0} \in(0,1)$, then equation (2.2) becomes

$$
\operatorname{det}\left[I-\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right]=0
$$

this implies that

$$
\lambda\left(\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right)=1
$$

Otherwise, we have for $i=1,2, \ldots, m$,

$$
\inf _{0<\gamma_{0}<1} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}=\frac{\left(k_{i}+1\right)^{k_{i}+1}}{k_{i}^{k_{i}}}
$$

Then we get

$$
\lambda\left(\sum_{i=1}^{m} P_{i} \frac{\left(k_{i}+1\right)^{k_{i}+1}}{k_{i}^{k_{i}}}\right) \leq 1
$$

which is a contradiction to (2.1).
If $\gamma_{0}=1$, then equation (2.2) becomes

$$
\operatorname{det}\left[\sum_{i=1}^{m} P_{i}\right]=0
$$

and also

$$
\operatorname{det}\left[\sum_{i=1}^{m} P_{i} \frac{\left(k_{i}+1\right)^{k_{i}+1}}{k_{i}^{k_{i}}}\right]=0,
$$

which means that at least eigenvalue of the matrix $\sum_{i=1}^{m} P_{i} \frac{\left(k_{i}+1\right)^{k_{i}+1}}{k_{i}^{k_{i}}}$ is zero. So, we obtain a contradiction to (2.1).

Next, assume that $k_{i} \in\{\ldots,-3,-2,-1\}$ for $i=1,2, \ldots, m$. If $\gamma_{0} \in(0,1)$, then

$$
\operatorname{det}\left[I-\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right]=0 .
$$

Hence we say that

$$
\lambda\left(\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right)=1
$$

but, by condition (2.1), this is impossible, indeed we observe that for $i=$ $1,2, \ldots, m$,

$$
\lim _{\gamma_{0} \rightarrow 0^{+}} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)} \quad \text { and } \quad \lim _{\gamma_{0} \rightarrow 1^{-}} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}=\infty,
$$

then, under condition (2.1), we have

$$
\lambda\left(\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right)<0 .
$$

If $\gamma_{0} \in(1, \infty)$, then equation (2.2) becomes

$$
\operatorname{det}\left[I+\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(\gamma_{0}-1\right)}\right]=0
$$

and

$$
\operatorname{det}\left[I-\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right]=0,
$$

this implies that

$$
\lambda\left(\sum_{i=1}^{m} P_{i} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}\right)=1
$$

but, by condition (2.1), this is impossible, indeed, we have for $i=1,2, \ldots, m$,

$$
\max _{\gamma_{0}>1} \frac{\gamma_{0}^{-k_{i}}}{\left(1-\gamma_{0}\right)}=\frac{\left(k_{i}+1\right)^{k_{i}+1}}{k_{i}^{k_{i}}}
$$

then we get

$$
\lambda\left(\sum_{i=1}^{m} P_{i} \frac{\left(k_{i}+1\right)^{k_{i}+1}}{k_{i}^{k_{i}}}\right) \leq 1
$$

which is a contradiction to (2.1).
If $\gamma_{0}=1$, then we also obtain a contradiction to (2.1) as above. Thus the proof is complete.

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