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# A 195, 747, 435 VERTEX GRAPH RELATED TO THE FISHER GROUP $F i_{23}$, I 

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#### Abstract

The 195, 747, 435 vertex graph studied here is the point-line collinearity graph of a geometry for the second largest Fischer group $F i_{23}$. In this paper and [7] a detailed description of this graph is obtained.


## 1. Introduction

It is the aim of this paper and [6] to lay bare the bones of $\mathcal{G}$, the point-line collinearity graph of $\Gamma$ where $\Gamma$ is a geometry associated with the second largest Fischer group $F i_{23}$. The geometry $\Gamma$ has rank 4 and is closely related to the transpositions of $F i_{23}$. Diagrammatically we may describe $\Gamma$ as follows:
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The groups listed at the top are the stabilizers in $F i_{23}$ of the various objects in $\Gamma$ - we have also given a description of each type of object in "transposition language" (see [1; p. 177] for more on this). The geometric names above are those we will use and are just meant to be names with no projective geometry connotations whatsoever.

Our anatomical description of $\mathcal{G}$ is given in terms of the geometry $\Gamma$. Consequently the residue of a point - intimately connected with the Steiner system $S(23,7,4)$ - is to the forefront in all that follows. Also very much in evidence is the residue of a hyperplane - we rely upon [5] for information about this geometry. A detailed discussion of $\Gamma$ as it relates to $\mathcal{G}$ will be given in Section 2 though we remark here that $F i_{23}$ acts flag transitively on $\Gamma$ and so, in particular, is a subgroup of Aut $\mathcal{G}$ acting transitively on the $195,747,435$ vertices of $\mathcal{G}$. Also we note that $\mathcal{G}$ may be viewed as the graph where vertices are the bases (23 pair-wise commuting transpositions) with two vertices joined whenever they intersect in a heptad (of transpositions).

We now state our main results on the structure of $\mathcal{G}$. Our first theorem is a broad-brush description of $\mathcal{G}$. This also appears in [4;2.21(iv)] and was obtained using extensive machine calculations. The results given in the present paper and [6] do not rely upon any machine calculations and moreover, Theorems 2-16 paint a much more detailed picture of the structure of $\mathcal{G}$. This detailed data on the point distribution of line orbits is deployed in the study [7] of the point-line collinearity graph of the maximal 2-local geometry for $F i_{24}^{\prime}$, the largest simple Fischer group.

From now on we put $G=F i_{23}$.
Theorem 1. Let a be a fixed point of $\mathcal{G}$. Then $G_{a}$ has 16 orbits $\Delta_{j}^{i}(a)$ upon the points of $\mathcal{G}$ whose sizes and collapsed adjacencies are given in Table 1 and Figure 1.

| $\Delta_{j}^{i}(a)$ | $\left\|\Delta_{j}^{i}(a)\right\|$ |  | $\Delta_{j}^{i}(a)$ | $\left\|\Delta_{j}^{i}(a)\right\|$ |  | $\Delta_{j}^{i}(a)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\Delta_{1}(a)$ | 2.11 .23 |  | $\Delta_{3}^{3}(a)$ | $2^{10} .7 .11 .23$ |  | $\Delta_{4}^{2}(a)$ |
| $\Delta_{2}^{1}(a)$ | $2^{4} .7 .11 .23$ |  | $\Delta_{3}^{4}(a)$ | $2^{12}(a) \mid$ |  |  |
| $\Delta_{2}^{2}(a)$ | $2^{6} .7 .11 .23$ |  | $\Delta_{3}^{5}(a)$ | $2^{12} .3 .11 .23$ | $\Delta_{4}^{3}(a)$ | $2^{12} .5 .7 .11 .23$ |
| $\Delta_{3}^{1}(a)$ | $2^{9} .11 .23$ |  | $\Delta_{3}^{6}(a)$ | $2^{9} .5 .7 .11 .23$ |  | $\Delta_{4}^{4}(a)$ |
| $\Delta_{3}^{2}(a)$ | $2^{8} .3 .5 .11 .23$ | $\Delta_{4}^{1}(a)$ | $2^{13} .3 .3 .7 .23 .11 .23$ | $\Delta_{4}^{5}(a)$ | $2_{4}^{4}(a)$ | $2^{15} .11 .23$ |
| $2^{15} .7 .11 .23$ |  |  |  |  |  |  |

Table 1.
The finer structure of $\mathcal{G}$, from which the information in Theorem 1 is derived, is the subject of Theorems 2-16. In each of these results $a$ is a fixed point of $\mathcal{G}$ and for $x \in \Delta_{j}^{i}(a)$ we give the point distribution for each representative line $l$ in a $G_{a x}$-orbit on $\Gamma_{1}(x)$. That is we state in which $G_{a}$-orbit each of the three points incident with $l$ belong. So, for example, in Theorem 4 of the three points incident with $l \in \alpha_{1,1}(x, x+b, X(x, a))$ one is in $\Delta_{2}^{2}(a)$, one is in $\Delta_{3}^{3}(a)$ and one is in $\Delta_{3}^{2}(a)$ while for $l \in$ $\alpha_{3,1}(x, x+b, X(x, a))$ one point is in $\Delta_{2}^{2}(a)$ and the other two in $\Delta_{3}^{3}(a)$.

The notation and conventions relating to the descriptions of $G_{a x}{ }^{-}$ orbits on $\Gamma_{1}(x)$, as well as definitions of the $\Delta_{j}^{i}(a)$, are to be found in Section 2.

Theorem 2. Let $x \in \Delta_{1}(a)$. Then $G_{a x} \sim 2^{10} 2^{4} A_{7}$ (with $G_{a x}^{* x} \sim$ $2^{4} A_{7}$ ) has 3 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

$$
\begin{array}{ccc}
\text { ORBIT } & \text { SIZE } & \text { POINT DISTRIBUTION } \\
\{x+a\} & 1 & \{a\} 2 \Delta_{1} \\
\alpha_{1}(x, x+a) & 112 & \Delta_{1} 2 \Delta_{2}^{2} \\
\alpha_{3}(x, x+a) & 140 & \Delta_{1} 2 \Delta_{2}^{1}
\end{array}
$$



Figure 1.

Theorem 3. Let $x \in \Delta_{2}^{1}(a)$. Then $G_{a x} \sim 2^{7} 2^{4} S_{5} 3$ (with $G_{a x}^{* x} \sim$ $\left.2^{4} S_{5} 3\right)$ has 4 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\alpha_{3}(x, T(x, a))$ | 5 | $\Delta_{1} 2 \Delta_{2}^{1}$ |
| $\alpha_{2}(x, T(x, a))$ | 48 | $\Delta_{1}^{2} 2 \Delta_{3}^{1}$ |
| $\alpha_{0}(x, T(x, a))$ | 80 | $\Delta_{2}^{1} 2 \Delta_{3}^{6}$ |
| $\alpha_{1}(x, T(x, a))$ | 120 | $\Delta_{2}^{1} 2 \Delta_{3}^{2}$ |

For $x$ in either of the $G_{a}$-orbits $\Delta_{2}^{2}(a), \Delta_{3}^{2}(a), \Delta_{3}^{3}(a), \Delta_{3}^{4}(a)$ there is a unique hyperplane which is incident with both $a$ and $x$. We denote this unique hyperplane by $X(a, x)$ (when viewed as being in $\Gamma_{a}$ ) and $X(x, a)$ (when viewed as being in $\left.\Gamma_{x}\right)$ - note that $X(a, x)$ and $X(x, a)$ both denote the same hyperplane of $\Gamma$.

Theorem 4. Let $x \in \Delta_{2}^{2}(a)$. Then $G_{a x} \sim 2^{5} 2^{4} A_{6}$ (with $G_{a x}^{* x} \sim$ $2^{4} A_{6}$ ) has 5 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\{x+b\}$ | 1 | $\Delta_{1} 2 \Delta_{2}^{2}$ |
| $\alpha_{1,1}(x, x+b, X(x, a))$ | 16 | $\Delta_{2}^{2} \Delta_{3}^{3} \Delta_{3}^{4}$ |
| $\alpha_{3,1}(x, x+b, X(x, a))$ | 60 | $\Delta_{2}^{2} 2 \Delta_{3}^{2}$ |
| $\alpha_{3,0}(x, x+b, X(x, a))$ | 80 | $\Delta_{2}^{2} 2 \Delta_{3}^{6}$ |
| $\alpha_{1,0}(x, x+b, X(x, a))$ | 96 | $\Delta_{2}^{2} 2 \Delta_{3}^{5}$ |

Theorem 5. Let $x \in \Delta_{3}^{1}(a)$. Then $G_{a x} \sim 2^{2} L_{3}(4) 2$ (with $G_{a x}^{* x} \sim$ $\left.L_{3}(4) 2\right)$ has 3 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\alpha_{2}(x, D(x, a))$ | 21 | $\Delta_{2}^{1} 2 \Delta_{3}^{1}$ |
| $\alpha_{1}(x, D(x, a))$ | 112 | $\Delta_{3}^{1} 2 \Delta_{3}^{3}$ |
| $\alpha_{0}(x, D(x, a))$ | 120 | $\Delta_{3}^{1} 2 \Delta_{4}^{1}$ |

Theorem 6. Let $x \in \Delta_{3}^{2}(a)$. Then $G_{a x} \sim\left[2^{7}\right] L_{3}(2)$ (with $G_{a x}^{* x} \sim$ $\left.2^{3} L_{3}(2)\right)$ has 6 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\alpha_{0,1}(x, O(x, a), X(x, a))$ | 7 | $\Delta_{2}^{1} 2 \Delta_{3}^{2}$ |
| $\alpha_{0,0}(x, O(x, a), X(x, a))$ | 8 | $\Delta_{3}^{2} 2 \Delta_{4}^{2}$ |
| $\alpha_{4,1}(x, O(x, a), X(x, a))$ | 14 | $\Delta_{2}^{2} 2 \Delta_{3}^{2}$ |
| $\alpha_{2,1}(x, O(x, a), X(x, a))$ | 56 | $\Delta_{3}^{2} 2 \Delta_{3}^{3}$ |
| $\alpha_{4,0}(x, O(x, a), X(x, a))$ | 56 | $\Delta_{3}^{2} 2 \Delta_{4}^{3}$ |
| $\alpha_{2,0}(x, O(x, a), X(x, a))$ | 112 | $\Delta_{3}^{2} 2 \Delta_{4}^{1}$ |

Theorem 7. Let $x \in \Delta_{3}^{3}(a)$. Then $G_{a x} \sim 22^{4} A_{6}$ (with $\left.G_{a x}^{* x} \sim 2^{4} A_{6}\right)$ has 5 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\{x+b\}$ | 1 | $\Delta_{2}^{2} \Delta_{3}^{3} \Delta_{3}^{4}$ |
| $\alpha_{1,1}(x, x+b, X(x, a))$ | 16 | $\Delta_{3}^{1} 2 \Delta_{3}^{3}$ |
| $\alpha_{3,1}(x, x+b, X(x, a))$ | 60 | $\Delta_{3}^{2} 2 \Delta_{3}^{3}$ |
| $\alpha_{3,0}(x, x+b, X(x, a))$ | 80 | $\Delta_{3}^{3} 2 \Delta_{4}^{6}$ |
| $\alpha_{1,0}(x, x+b, X(x, a))$ | 96 | $\Delta_{3}^{3} 2 \Delta_{4}^{4}$ |

Theorem 8. Let $x \in \Delta_{3}^{4}(a)$. Then $G_{a x} \sim 2 M_{22}$ (with $G_{a x}^{* x} \sim M_{22}$ ) has 2 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\alpha_{1}(x, X(x, a))$ | 77 | $\Delta_{2}^{2} \Delta_{3}^{3} \Delta_{3}^{4}$ |
| $\alpha_{0}(x, X(x, a))$ | 176 | $\Delta_{3}^{4} 2 \Delta_{4}^{5}$ |

Theorem 9. Let $x \in \Delta_{3}^{5}(a)$. Then $G_{a x} \sim 2^{4} A_{5}$ (with $G_{a x}^{* x} \sim 2^{4} A_{5}$ ) has 6 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\{x+b\}$ | 1 | $\Delta_{2}^{2} 2 \Delta_{3}^{5}$ |
| $\alpha_{1}(x, x+b,+)$ | 16 | $\Delta_{3}^{5} \Delta_{4}^{4} \Delta_{4}^{5}$ |
| $\alpha_{3}^{(1)}(x, x+b,-)$ | 40 | $\Delta_{3}^{5} 2 \Delta_{4}^{3}$ |
| $\alpha_{3}^{(2)}(x, x+b,-)$ | 40 | $\Delta_{3}^{5} \Delta_{4}^{5} \Delta_{4}^{6}$ |
| $\alpha_{3}(x, x+b,+)$ | 60 | $\Delta_{3}^{5} \Delta_{4}^{1} \Delta_{4}^{3}$ |
| $\alpha_{1}(x, x+b,-)$ | 96 | $2 \Delta_{3}^{5} \Delta_{4}^{6}$ |

Theorem 10. Let $x \in \Delta_{3}^{6}(a)$. Then $G_{a x} \sim\left[2^{9}\right] 3^{2}$ (with $G_{a x}^{* x} \sim$ $\left.\left[2^{7}\right] 3^{2}\right)$ has 7 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\{x+b\}$ | 1 | $\Delta_{2}^{1} 2 \Delta_{3}^{6}$ |
| $\alpha_{3,3}(x, x+b, T R I)$ | 4 | $\Delta_{2}^{2} 2 \Delta_{3}^{6}$ |
| $\alpha_{3,0}(x, x+b, T R I)$ | 16 | $\Delta_{3}^{6} \Delta_{4}^{2} \Delta_{4}^{3}$ |
| $\alpha_{1,1}(x, x+b, T R I)$ | 48 | $\Delta_{3}^{6} 2 \Delta_{4}^{3}$ |
| $\alpha_{3,2}(x, x+b, T R I)$ | 48 | $\Delta_{3}^{6} 2 \Delta_{4}^{1}$ |
| $\alpha_{1,0}(x, x+b, T R I)$ | 64 | $\Delta_{3}^{6} \Delta_{4}^{5} \Delta_{4}^{6}$ |
| $\alpha_{3,1}(x, x+b, T R I)$ | 72 | $\Delta_{3}^{6} 2 \Delta_{4}^{1}$ |

Theorem 11. Let $x \in \Delta_{4}^{1}(a)$. Then $G_{a x} \sim 2 L_{3}(2) 2$ (with $G_{a x}^{* x} \sim$ $\left.L_{3}(2) 2\right)$ has 8 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\{x+b\}$ | 1 | $\Delta_{3}^{1} 2 \Delta_{4}^{1}$ |
| $\alpha_{3,2}(x, x+b, D U A D)$ | 7 | $\Delta_{3}^{2} 2 \Delta_{4}^{1}$ |
| $\alpha_{1,2}(x, x+b, D U A D)$ | 14 | $\Delta_{3}^{6} 2 \Delta_{4}^{1}$ |
| $\alpha_{3,0}^{\mathcal{L}}(x, x+b, D U A D)$ | 21 | $\Delta_{3}^{6} 2 \Delta_{4}^{1}$ |
| $\alpha_{1,1}(x, x+b, D U A D)$ | 42 | $\Delta_{3}^{5} \Delta_{4}^{1} \Delta_{4}^{3}$ |
| $\alpha_{1,0}(x, x+b, D U A D)$ | 56 | $\Delta_{4}^{1} 2 \Delta_{4}^{6}$ |
| $\alpha_{3,0}^{\mathcal{C}}(x, x+b, D U A D)$ | 56 | $\Delta_{4}^{1} \Delta_{4}^{4} \Delta_{4}^{6}$ |
| $\alpha_{3,1}(x, x+b, D U A D)$ | 56 | $\Delta_{4}^{1} 2 \Delta_{4}^{4}$ |

Theorem 12. Let $x \in \Delta_{4}^{2}(a)$. Then $G_{a x} \cong A_{8}$ (with $G_{a x}^{* x} \cong A_{8}$ ) has 3 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\alpha_{0}(x, O(x, a))$ | 15 | $\Delta_{3}^{2} 2 \Delta_{4}^{2}$ |
| $\alpha_{4}(x, O(x, a))$ | 70 | $\Delta_{3}^{6} \Delta_{4}^{2} \Delta_{4}^{3}$ |
| $\alpha_{2}(x, O(x, a))$ | 168 | $\Delta_{4}^{2} 2 \Delta_{4}^{4}$ |

Theorem 13. Let $x \in \Delta_{4}^{3}(a)$. Then $G_{a x} \sim\left[2^{6}\right] 3^{2}$ (with $G_{a x}^{* x} \sim$ $\left.\left[2^{6}\right] 3^{2}\right)$ has 8 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\alpha_{3,4 \mid 0}(x, T R I, O C T)$ | 2 | $\Delta_{3}^{6} \Delta_{4}^{2} \Delta_{4}^{3}$ |
| $\alpha_{3,0}(x, T R I, O C T)$ | 3 | $\Delta_{3}^{2} 2 \Delta_{4}^{3}$ |
| $\alpha_{1,0}(x, T R I, O C T)$ | 12 | $\Delta_{3}^{6} 2 \Delta_{4}^{3}$ |
| $\alpha_{0,3 \mid 1}(x, T R I, O C T)$ | 32 | $2 \Delta_{4}^{3} \Delta_{4}^{5}$ |
| $\alpha_{1,2 \mid 2}(x, T R I, O C T)$ | 36 | $\Delta_{3}^{5} \Delta_{4}^{1} \Delta_{4}^{3}$ |
| $\alpha_{0,1 \mid 1}(x, T R I, O C T)$ | 48 | $\Delta_{3}^{5} 2 \Delta_{4}^{3}$ |
| $\alpha_{2,1 \mid 1}(x, T R I, O C T)$ | 48 | $\Delta_{4}^{3} \Delta_{4}^{4} \Delta_{4}^{6}$ |
| $\alpha_{1,2 \mid 0}(x, T R I, O C T)$ | 72 | $\Delta_{4}^{3} 2 \Delta_{4}^{6}$ |

Theorem 14. Let $x \in \Delta_{4}^{4}(a)$. Then $G_{a x} \cong L_{2}(11)$ (with $G_{a x}^{* x} \cong$ $\left.L_{2}(11)\right)$ has 6 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

$$
\begin{array}{ccc}
\text { ORBIT } & \text { SIZE } & \text { POINT DISTRIBUTION } \\
\alpha_{1}(x, E N D,+) & 11 & \Delta_{4}^{2} 2 \Delta_{4}^{4} \\
\alpha_{1}(x, E N D,-) & 11 & \Delta_{3}^{3} 2 \Delta_{4}^{4} \\
\alpha_{5}(x, E N D,+) & 11 & \Delta_{3}^{5} \Delta_{4}^{4} \Delta_{4}^{5} \\
\alpha_{3}(x, E N D,+) & 55 & \Delta_{4}^{1} \Delta_{4}^{4} \Delta_{4}^{6} \\
\alpha_{5}(x, E N D,-) & 55 & \Delta_{4}^{3} \Delta_{4}^{4} \Delta_{4}^{6} \\
\alpha_{3}(x, E N D,-) & 110 & \Delta_{4}^{4} 2 \Delta_{4}^{4}
\end{array}
$$

Theorem 15. Let $x \in \Delta_{4}^{5}(a)$. Then $G_{a x} \cong A_{7}$ (with $G_{a x}^{* x} \cong A_{7}$ ) has 5 orbits on $\Gamma_{1}(x)$ with point distribution as follows:

$$
\begin{array}{ccc}
\text { ORBIT } & \text { SIZE } & \text { POINT DISTRIBUTION } \\
\{x+b\} & 1 & \Delta_{3}^{4} 2 \Delta_{4}^{5} \\
\alpha_{3}(x, x+b,+) & 35 & \Delta_{3}^{6} \Delta_{4}^{5} \Delta_{4}^{6} \\
\alpha_{1}(x, x+b,+) & 42 & \Delta_{3}^{5} \Delta_{4}^{4} \Delta_{4}^{5} \\
\alpha_{1}(x, x+b,-) & 70 & 2 \Delta_{4}^{3} \Delta_{4}^{5} \\
\alpha_{3}(x, x+b,-) & 105 & \Delta_{3}^{5} \Delta_{4}^{5} \Delta_{4}^{6}
\end{array}
$$

Theorem 16. Let $x \in \Delta_{4}^{6}(a)$. Then $G_{a x} \sim\left(3 \times A_{5}\right) 2$ (with $G_{a x}^{* x} \sim$ $\left.\left(3 \times A_{5}\right) 2\right)$, $G_{a x}^{* x}$ being the normalizer in $G_{x}^{* x}$ of a group of order 3) has 8 orbits on $\Gamma_{1}(x)$ with point distribution as follows.

| ORBIT | SIZE | POINT DISTRIBUTION |
| :---: | :---: | :---: |
| $\alpha_{0,4}(x, T R I, F I X)$ | 5 | $\Delta_{3}^{3} 2 \Delta_{4}^{6}$ |
| $\alpha_{3,1}(x, T R I, F I X)$ | 5 | $\Delta_{3}^{6} \Delta_{4}^{5} \Delta_{4}^{6}$ |
| $\alpha_{0,0}(x, T R I, F I X)$ | 15 | $\Delta_{3}^{5} \Delta_{4}^{5} \Delta_{4}^{6}$ |
| $\alpha_{2,0}(x, T R I, F I X)$ | 18 | $2 \Delta_{3}^{5} \Delta_{4}^{6}$ |
| $\alpha_{1,3}(x, T R I, F I X)$ | 30 | $\Delta_{4}^{1} \Delta_{4}^{4} \Delta_{4}^{6}$ |
| $\alpha_{2,2}(x, T R I, F I X)$ | 30 | $\Delta_{4}^{3} \Delta_{4}^{4} \Delta_{4}^{6}$ |
| $\alpha_{0,2}(x, T R I, F I X)$ | 60 | $\Delta_{4}^{1} 2 \Delta_{4}^{6}$ |
| $\alpha_{1,1}(x, T R I, F I X)$ | 90 | $\Delta_{4}^{3} 2 \Delta_{4}^{6}$ |

In the present paper we explore $\mathcal{G}$ as far as the third disc $\Delta_{3}(a)$, where $a$ is a fixed point of $\mathcal{G}$. The analysis of $\Delta_{3}(a)$ is completed in [6] where we also carry out the dissection of $\Delta_{4}(a)$. We now discuss the contents of this paper and highlight some important features of the proofs of Theorems 1-16.

Section 2 begins with a quick reminder of some standard geometric notation before giving the promised further details on $\Gamma$. Then follows a long list of orbits on $\Gamma_{1}(x)\left(x \in \Gamma_{0}\right)$ for a variety of subgroups of $G_{x}^{* x} \cong$ $M_{23}$. These orbits, and particularly their combinatorial description, lie at the heart of many of our later arguments.

The peeling back of the flesh of $\mathcal{G}$ gets underway in Section 3 where we examine the first two discs $\Delta_{1}(a)$ and $\Delta_{2}(a)$. We soon learn that $\Delta_{2}(a)$ is the union of two $G_{a}$-orbits, $\Delta_{2}^{1}(a)$ and $\Delta_{2}^{2}(a)$. The former of these $G_{a}$-orbits furnishes us with a useful configuration which we call a diamond. These are discussed after Lemma 3.9 with some of their properties stated in Lemmas 3.10 and 3.11. Diamonds are often used in the following way. We begin with a point, say $x$ of $\mathcal{G}$ and two lines $x+y$
and $x+z$ (in $\left.\Gamma_{1}(x)\right)$ with $x+z \in \alpha_{3}(x, x+y)$. (For an explanation of $x+y, x+z$ and $\alpha_{3}(x, x+y)$, see Section 2.) Usually, from the choice of $x+y$ and $x+z$ we will know to which $G_{a}$-orbit $x, y$ and $z$ belong. Then shifting our view to other points of the diamond we seek to identify to which $G_{a}$-orbit they belong and as a consequence further increase our knowledge of $\mathcal{G}$. This type of strategy is frequently employed in [6] - for an inkling of what is in store see Lemma 4.5(iii). Also in Section 3 we meet $\tau(x)$. Lemma 3.2 gives a property of $\tau(x)$ that we use time and again.

In Section 4 we start to look at $\Delta_{3}(a)$ - this set breaks up into six $G_{a}$-orbits. For four of these orbits $\left(\Delta_{3}^{i}(a), i=1,2,3,4\right)$ we see that $\Gamma_{3}(a, x) \neq \emptyset$ (where $\left.x \in \Delta_{3}^{i}(a), i \in\{1,2,3,4\}\right)$. So, particularly in the light of Lemma 4.3, this is why hyperplane residues are important. For subsequent work in [6] on $\Delta_{4}(a)$ we single out for mention the summary results Lemmas 4.8 and 4.11 and Theorem 4.13.

At certain points in this paper and [6] we will draw pictures depicting portions of $\mathcal{G}$. Rather than drawing

$a, b, c$ points of $\mathcal{G}$; so $\left.\{a, b, c\}=\Gamma_{0}(l)\right)$ for some line lof $\Gamma$ by Lemma 3.4) we usually draw


This is to simplify our pictures - usually we will have begun with collinear points $a$ and $c$ (adjacent points of $\mathcal{G}$ ) and later $b$ comes in for attention. So, for example, the situation in Lemma 3.10 (using the notation there) is drawn thus


We will follow the ATLAS [1] in our description of group structures and our group theoretic notation is standard as given in either [3] or [8]. Also, if $H$ and $K$ are groups, $H \sim K$ means that $H$ and $K$ have the
same shape. Finally, we recommend the reader to also look on Figure 1 as a useful navigational aid for keeping track of our whereabouts in the graph.

## 2. Notation and Line Orbits

First we review some standard geometric notation and begin by recalling the definition of a geometry. A geometry $\Gamma$ is, strictly, a triple $(\Gamma, t, *)$ where $\Gamma$ is a set, $t$ is the type map $(t: \Gamma \rightarrow\{0,1, \ldots, n-1\})$ and $*$ is a symmetric incidence relation on $\Gamma$ with the property that whenever $x * y(x, y \in \Gamma)$ then $t(x) \neq t(y)$. If $t$ is onto, then $\Gamma$ is said to have rank $n$.

Let $i \in\{0,1, \ldots, n-1\}, x \in \Gamma$ and $\Sigma \subseteq \Gamma$. Then

$$
\begin{aligned}
\Gamma_{i} & :=\{y \in \Gamma \mid \tau(y)=i\} \text { (the objects of } \Gamma \text { of type } i) ; \\
\Gamma_{x} & :=\{y \in \Gamma \mid x * y\} \text { (the residue geometry of } x) ; \\
\Gamma(\Sigma) & :=\{y \in \Gamma \mid x * y \text { for all } x \in \Sigma\} ; \text { and } \\
\Gamma_{i}(\Sigma) & :=\Gamma_{i} \cap \Gamma(\Sigma) .
\end{aligned}
$$

If $\Sigma=\left\{x_{1}, \ldots, x_{k}\right\}$, then we write $\Gamma\left(x_{1}, \ldots, x_{k}\right)$ and $\Gamma_{i}\left(x_{1}, \ldots, x_{k}\right)$ instead of $\Gamma\left(\left\{x_{1}, \ldots, x_{k}\right\}\right)$ and $\Gamma_{i}\left(\left\{x_{1}, \ldots, x_{k}\right\}\right)$. Note that $\Gamma_{i}(x)=\Gamma_{x} \cap$ $\Gamma_{i}$. If $G$ is a subgroup of Aut $\Gamma$, then $G_{\Sigma}$ or $G_{x_{1} \ldots, x_{k}}$ denotes the subgroup of $G$ fixing every object in $\Sigma=\left\{x_{1}, \ldots, x_{k}\right\}$. For $g \in G$ and $x \in \Gamma, x^{g}$ is the image of $x$ under $g$. Also we define

$$
Q(x):=\left\{g \in G_{x} \mid g \text { fixes every object in } \Gamma_{x}\right\}
$$

So $Q(x)$ is a normal subgroup of $G_{x}$. For $H \leq G_{x}$ we denote $H Q(x) / Q(x)$ by $H^{* x}$.

From now on $\Gamma$ will be the rank 4 geometry introduced in Section 1 upon which $G=F i_{23}$ acts flag transitively and $\mathcal{G}$ the point-line
collinearity graph of $\Gamma$. The graph distance metric in $\mathcal{G}$ will be denoted by $d($,$) , and for x \in \Gamma_{0}$

$$
\Delta_{i}(x)=\left\{y \in \Gamma_{0} \mid d(y, x)=i\right\}(\text { the } i \text { th disc of } x) .
$$

For $x, y \in \Gamma_{0}$, we put $\{x, y\}^{\perp}=\Delta_{1}(x) \cap \Delta_{1}(y)$.
Next we survey the properties of $\Gamma$ that will be used in our analysis of $\mathcal{G}$. First we recall that $\Gamma$ is a string geometry (meaning that for $0 \leq i<j<k \leq 3$ and $a_{r} \in \Gamma_{r}, r \in\{i, j, k\}, a_{i} * a_{j}$ and $a_{j} * a_{k}$ implies that $\left.a_{i} * a_{k}\right)$. Not surprisingly, in examining $\mathcal{G}$ the most important subgeometry of $\Gamma$ is $\Gamma_{x}$, the residue geometry of a point $x$. Here we have $G_{x} / Q(x) \cong M_{23}$ with $Q(x)$ being the 11-dimensional irreducible $G F(2) M_{23}$ Todd-module. $\Gamma_{x}$ and the induced action of $G_{x} / Q(x)$ is best viewed by taking a 23 -element set, denoted by $\Omega_{x}$ endowed with the Steiner system $S(23,7,4)$. (Note the use of the word element so as to distinguish them from the points of $\Gamma$.) Then $\Gamma_{x}:=\Delta=\Delta_{0} \cup \Delta_{1} \cup \Delta_{2}$ is a rank 3 geometry where $\Delta_{0}$ consists of the heptads of the $S(23,7,4)$ on $\Omega_{x}, \Delta_{1}$ of all 3-element subsets of $\Omega_{x}$ and $\Delta_{2}=\Omega_{x}$, with incidence given by (symmetrized) containment. The lines of $\Gamma$ in $\Gamma_{x}$ correspond to $\Delta_{0}$ and the hyperplanes of $\Gamma$ in $\Gamma_{x}$ correspond to $\Delta_{2}$.

For $X$ a hyperplane of $\Gamma$, we have $G_{X} / Q(X) \cong F i_{22}$ (the smallest Fischer group) with $|Q(X)|=2$. We observe that if two points (bases) are both incident with the same hyperplane (transvection), and are collinear in $\Gamma$, then they are also collinear in $\Gamma_{X}$. The only other information about $\Gamma_{X}$ pertinent here is the structure of the graph given in [5; Appendix 1] which is the induced subgraph $\Gamma_{0} \cap \Gamma_{X}$ of $\mathcal{G}$. (Though [5] deals with the minimal parabolic geometries of $F i_{22}$, note that Lemma 4.4 and discussion following in [5] show that it is the induced subgraph $\left.\Gamma_{0} \cap \Gamma_{X}.\right)$

Throughout this work, we adopt the following convention in order to
avoid rampant notation. A line $l$ and hyperplane $X$ of $\Gamma$ when viewed in the residue of some point $x$ of $\Gamma$ will metamorphose into (respectively) a heptad and an element of $\Omega_{x}$. Equally, without further mention we shall regard heptads and elements of $\Omega_{x}$ as lines and hyperplanes of $\Gamma_{x}$.

Concerning the set $\Omega_{x}\left(x \in \Gamma_{0}\right)$, for concrete calculations we regard $\Omega_{x}$ as a subset of the MOG thus

(the top left-most element being removed). And of course we carry out these calculations in $\mathrm{S}(23,7,4)$ with the aid of Curtis's MOG [2].

As is observed in Lemma 3.3 two collinear points $x$ and $y$ of $\Gamma_{0}$ determine a unique line of $\Gamma_{1}$ - frequently we shall denote this line by $x+y$ (respectively $y+x$ ) to alert us to the fact that we are viewing the line in $\Gamma_{x}$ (respectively $\Gamma_{y}$ ).

Fix $x \in \Gamma_{0}$ and let $H$ be a subgroup of $L:=G_{x} / Q(x)\left(\cong M_{23}\right)$. Before dealing with specific subgroups of $H$ of $M_{23}$ and their orbits on $\Gamma_{1}(x)$, we say a few words about their taxonomy. Frequently $H$ may be specified as the subgroup of $M_{23}$ stabilizing two particular subsets of $\Omega_{x}$. Then, usually, the orbits of $H$ upon $\Gamma_{1}(x)$ are determined by the intersections of the heptads (lines of $\Gamma_{x}$ ) with these subsets of $\Omega_{x}$. Accordingly, the notation for an $H$-orbit on $\Gamma_{1}(x)$ is often of the form

$$
\alpha_{i, j}(x, R, S)
$$

The first entry $x$ tells us we are working in the residue $\Gamma_{x}$, and $R$ and $S$ are subsets of $\Omega_{x}$. So $l \in \alpha_{i, j}(x, R, S)$ means that $l$ is a heptad of $\Omega_{x}$ with $|l \cap R|=i$ and $|l \cap S|=j$. In some instances the orbits may be
described just using one subset of $\Omega_{x}$, so the following is used

$$
\alpha_{i}(x, R)
$$

Frequently we have the case $|S|=1$, say $S=\{X\}$. Then we write $\alpha_{i, j}(x, R, X)$ instead of $\alpha_{i, j}(x, R,\{X\})$ - for $l \in \alpha_{i, j}(x, R, X), j=0$ is, of course, equivalent to $X \notin l$ and $j=1$ to $X \in l$. Still with the case when $|S|=1$, we shall see instances where there is no obvious description of $X$. When this happens we use the following variant of the $\alpha_{i, j}(x, R, X)$ notation:

$$
\alpha_{i}(x, R,+) \text { or } \alpha_{i}(x, R,-) .
$$

Here $l \in \alpha_{i}(x, R,+)\left(\right.$ respectively $\left.\alpha_{i}(x, R,-)\right)$ means $l \in \Gamma_{1}(x),|R \cap l|=$ $i$ and $X \in l$ (respectively $X \notin l$ ). There are some minor variations to the above scheme which we deal with as they arise.
In (2.1) - (2.14) we list data on the line orbits for various subgroups of $M_{23}$ (to aid reference to these results, we indicate the $G_{a}$-orbit(s) where this information will be used). In the following statements, we first define the relevant subsets of $\Omega_{x}$ and then give the $H$-orbits, their sizes as well as a representative line (as a heptad in $\Omega_{x}$ ) for each H -orbit. When mentioned, $x+b$ is some fixed line of $\Gamma_{1}(x)$ (so $\left.b \in \Delta_{1}(x)\right)$ and will be taken to be the standard heptad

|  | $\times$ |  |
| :---: | :---: | :---: | :---: |
| $\times$ | $\times$ |  |
| $\times$ | $\times$ |  |
| $\times$ | $\times$ |  |

of $\Omega_{x}$.
(2.1) $\left(\Delta_{1}(a)\right.$ orbit) $H \sim 2^{4} A_{7}$. $\{x+b\} \quad 1$

$\alpha_{3}(x, x+b) \quad 140$

|  | $\times$ |  |
| :---: | :---: | :---: |
| $\times$ | $\times$ |  |
| $\times$ | $\times$ |  |
| $\times$ | $\times$ |  |

(2.2) ( $\Delta_{2}^{1}(a)$ orbit) $H \sim 2^{4} S_{5} 3$.

$$
T(x, a):=\begin{array}{|l|l|l|}
\hline & & \\
0 & & \\
0 & & \\
0 & & \\
\hline
\end{array}
$$


(2.3) ( $\Delta_{2}^{2}(a)$ and $\Delta_{3}^{3}(a)$ orbits) $H \sim 2^{4} A_{6}$.

$$
X=X(x, a):=\begin{array}{|l|l}
\hline & 0 \\
& \text { (so } X(x, a) \in x+b) \\
\hline
\end{array}
$$



Remark. Let $l \in \alpha_{3,0}(x, x+b, X(x, a))$ where

$$
l=\begin{array}{|l|l|l|}
\hline & \times & \\
\hline \times & \times & \\
\times & \times & \\
\times & \times & \\
\hline
\end{array} .
$$

Then $H_{l}$, which has order $2^{3} .3^{2}$, has a normal subgroup of order 3 generated by $\xi$ where


Further, $\xi$ fixes 4 heptads in $\alpha_{1,1}(x, x+b, X(x, a))$, each of which form a diamond with $l$ (see Section 3 for the definition of a diamond). Also $H_{l}$ contains a subgroup isomorphic to $3 \times A_{4}$.
(2.4) $\left(\Delta_{3}^{1}(a)\right.$ orbit) $H \sim L_{3}(4) 2$.

$$
D=D(x, a):=\begin{array}{|l|l|l|}
\hline & \circ & \\
\hline & & \\
\hline
\end{array}
$$


(2.5) $\left(\Delta_{3}^{2}(a)\right.$ orbit) $H \sim 2^{3} L_{3}(2)$.


Remark. (i) For $l \in \alpha_{0,0}(x, O(x, a), X(x, a))$, we have $H_{l} \cong L_{3}(2)$.
(ii) Assume that $l \in \alpha_{4,0}(x, O(x, a), X(x, a))$. Then $H_{l} \sim 2^{3} .3, H_{l} \cap$ $O_{2}(H)=1$ and $H_{0}:=\left\langle H_{l}, O_{2}(H)\right\rangle$ contains no normal subgroup of $H_{0}$ of order $2^{2}$.
(2.6) $\left(\Delta_{3}^{4}(a)\right.$ orbit) $H \cong M_{22}$.

$$
X=X(x, a):=\begin{array}{|l|l|l|}
\hline & \circ & \\
\hline & & \\
\hline
\end{array}
$$


(2.7) $\left(\Delta_{3}^{5}(a)\right.$ orbit) $H \sim 2^{4} A_{5} \leq 2^{4} A_{7}$ (the stabilizer of $x+b$ ) where the $A_{5}$ has orbits of sizes 1 and 6 on the elements of $x+b$, the standard heptad.


Remark. (i) For $l \in \alpha_{1}(x, x+b,+), H_{l} \cong A_{5}$ and $H_{l}$ has orbits of length 1 and 6 upon the elements of the heptad $x+b$.
(ii) In (2.7) we have the exceptional degree $6 A_{5}$ permutation representation making an appearance - since this not a 3-transitive permutation representation, $\alpha_{3}(x, x+b,-)$ splits into two orbits, called $\alpha_{3}^{(1)}(x, x+b,-)$ and $\alpha_{3}^{(2)}(x, x+b,-)$. In order to give representatives for each of these two orbits we need to specify $H=2^{4} A_{5}$ "concretely". We will not do this since these two orbits will be distinguished via certain configurations in $\mathcal{G}$ (see [6; Section 5]).
(2.8) $\left(\Delta_{3}^{6}(a)\right.$ orbit) $H \sim\left[2^{7}\right] 3^{2} \leq 2^{4} A_{7}$ (the stabilizer of $\left.x+b\right) ; H$ is the stabilizer of a 3 -set of $x+b$.

$$
T=T R I:=\begin{array}{|l|l|l|}
\hline & & \\
\hline 0 & \\
\circ & \\
\hline & & \\
\hline
\end{array}
$$


(2.9) $\Delta_{4}^{1}(a)$ orbit) $H \sim L_{3}(2) 2\left(\leq L_{3}(4) 2\right)$.

$$
D=\text { DUAD }:=\begin{array}{|l|ll|l|}
\hline & & \circ & \circ \\
& & \\
\hline
\end{array}
$$

The 7 heptads in $\alpha_{3,2}(x, x+b$, DUAD) intersect the standard heptad in seven 3 -element subsets and these 3 -elements are the lines of a projective plane on the 7 elements of the standard heptad. Denote this collection of 3 -elements of the standard heptad by $\mathfrak{L}$. Now $\alpha_{3,0}^{\mathfrak{R}}(x, x+b$, DUAD $)$ consists of all heptads which, in addition to missing DUAD, intersect the standard heptad in a 3 -element subset of $\mathfrak{L}$, and $\alpha_{3,0}^{\mathfrak{R c}}(x, x+b, \mathrm{DUAD})=\alpha_{3,0}(x, x+b, \mathrm{DUAD}) \backslash \alpha_{3,0}^{\mathfrak{L}}(x, x+b, \mathrm{DUAD})$.

(2.10) $\left(\Delta_{4}^{2}(a)\right.$ orbit) $H \cong A_{8}$.


Remark. (i) For $l \in \alpha_{4}(x, O(x, a)), O_{2}\left(H_{l}\right) \cong 2^{2}$.
(ii) If $l \in \alpha_{2}(x, O(x, a))$, then $H_{l} \sim A_{5} 2$.
(2.11) $\left(\Delta_{4}^{3}(a)\right.$ orbit) $H \sim\left[2^{6}\right] 3^{2}$ (the stabilizer of $O C T$ and the standard sextet).

$$
T=T R I:=\begin{array}{|l|l|l}
\hline & \\
\hline \\
0 \\
\circ & & \\
\hline
\end{array} \quad O=O C T:=\begin{array}{|l|l|l|}
\hline & & \otimes 0 \\
\otimes \circ \\
\otimes 0 \\
\otimes 0 \\
\hline
\end{array}
$$

The orbits of $H$ on $\Gamma_{1}(x)$ are parameterized by intersections with TRI and the partition of $O C T$ into $4 \mid 4$ indicated by the $\otimes$ 's and o's. The subscript $j \mid k$ below describes how the intersection of a heptad with $O C T$ splits with respect to this partition.


Remark. We note that $T R I$ is the triad contained in all heptads in $\alpha_{3,4 \mid 0}(x, T R I, O C T)$ and $\alpha_{3,0}(x, T R I, O C T)$ and that the partition of the octad $O C T$ is determined by the intersection with $O C T$ of either of the heptads in $\alpha_{3,4 \mid 0}(x, T R I, O C T)$.
(2.12) $\left(\Delta_{4}^{4}(a)\right.$ orbit) $H \cong L_{2}(11)$.

$E N D:=$|  |  | 0 |  | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 |  | 0 |  | 0 |
|  | 0 |  | 0 |  | 0 |
|  | 0 |  | 0 |  | 0 |


(So $E N D$ is an endecad of the MOG; see [1].)

(2.13) $\left(\Delta_{4}^{5}(a)\right.$ orbit) $H \cong A_{7}$.

$$
X:=\begin{array}{|l|l|l|}
\hline & & \circ \\
& & \\
& & \\
\hline
\end{array}
$$


(2.14) $\left(\Delta_{4}^{6}(a)\right.$ orbit) $H \sim\left(3 \times A_{5}\right) 2\left(=N_{L}(T)\right.$ where $T \leq L$ has order 3). Also recall that $H$ is a subgroup of a triad stabilizer and that $T$ fixes exactly 5 elements of $\Omega_{x}$.


| $\alpha_{0,4}(x, T, F) \quad 5$ |  | $\times \times$ | $\times \times$ | $\alpha_{3,1}(x, T, F) \quad 5$ | $\square$ <br> $\times$ <br> $\times$ <br> $\times$ <br> $\times$ <br> $\times$ <br> $\times$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\alpha_{0,0}(x, T, F) \quad 15$ |  | $\times \times$ | $\times \times$ | $\alpha_{2,0}(x, T, F) \quad 18$ | $\begin{array}{\|l\|} \hline \square \\ \times \\ \times \\ \times \\ \times \end{array}$ | $\times \times$ | $\times \times$ |
| $\alpha_{1,3}(x, T, F) \quad 30$ | \|r $\times \times$ | $\times$ $\times$ <br> $\times \times$  |  | $\alpha_{2,2}(x, T, F) \quad 30$ |   <br>   <br> $\times$  <br> $\times$  <br> $\times$  <br> $\times$  | $\times$ | $\times \times$ |



Remark. The group $T$ above is generated by

(2.15) Let $a$ be a point of $\mathcal{G}$. (The notation, $T(c, a)$ and $X(c, a)$, for $c \in \Delta_{2}(a)$ is introduced in Section 3 while, for $d \in \Delta_{3}(a), X(d, a)$ is given after Lemma 4.3 and $O(d, a)$ is given in Theorem 4.13(iv).)
(i) $\Delta_{2}^{1}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $b \in\{a, x\}^{\perp}$ such that $b+x \in$ $\left.\alpha_{3}(b, b+a)\right\}$.
(ii) $\Delta_{2}^{2}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $b \in\{a, x\}^{\perp}$ such that $b+x \in$ $\left.\alpha_{1}(b, b+a)\right\}$.
(iii) $\Delta_{3}^{1}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $c \in \Delta_{2}^{1}(a) \cap \Delta_{1}(x)$ such that $c+x \in$ $\left.\alpha_{2}(c, T(c, a))\right\}$.
(iv) $\Delta_{3}^{2}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $c \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ such that $c+x \in$ $\alpha_{3,1}(c, c+b, X(c, a))$, where $\left.\{b\}=\{a, c\}^{\perp}\right\}$.
(v) $\Delta_{3}^{3}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $c \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ such that $c+x \in$ $\alpha_{1,1}(c, c+b, X(c, a))$ (where $\{b\}=\{a, c\}^{\perp}$ ) and $c$ is the unique point in $\Gamma_{0}(X(a, c))$ lying in $\left.\Delta_{2}^{2}(a) \cap \Delta_{1}(x)\right\}$.
(vi) $\Delta_{3}^{4}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $c \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ such that $c+x \in$ $\alpha_{1,1}(c, c+b, X(c, a))\left(\right.$ where $\left.\{b\}=\{a, c\}^{\perp}\right)$ and there are 77 points in $\Gamma_{0}(X(a, c))$ lying in $\left.\Delta_{2}^{2}(a) \cap \Delta_{1}(x)\right\}$.
(vii) $\Delta_{3}^{5}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $c \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ such that $c+x \in$ $\alpha_{1,0}(c, c+b, X(c, a))$, where $\left.\{b\}=\{a, c\}^{\perp}\right\}$.
(viii) $\Delta_{3}^{6}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $c \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ such that $c+x \in$ $\alpha_{3,0}(c, c+b, X(c, a))$, where $\left.\{b\}=\{a, c\}^{\perp}\right\}$.
(ix) $\Delta_{4}^{1}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $d \in \Delta_{3}^{1}(a) \cap \Delta_{1}(x)$ such that $d+x \in$ $\left.\alpha_{0}(d, D(d, a))\right\}$.
(x) $\Delta_{4}^{2}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $d \in \Delta_{3}^{2}(a) \cap \Delta_{1}(x)$ such that $d+x \in$ $\left.\alpha_{0,0}(d, O(d, a), X(d, a))\right\}$.
(xi) $\Delta_{4}^{3}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $d \in \Delta_{3}^{2}(a) \cap \Delta_{1}(x)$ such that $d+x \in$ $\left.\alpha_{4,0}(d, O(d, a), X(d, a))\right\}$.
(xii) $\Delta_{4}^{4}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $d \in \Delta_{3}^{3}(a) \cap \Delta_{1}(x)$ such that $d+x \in$ $\alpha_{1,0}(d, d+b, X(d, a))$ where $\left.\{b\}=\Delta_{1}(d) \cap \Delta_{2}^{2}(a)\right\}$.
(xiii) $\Delta_{4}^{5}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $d \in \Delta_{3}^{4}(a) \cap \Delta_{1}(x)$ such that $d+x \in$ $\left.\alpha_{0}(d, X(d, a))\right\}$.
(xiv) $\Delta_{4}^{6}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $d \in \Delta_{3}^{3}(a) \cap \Delta_{1}(x)$ such that $d+x \in$ $\alpha_{3,0}(d, d+b, X(d, a))$ where $\left.\{b\}=\Delta_{1}(d) \cap \Delta_{2}^{2}(a)\right\}$.

We remark that our notation has been chosen so as to mesh with that of [5] - so here our $\Delta_{1}(a), \Delta_{2}^{1}(a), \Delta_{2}^{2}(a), \Delta_{3}^{1}(a), \Delta_{3}^{2}(a), \Delta_{3}^{3}(a), \Delta_{3}^{4}(a)$ when intersected with $\Gamma_{X}$ (for $\left.X \in \Gamma_{3}(a)\right)$ gives precisely the $\Delta_{i}^{j}(a)$ of [5].

## 3. The First Two Discs and Diamonds

Lemma 3.1 ("Three points on a line"). For $l \in \Gamma_{1},\left|\Gamma_{0}(l)\right|=3$.
Proof. Let $X \in \Gamma_{3}(l)$. Then $\Gamma$ being a string geometry implies that $\Gamma_{0}(l) \subseteq \Gamma_{0}(X)$, whence Lemma 3.1 follows from [5; Lemma 4.4].

Since, for $X \in \Gamma_{3}, G_{X} \cong 2 F i_{22}$ and $\left|Z\left(G_{X}\right)\right|=2$, let $\tau(X) \in G_{X}$ be such that $\langle\tau(X)\rangle=Z\left(G_{X}\right)$. (Of course $\tau(X)$ is just a transposition of $G=F i_{23}$.) Note that, for $x \in \Gamma_{0}(X)$, we have $\tau(X) \in Q(x)$. Also,
for $l \in \Gamma_{1}(X), \Gamma$ being a string geometry and $\tau(X) \in Q(X)$ means that $\tau(X)$ fixes each of the points of $\Gamma_{0}(l)$.

Lemma 3.2. Suppose $x \in \Gamma_{0}, l \in \Gamma_{1}(x)$ and $X \in \Gamma_{3}(x)$. Then $\tau(X)$ interchanges $\Gamma_{0}(l) \backslash\{x\}$ if and only if $X \notin l$. (Recall our convention - in $\Gamma_{x}, X$ is an element and $l$ a heptad of $\Omega_{x}$.)

Proof. Since $G_{x X}^{* x} \cong M_{22}, G_{x X}$ has two orbits upon the 253 heptads in $\Omega_{x}$ - those containing $X$ (77) and those not containing $X$ (176). If the result were false, then, since $\tau(X) \in Z\left(G_{x X}\right)$, we infer that $\tau(X)$ fixes the points in $\Gamma_{0}(l)$ for all $l \in \Gamma_{1}(x)$. Because $Q(x)$ is an irreducible $G F(2) G_{x}$-module, $Q(x)$ then fixes the points in $\Gamma_{0}(l)$ for all $l \in \Gamma_{1}(x)$, contradicting [5; Lemma 4.2(iii)].

Lemma 3.3. If $x$ and $y$ are collinear points of $\Gamma$, then $\left|\Gamma_{1}(x, y)\right|=$ 1.

Proof. Suppose we have $l, k \in \Gamma_{1}(x, y)$, and let $X \in \Gamma_{3}(l)$. Hence, as $\Gamma$ is a string geometry, $X \in \Gamma_{3}(x) \cap \Gamma_{3}(y)$. So, in particular, $\tau(X)$ fixes $y$ and thus, applying Lemma 3.2 in $\Gamma_{x}$, we get $X \in k$. That is $l, k \in \Gamma_{1}(X)$, whence $l=k$ by the structure of $\Gamma_{X}$ (see [5; Lemma 4.4]).

Lemma 3.4. If $x, y$ and $z$ form a triangle in $\mathcal{G}_{0}$ where $x, y, z \in \Gamma_{0}$, then $\{x, y, z\}=\Gamma_{0}(l)$ for some $l \in \Gamma_{1}$.

Proof. Let $\{l\}=\Gamma_{1}(x, y),\{m\}=\Gamma_{1}(y, z)$ and $\{k\}=\Gamma_{1}(z, x)$. Choose $X \in \Gamma_{3}(l)$. So $\tau(X) \in Q(x) \cap Q(y)$ and therefore $z^{\tau(X)} \in$ $\Gamma_{0}(m) \cap \Gamma_{0}(k)$. If $k \notin \Gamma_{X}$, then $z^{\tau(X)} \neq z$ by Lemma 3.2. Therefore, using Lemma 3.3, $m=z+z^{\tau(X)}=k$, and then $k=l$, a contradiction. Thus $k \in \Gamma_{X}$, and so we get $l, k, x, y, z \in \Gamma_{X}$, whence $m \in \Gamma_{X}$ and then [5; Lemma 5.5] gives the lemma.

We now choose, and keep fixed, a point $a \in \Gamma_{0}$; our next result is about $\Delta_{1}(a)$, the first disc of $a$.

Lemma 3.5. (i) $\Delta_{1}(a)$ is a $G_{a}$-orbit and, for $x \in \Delta_{1}(a), G_{a x} \sim$ $2^{10} 2^{4} A_{7}$ with $G_{a x}^{* x} \sim 2^{4} A_{7}$ (the stabilizer in $G_{x}^{* x}$ of the line $x+a$ ); and
(ii) $\left|\Delta_{1}(a)\right|=2.11 .23$.

Proof. Let $x \in \Delta_{1}(a)$, and select $X \in \Omega_{a}$ such that $X \notin \Gamma_{3}(a+x)$. Then $\tau(X)$ interchanges the two points in $\Gamma_{0}(a+x) \backslash\{a\}$ by Lemma 3.2 and therefore, as $G_{a}$ is transitive on $\Gamma_{1}(a)$, we obtain (i). Since $\Gamma_{1}(a)$ has $253=11.23$ lines, (ii) follows using Lemma 3.1.

From Lemmas 3.4 and 3.5 , (2.1) and the definition of $\Delta_{2}^{1}(a)$ and $\Delta_{2}^{2}(a)$ we see that Theorem 2 holds. We now proceed to examine $\Delta_{2}(a)$, the second disc of $a$.

Lemma 3.6. Let $X \in \Gamma_{3}$. If $x, y \in \Gamma_{0}(X)$, then $\{x, y\}^{\perp} \subseteq \Gamma_{0}(X)$.
Proof. Suppose we have $b \in\{x, y\}^{\perp}$ with $b \notin \Gamma_{0}(X)$. Then $b+x \neq$ $b+y$. In $\Omega_{x}, x+b$ is a heptad not containing $X$. So $b^{\tau(X)} \neq b$ by Lemma 3.2. Now $\tau(X) \in Q(x) \cap Q(y)$ and hence $b^{\tau(X)} \in \Gamma_{0}(x+b) \cap \Gamma_{0}(y+b)$. But then, by Lemma 3.3, $b+x=b+b^{\tau(X)}=b+y$, a contradiction.

Lemma 3.7. Let $x \in \Delta_{2}^{1}(a)$. Then
(i) $\left|\{a, x\}^{\perp}\right|=5$ and there are exactly 3 hyperplanes $\left\{X_{1}, X_{2}, X_{3}\right\}$ in $\Gamma_{3}(a, x)$, and $\{a, x\}^{\perp} \subseteq \Gamma_{0}\left(X_{i}\right)$ for $i=1,2,3$;
(ii) $\Delta_{2}^{1}(a)$ is a $G_{a}$-orbit and $G_{a x} \sim 2^{7} 2^{4} S_{5} 3$ (with $G_{a x}^{* x} \sim 2^{4} S_{5} 3$ ); and (iii) $\left|\Delta_{2}^{1}(a)\right|=2^{4} .7 .11 .23$.

Proof. Let $b \in\{a, x\}^{\perp}$ be such that $b+x \in \alpha_{3}(b, b+a)$. So (in $\Omega_{b}$ ) $(b+a) \cap(b+x)=\left\{X_{1}, X_{2}, X_{3}\right\}$. Hence $a, x \in \Gamma_{0}\left(X_{i}\right)$ and consequently $\{a, x\}^{\perp} \subseteq \Gamma_{0}\left(X_{i}\right)$ for $i=1,2,3$ by Lemma 3.6. From [5; Lemma 5.7(ii)] $\left|\{a, x\}^{\perp}\right|=5$, and we have (i).

By Lemma 3.5(i) and (2.1) $G_{a b}$ is transitive on the heptads of $\Omega_{b}$ intersecting $b+a$ in 3 elements. Also, by selecting a $Y \in \Gamma_{3}(b+a) \backslash \Gamma_{3}(b+$ $x)$ we get that $\tau(Y)$ interchanges $\Gamma_{0}(b+x) \backslash\{b\}$ by Lemma 3.2. Hence, as $G_{a}$ is transitive on $\Delta_{1}(a), \Delta_{2}^{1}(a)$ is a $G_{a}$-orbit. Using $\left|\{a, x\}^{\perp}\right|=5$, we may count thus

$$
\left|\Delta_{2}^{1}(a)\right|=\frac{2 \cdot\left|\Delta_{1}(a)\right| \cdot 140}{5}=2^{4} .7 .11 .23
$$

Now, by part (i), $\left[G_{a x}: G_{a x} \cap G_{X_{1}}\right]=1$ or 3 and then combining $\left|\Delta_{2}^{1}(a)\right|$ with $\Delta_{2}^{1}(a)$ being a $G_{a}$-orbit and $\left|G_{a x} \cap G_{X_{1}}\right|=2^{14} .3 .5$ (see [5;Lemma 5.7 (iii)]) yields $\left[G_{a x}: G_{a x} \cap G_{X_{1}}\right]=3$. Appealing to [5; Lemma 5.7(iii)] again gives the shape of $G_{a x}$, and this completes the proof of Lemma 3.7.

Lemma 3.8. Let $x \in \Delta_{2}^{2}(a)$. Then
(i) $\left|\{a, x\}^{\perp}\right|=1$ and there is a unique hyperplane $X$ in $\Gamma_{3}(a, x)$, and $\{a, x\}^{\perp} \subseteq \Gamma_{0}(X) ;$
(ii) $\Delta_{2}^{2}(a)$ is a $G_{a}$-orbit and $G_{a x} \sim 2^{5} 2^{4} A_{6}$ (with $G_{a x}^{* x} \sim 2^{4} A_{6}$ ); and
(iii) $\left|\Delta_{2}^{2}(a)\right|=2^{6}$.7.11.23.

Proof. This result may be proved in the same manner as Lemma 3.7, using [5; Lemma 5.10] in place of [5; Lemma 5.7(iii)].

Lemma 3.9. $\Delta_{2}(a)=\Delta_{2}^{1}(a) \dot{\cup} \Delta_{2}^{2}(a)$.
Proof. Clearly, by Lemmas 3.3 and 3.4, we have $\Delta_{2}(a)=\Delta_{2}^{1}(a) \cup$ $\Delta_{2}^{2}(a)$. So we only need to show that $\Delta_{2}^{1}(a) \cap \Delta_{2}^{2}(a)=\emptyset$. Suppose we have $x \in \Delta_{2}^{1}(a) \cap \Delta_{2}^{2}(a)$. Then there exist $b, b^{\prime} \in\{a, x\}^{\perp}$ such that $|(b+a) \cap(b+x)|=1$ and $\left|\left(b^{\prime}+a\right) \cap\left(b^{\prime}+x\right)\right|=3$. Employing Lemma 3.7 gives $\left\{b, b^{\prime}\right\} \subseteq \Gamma_{0}\left(X_{i}\right)$ for $i=1,2,3$ where $\left\{X_{1}, X_{2}, X_{3}\right\}=\Gamma_{3}(a, x)$. But this contradicts $|(b+a) \cap(b+x)|=1$.

Let $x, y \in \Gamma_{0}$ with $y \in \Delta_{2}^{1}(x)$ (so $x \in \Delta_{2}^{1}(y)$ also). By Lemma 3.7 $\{x, y\}^{\perp}=\left\{b_{1}, b_{2}, b_{3}, b_{4}, b_{5}\right\}$ and $\Gamma_{3}(x, y)=\left\{X_{1}, X_{2}, X_{3}\right\}$. So we have

and we will call such a configuration in $\mathcal{G}$ a diamond. Note that for $i \neq j, b_{i} \in \Delta_{2}^{1}\left(b_{j}\right)$. We will employ the same positional aid notation as for lines and denote $\left\{X_{1}, X_{2}, X_{3}\right\}$ by $T(x, y)$ so as to signal that we are viewing this as a subset of $\Omega_{x}$.

A crucial observation, used repeatedly in later arguments, is that this set of hyperplanes $\left\{X_{1}, X_{2}, X_{3}\right\}$ manifests itself in the residue of any point in the diamond. That is, $T\left(b_{i}, b_{j}\right)=\left\{X_{1}, X_{2}, X_{3}\right\}=T(y, x)$; moreover $T\left(b_{i}, b_{j}\right)=\left(b_{i}+x\right) \cap\left(b_{j}+y\right), T(x, y)=\left(x+b_{i}\right) \cap\left(x+b_{j}\right)$ and $T(y, x)=\left(y+b_{i}\right) \cap\left(y+b_{j}\right)(1 \leq i<j \leq 5)$. Also $\left\{x+b_{i} \mid i=1, \ldots, 5\right\}$ are precisely the 5 heptads which contain $T(x, y)$ - with a similar statement at other points in the diamond.

Lemma 3.10. Let $y \in \Delta_{2}^{1}(x)$ and let $\left\{b, b^{\prime}\right\} \subseteq\{x, y\}^{\perp}$ with $b \neq b^{\prime}$ (so we are considering part of a diamond). If $\Gamma_{0}(x+b)=\{x, b, c\}$ and $\Gamma_{0}\left(y+b^{\prime}\right)=\left\{y, b^{\prime}, c^{\prime}\right\}$, then $d\left(c, c^{\prime}\right)=1$.

Proof. Since we may choose $X \in \Gamma_{3}\left(x, b^{\prime}\right)$ with $X \notin x+b$ and $X \notin b^{\prime}+y, b^{\tau(X)}=c$ and $y^{\tau(X)}=c^{\prime}$ by Lemma 3.2. This proves the lemma as $d(b, y)=1$.

In the last result of this section which follows directly from Lemma 3.10 and the discussion preceding it, we assume the notation given in the diamond above.

Lemma 3.11. (i) Assume that $\Gamma_{0}\left(x+b_{1}\right)=\left\{x, b_{1}, c\right\}$ and, for

$$
i=1, \ldots, 5, \Gamma_{0}\left(y+b_{i}\right)=\left\{y, b_{i}, c_{i}\right\} . \text { Then }\{c, y\}^{\perp}=\left\{b_{1}, c_{2}, c_{3}, c_{4}, c_{5}\right\} .
$$

(ii) If $X \in \Gamma_{3}(x)$, then $X \in \Gamma_{3}\left(x+b_{i}\right)$ for some $i \in\{1, \ldots, 5\}$.

Finally, in the situation of Lemma 3.8 we denote the unique hyperplane in $\Gamma_{3}(a, x)$ by $X(a, x)$, (respectively $\left.X(x, a)\right)$ if it is viewed as an element of $\Omega_{a}$ (respectively $\Omega_{x}$ ).

## 4. Preliminaries on the Third Disc

In this section, in addition to establishing Theorems 3 and 4, we find the $G_{a}$-orbits of $\Delta_{3}(a)$, their sizes and determine the structure of $G_{a x}$ for $x$ in each of these orbits. This information, the salient points being summarized in Theorem 4.13, together with the data on line orbits in Section 2, serves as a launch pad for our investigations in [6].

For $x \in \Delta_{3}^{2}(a) \cup \Delta_{3}^{3}(a) \cup \Delta_{3}^{4}(a)$ from the definitions (plus the fact that $\Gamma$ is a string geometry), $X(a, c) \in \Gamma_{3}(a, x)$, where $c \in \Delta_{2}^{2}(a) \cap$ $\Delta_{1}(x)$ is such that $c+x \in \alpha_{i, 1}(c, c+b, X(c, a))(i=1$ or 3$)$ and $\{b\}=$ $\{a, c\}^{\perp}$. While for $x \in \Delta_{3}^{1}(a)$, two of the hyperplanes of $T(a, c)$ are in $\Gamma_{3}(a, x)$ (where $c \in \Delta_{2}^{1}(a) \cap \Delta_{1}(x)$ and $c+x \in \alpha_{2}(c, T(c, a))$ ). So it is not surprising that properties of these sets are very much tied up with the point-line collinearity graph of the $F i_{22}$-geometry $\Gamma_{X}\left(X \in \Gamma_{3}\right)$. Suppose $X \in \Gamma_{3}$ and $x, y \in \Gamma_{0}(X)$. If, say, $x$ and $y$ are distance 3 apart in the point-line collinearity graph of $\Gamma_{X}$, then, by Lemma 3.6, we also have $d(x, y)=3$ (distance in $\mathcal{G}$ ).

Diamonds make their debut in our next argument.
Lemma 4.1. Let $X \in \Gamma_{3}$ and let $w, z \in \Gamma_{0}(X)$ with $w \neq z$. If $\{w, x, y, z\}$ is a path in $\mathcal{G}$ of length 3, then either $x, y \in \Gamma_{0}(X)$ or $d(w, z)=1$.

Proof. Suppose the result is false. If either $x \in \Gamma_{0}(X)$ or $y \in$
$\Gamma_{0}(X)$, then Lemma 3.6 would force $x, y \in \Gamma_{0}(X)$. Thus we have $x, y \notin$ $\Gamma_{0}(X)$. Hence $x^{\tau(X)} \neq x$ and $y^{\tau(X)} \neq y$ by Lemma 3.2. Also $x^{\tau(X)} \in$ $\Gamma_{0}(w+x)$ and $y^{\tau(X)} \in \Gamma_{0}(z+y)$. So we have


If $d\left(x^{\tau(X)}, y\right)=1$, then Lemmas 3.3 and 3.4 force $d(w, y)=1$, whence $y \in \Gamma_{0}(X)$ by Lemma 3.6. So $d\left(x^{\tau(X)}, y\right)=2$. If $x=y^{\tau(X)}$, then using Lemma 3.6 again gives $x \in \Gamma_{0}(X)$. Hence $x \neq y^{\tau(X)}$ and therefore $y \in \Delta_{2}^{1}\left(x^{\tau(X)}\right)$ by Lemmas 3.8(i) and 3.9. (So we see part of a diamond.) Now using Lemma 3.10 yields $d(w, z)=1$, contrary to our supposition. This completes the proof of the lemma.

Lemma 4.2. $\bigcup_{i=1}^{6} \Delta_{3}^{i}(a) \subseteq \Delta_{3}(a)$.
Proof. For $x \in \Delta_{3}^{i}(a)(i=1,2,3,4)$ we have $a, x \in \Gamma_{0}(X)$ for some $X \in \Gamma_{3}$ with $a$ and $x$ distance 3 apart in the point-line collinearity graph of $\Gamma_{X}$. Therefore $x \in \Delta_{3}(a)$.

Suppose that $x \in \Delta_{3}^{5}(a)$. Then by (2.15) there exists $c \in \Delta_{2}^{2}(a)$ such that $c+x \in \alpha_{1,0}(c, c+b, X(c, a))$ (where $\{b\}=\{a, c\}^{\perp}$ ). If $d(a, x)=1$, then $x \in\{a, c\}^{\perp}$ and so $x=b$, whereas $c+x \neq c+b$. So $d(a, x) \geq 2$. If $d(a, x)=2$, then, by Lemmas 3.7(i) and 3.8(i), $a, x \in \Gamma_{0}(X)$ for some $X \in \Gamma_{3}$. Since $\{a, b, c, x\}$ is a path of length 3 in $\mathcal{G}$, Lemma 4.1 forces $b, c \in \Gamma_{0}(X)$. But then $X=X(a, c)$ and $X(c, a) \in c+x$, contradicting $c+x \in \alpha_{1,0}(c, c+b, X(c, a))$. Consequently $x \in \Delta_{3}(a)$. A similar argument yields that $\Delta_{3}^{6}(a) \subseteq \Delta_{3}(a)$, so proving the lemma.

Lemma 4.3. (i) Let $x \in \bigcup_{i=1}^{4} \Delta_{3}^{i}(a)$, and suppose $X \in \Gamma_{3}(a, x)$. Then the vertices of every length 3 path from a to $x$ are in $\Gamma_{0}(X)$.
(ii) Let $y \in \Delta_{3}^{1}(a)$ and $x \in \bigcup_{i=2}^{4} \Delta_{3}^{i}(a)$. Then for every $c \in \Delta_{2}^{2}(a) \cap$ $\Delta_{1}(x),\{X(a, c)\}=\Gamma_{3}(a, x)$ and for every $d \in \Delta_{2}^{1}(a) \cap \Delta_{1}(y)$,
$T(a, d) \cap(d+y)=\Gamma_{3}(a, y)$. In particular, $\left|\Gamma_{3}(a, x)\right|=1$ and $\left|\Gamma_{3}(a, y)\right|=2$.
(iii) For $i=1,2,3,4$ and $X \in \Gamma_{3}(a), \Gamma_{0}(X) \cap \Delta_{3}^{i}(a)$ is equal to the correspondingly named set in [5; Appendix 1].

Proof. Since $d(a, x)=3$, (i) follows immediately from Lemma 4.1. Note that one consequence of (i), using [5], is that for $y \in \Delta_{3}^{1}(a)$ and $d \in \Delta_{2}^{1}(a) \cap \Delta_{1}(y)$, we must have $d+y \in \alpha_{2}(d, T(d, a))$. Now, parts (ii) and (iii) are consequences of part (i).

Notation. For $x \in \bigcup_{i=2}^{4} \Delta_{3}^{i}(a)$ we use $X(a, x)$ (or $\left.X(x, a)\right)$ to denote the unique hyperplane in $\Gamma_{3}(a, x)$ - by Lemma 4.3(ii) $X(a, x)=X(a, c)$ for any $c \in \Delta_{2}^{1}(a) \cap \Delta_{1}(x)$. While, for $y \in \Delta_{3}^{1}(a)$ we use $D(a, y)$ (or $D(y, a))$ to denote $\Gamma_{3}(a, y)$. Again we are using our "positional convention" - note that $D(a, y)$ (respectively $D(y, a))$ is a duad of $\Omega_{a}$ (respectively $\Omega_{y}$ ).

Lemma 4.4. For $i=1,2,3,4,5,6, \Delta_{3}^{i}(a)$ is a $G_{a}$-orbit.
Proof. By Lemma 4.3(iii) and [5] $\Gamma_{0}(X) \cap \Delta_{3}^{i}(a)(i=1,2,3,4$, and $\left.X \in \Gamma_{3}(a)\right)$ are $G_{a X}$-orbits. So, since $G_{a}$ is transitive on $\Gamma_{3}(a)$, the lemma holds for $i=1,2,3,4$. For $x$ in $\Delta_{3}^{5}(a)$ or $\Delta_{3}^{6}(a)$ we have $c \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ for which $X(c, a) \notin c+x$. Hence $\Gamma_{0}(c+x) \backslash\{c\}$ is contained in a $G_{a}$-orbit by Lemma 3.2. Because $\Delta_{2}^{2}(a)$ is a $G_{a}$-orbit with $G_{a c}^{* c} \sim 2^{4} A_{6}$, appealing to (2.3) we deduce that $\Delta_{3}^{5}(a)$ and $\Delta_{3}^{6}(a)$ are $G_{a}$-orbits too.

Lemma 4.5. Let $x \in \Delta_{3}^{6}(a)$ and let $c_{1} \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ be such that $c_{1}+x \in \alpha_{3,0}\left(c_{1}, c_{1}+b, X\left(c_{1}, a\right)\right)$, where $\{b\}=\left\{a, c_{1}\right\}^{\perp}$. Then
(i) $\left|\{b, x\}^{\perp} \cap \Delta_{2}^{2}(a)\right|=4$ and $\left|\{b, x\}^{\perp} \cap \Delta_{2}^{1}(a)\right|=1$;
(ii) suppose $\left\{c_{1}, c_{2}, c_{3}, c_{4}\right\}=\{b, x\}^{\perp} \cap \Delta_{2}^{2}(a)$ and $\{c\}=\{b, x\}^{\perp} \cap$ $\Delta_{2}^{1}(a)$. Then $X\left(a, c_{i}\right) \neq X\left(a, c_{j}\right)$ for $1 \leq i<j \leq 4$, and $X\left(a, c_{i}\right) \notin$
$T(a, c)$ for $i=1,2,3,4$. Further, $b+a=\left\{X\left(a, c_{i}\right) \mid i=1,2,3,4\right\} \cup$ $T(a, c)$; and
(iii) set $\{a, c\}^{\perp}=\left\{b, b_{1}, b_{2}, b_{3}, b_{4}\right\}$.

Then we have

with $c \in \Delta_{2}^{1}(a), c_{i} \in \Delta_{2}^{2}(a), b \in \Delta_{2}^{1}(x)$ and $b_{i} \in \Delta_{2}^{2}(x)(i=1,2,3,4)$.
Proof. First we observe that, because $c_{1}+x \in \alpha_{3,0}\left(c_{1}, c_{1}+b, X\left(c_{1}, a\right)\right)$ and $d(a, x)=3, \Gamma_{3}(a, x)=\emptyset$ by Lemma 4.1. Now $c_{1}+x \in \alpha_{3}\left(c_{1}, c_{1}+b\right)$ implies that $\left|\{b, x\}^{\perp}\right|=5$. Thus we have


Since $(b+a) \cap T(b, x) \subseteq \Gamma_{3}(a, x),(b+a) \cap T(b, x)=\emptyset$ (in $\left.\Omega_{b}\right)$. Therefore, as $\left\{b+y \mid y \in\{b, x\}^{\perp}\right\}$ intersects in $T(b, x)$ and their union is the whole of $\Omega_{b}, b+a$ must intersect one of these heptads in 3 elements and four of these heptads in one element. This yields part (i).

If $X\left(a, c_{i}\right)=X\left(a, c_{j}\right)$ for $i \neq j$, then calling upon Lemma 3.6 gives $x \in \Gamma_{0}\left(X\left(a, c_{i}\right)\right)=\Gamma_{0}\left(X\left(a, c_{j}\right)\right)$, contrary to $\Gamma_{3}(a, x)=\emptyset$. Similar considerations yield that $X\left(a, c_{i}\right) \notin T(a, c)$, and so (ii) holds. Noting that $a \in \Delta_{3}^{6}(x)$ we readily obtain (iii).

Our next result shows that looking out from a $\Delta_{2}^{1}(a)$ point, say $c$, "along" lines from $\alpha_{1}(c, T(c, a))$ or $\alpha_{0}(c, T(c, a))$ yields $G_{a}$-orbits already known to us.

Lemma 4.6. (i) $\Delta_{3}^{2}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $c \in \Delta_{2}^{1}(a)$ such that $\left.c+x \in \alpha_{1}(c, T(c, a))\right\}$.
(ii) $\Delta_{3}^{6}(a)=\left\{x \in \Gamma_{0} \mid\right.$ there exists $c \in \Delta_{2}^{1}(a)$ such that $c+x \in$ $\left.\alpha_{0}(c, T(c, a))\right\}$.

Proof. Part (i) follows from Lemma 4.3(iii) and [5; Appendix 1]. Turning to part (ii), we claim that $T:=\left\{x \in \Gamma_{0} \mid\right.$ there exists $c \in \Delta_{2}^{1}(a)$ such that $\left.c+x \in \alpha_{0}(c, T(c, a))\right\}$ is a $G_{a}$-orbit. By Lemma 3.7(ii), for $c \in \Delta_{2}^{1}(a), G_{a c}^{* c} \sim 2^{4} S_{5} 3$. Now using the fact that $\Delta_{2}^{1}(a)$ is a $G_{a}$-orbit, Lemma 3.2 and (2.2) gives the claim. Let $x \in \Delta_{3}^{6}(a)$. From Lemma 4.5 there exists $c \in \Delta_{2}^{1}(a) \cap \Delta_{1}(x)$. Because $\Gamma_{3}(a, x)=\emptyset$ we must have $(c+x) \cap T(c, a)=\emptyset$ and hence $x \in T$. Since $\Delta_{3}^{6}(a)$ is also a $G_{a}$-orbit we infer that $T=\Delta_{3}^{6}(a)$, and (ii) holds.

We pause to remark that Lemma 4.6, together with (2.2), (2.3) and Lemmas 3.7 and 3.8, establish Theorems 3 and 4.

Lemma 4.7. $\bigcup_{i=1}^{6} \Delta_{3}^{i}(a)=\Delta_{3}(a)$.

Proof. Combining Lemmas 3.7(ii), 3.8(ii), 4.2, 4.6 together with (2.2), (2.3) and (2.15) yields the lemma.

Lemma 4.8. (i) $\left|\Delta_{3}^{1}(a)\right|=2^{9} .11 .23$ and, for $x \in \Delta_{3}^{1}(a), G_{a x} \sim$ $2^{2} L_{3}(4) 2$ with $G_{a x}^{* x} \sim L_{3}(4) 2$.
(ii) $\Delta_{3}^{2}(a) \mid=2^{8}$.3.5.11.23 and, for $x \in \Delta_{3}^{2}(a), G_{a x} \sim 2^{7} L_{3}(2)$ with $G_{a x}^{* x} \sim 2^{3} L_{3}(2)$. Moreover, $Q(a) \cap Q(x)=<\tau(X(a, x))>$ with $Q(a)^{* x} \sim 2^{3} \sim Q(x)^{* a}$.
(iii) $\left|\Delta_{3}^{3}(a)\right|=2^{10} .7 .11 .23$ and, for $x \in \Delta_{3}^{3}(a), G_{a x} \sim 2^{5} A_{6}$ with $G_{a x}^{* x} \sim$ $2^{4} A_{6}$.
(iv) $\left|\Delta_{3}^{4}(a)\right|=2^{10} .23$ and, for $x \in \Delta_{3}^{3}(a), G_{a x} \sim 2 M_{22}$ with $G_{a x}^{* x} \cong$ $M_{22}$.

Proof. For parts (ii)-(iv), putting $X=X(a, c)$, we have $G_{a x}=$ $G_{a x X}$ and, using Lemma 4.3(ii), $\left|\Delta_{3}^{i}(a)\right|=23\left|\Delta_{3}^{i}(a) \cap \Gamma_{0}(X)\right|(i=$ 2,3,4). Consulting [5; Appendix 1 and Lemma 6.17(iii)] then gives parts (ii)-(iv).

Let $x \in \Delta_{3}^{1}(a)$. Again employing Lemma 4.3(ii), (iii) and [5; Appendix 1], we have that

$$
\left|\Delta_{3}^{1}(a)\right|=\frac{23\left|\Delta_{3}^{1}(a) \cap \Gamma_{0}(X)\right|}{2}=2^{9} .11 .23
$$

(where $X \in D(a, x)=\Gamma_{3}(a, x)$ ). Moreover, by Lemma 4.3 (ii), for $X \in \Gamma_{3}(a, x),\left[G_{a x}: G_{a x} \cap G_{X}\right] \leq 2$. Using $\left|\Delta_{3}^{1}(a)\right|,\left|G_{a x} \cap G_{X}\right|$ and the fact that $\Delta_{3}^{1}(a)$ is a $G_{a}$-orbit we find that $\left[G_{a x}: G_{a x} \cap G_{X}\right]=2$, whence by [5; Appendix 1] we obtain part (i). The proof of the lemma is complete.

In Lemma 4.8 we have amassed a good deal of information about $\Delta_{3}^{i}(a)$ for $i=1,2,3,4$. The next three results answer the corresponding questions for $\Delta_{3}^{5}(a)$ and $\Delta_{3}^{6}(a)$.

Lemma 4.9. Let $x \in \Delta_{3}^{5}(a)$ and let $c \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ be such that $c+x \in \alpha_{1,0}(c, c+b, X(c, a))$, where $\{b\}=\{a, c\}^{\perp}$. Then
(i) $\Delta_{2}^{2}(a) \cap \Delta_{1}(x)=\{c\}$; and
(ii) $a \in \Delta_{3}^{5}(x)$.

Proof. We first prove part (i). Assume there exists $c_{1} \in \Delta_{2}^{2}(a) \cap$ $\Delta_{1}(x)$ with $c_{1} \neq c$. Let $\left\{a, c_{1}\right\}^{\perp}=\left\{b_{1}\right\}$, and put $X=X(a, c)$ and $Y=X\left(a, c_{1}\right)$. Note that $b=b_{1}$ would imply, as $c \neq c_{1}$, that $x \in \Delta_{2}^{1}(b)$ and hence $c+x \in \alpha_{3}(c, c+b)$, which is not the case. So we have


Suppose that $b_{1} \in \Gamma_{0}(X)$. By Lemma 4.1 we then get that either $x, c_{1} \in \Gamma_{0}(X)$ or $d\left(c, b_{1}\right)=1$. The former possibility cannot occur as $\Gamma_{3}(a, x)=\emptyset$, while $d\left(c, b_{1}\right)=1$ implies (as $b \neq b_{1}$ ) that $c \in \Delta_{2}^{1}(a)$, whereas $c \in \Delta_{2}^{2}(a)$. Thus we conclude that $b_{1} \notin \Gamma_{0}(X)$. So, by Lemma $3.2, x^{\tau(X)} \neq x$ and $b_{1}^{\tau(X)} \neq b_{1}$ and hence we have (setting $\tau=\tau(X)$ )


Since $\tau \in Q(a), c_{1}^{\tau}, b_{1}^{\tau} \in \Gamma_{0}(Y)$. Now, because $c_{1} \neq c_{1}^{\tau}$ (else by Lemmas 3.3 and $3.4 c_{1}=a$ ), we may deploy Lemma 4.1 again to obtain either $x^{\tau}, x \in \Gamma_{0}(Y)$ or $d\left(c_{1}, c_{1}^{\tau}\right)=1$. Hence, as $\Gamma_{3}(a, x)=\emptyset, d\left(c_{1}, c_{1}^{\tau}\right)=1$. However, as $c_{1}^{\tau} \neq b_{1}$ (because $c_{1}^{\tau} \in \Delta_{2}(a)$ and $\left.b_{1} \in \Delta_{1}(a)\right), c_{1} \in \Delta_{2}^{1}\left(b_{1}^{\tau}\right)$, which gives $c_{1} \in \Delta_{2}^{1}(a)$. From this contradiction we infer that $\Delta_{2}^{2}(a) \cap$ $\Delta_{1}(x)=\{c\}$.

Note that part (i) and Lemma 4.5(i) together show that $\Delta_{3}^{5}(a) \neq$ $\Delta_{3}^{6}(a)$.

Moving on to part (ii), part (i), Theorem 3 and Lemma 3.7(i) imply that $b \in \Delta_{2}^{2}(x)$. From the definition of $\Delta_{3}^{5}(a), \Gamma_{3}(a, x)=\emptyset$ and so
$a \in \Delta_{3}^{5}(x) \cup \Delta_{3}^{6}(x)$ by Lemma 4.7. Since $b+c \in \alpha_{1}(b, b+a)$, the definition of $\Delta_{3}^{5}(x)$ gives $a \in \Delta_{3}^{5}(x)$.

Lemma 4.10. For $x \in \Delta_{3}^{6}(a),\left|\Delta_{2}^{1}(a) \cap \Delta_{1}(x)\right|=1$ and $\mid \Delta_{2}^{2}(a) \cap$ $\Delta_{1}(x) \mid=4$. In particular, the configuration in Lemma 4.5(iii) shows $\Delta_{1}(x) \cap \Delta_{2}(a)$ and $\Delta_{1}(a) \cap \Delta_{2}(x)$.

Proof. Suppose the result is false. Thus, appealing to Lemma 4.5(i), we have

where $b \in \Delta_{2}^{1}(x) \cap \Delta_{1}(a), z \in\left(\Delta_{2}(a) \cap \Delta_{1}(x)\right) \backslash\{b, x\}^{\perp}$ and $y \in\{a, z\}^{\perp}$. Evidently $y \neq b$. By Lemma 4.5(ii) there exists $c \in\{b, x\}^{\perp}$ such that $\Gamma_{3}(a, c, y) \neq \emptyset$ and hence, using Lemma 4.1 and $\Gamma_{3}(a, x)=\emptyset$, we deduce that $d(y, c)=1$. So $y \in\{a, c\}^{\perp}$ and therefore, as $y \neq b, c \in \Delta_{2}^{1}(a)$. But, by Lemma $4.5(\mathrm{iii}), y \in \Delta_{2}^{2}(x)$ which forces $z=c$, a contradiction.

Lemma 4.11. (i) $\left|\Delta_{3}^{5}(a)\right|=2^{12}$.3.7.11.23 and, for $x \in \Delta_{3}^{5}(a)$, $2^{4} A_{5} \sim G_{a x} \leq G_{a c b}$ where $\{c\}=\Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ and $\{b\}=\{a, c\}^{\perp}$. Furthermore $G_{a x}^{* x} \sim 2^{4} A_{5}$ with the $A_{5}$ having orbits of length 1 and 6 upon $\Gamma_{3}(x+c)$, the orbit of length 1 being $\{X(x, b)\}$.
(ii) $\left|\Delta_{3}^{6}(a)\right|=2^{9}$.5.7.11.23 and, for $x \in \Delta_{3}^{6}(a),\left[2^{9}\right] 3^{2} \sim G_{a x} \leq G_{a c x}$ where $\{c\}=\Delta_{2}^{1}(a) \cap \Delta_{1}(x)$.

Proof. (i) Combining (2.3), Lemmas 3.8(iii) and 4.9(i) with the definition of $\Delta_{3}^{5}(a)((2.15))$ gives

$$
\left|\Delta_{3}^{5}(a)\right|=2^{6} .7 \cdot 11.23 \cdot 2 \cdot 96=2^{12} .3 .7 .11 .23
$$

Therefore, by Lemma 4.4, $\left|G_{a x}\right|=2^{7}$.3.5. Since $\{a, b, c, x\}$ is the unique length 3 path from $x$ to $a$, clearly $G_{a x} \leq G_{a c b}$. Now, from (2.3), $G_{c c+x}^{* c} \cong A_{5}$ and so we see that $G_{a x} \sim 2^{4} A_{5}$ with $2^{4} \cong O_{2}\left(G_{a x}\right)=G_{a x} \cap Q(c)$. Also from (2.3) we have that $G_{c c+x}^{* c}$ has orbits of length 1 and 6 upon the elements of the heptad $c+x$ (note that $(c+b) \cap(c+x)$ is the orbit of length 1 ). Since elements of $\Omega_{c}$ correspond to hyperplanes of $\Gamma$, this information translates to $\Gamma_{x}$, so it remains to show that $G_{a x}^{* x} \sim 2^{4} A_{5}$. If this is not the case, then, as $O_{2}\left(G_{a x}\right)$ is a $G_{a x}$-chief factor, $O_{2}\left(G_{a x}\right) \leq Q(x)$. Because $a \in \Delta_{3}^{5}(x)$ by Lemma 4.9(ii) we also get $O_{2}\left(G_{a x}\right) \leq Q(a)$. But then $2^{4} \cong O_{2}\left(G_{a x}\right) \leq Q(a) \cap Q(c)$, which is untenable by [5; Lemma 5.10].
(ii) Putting together (2.3) and Lemmas 3.8(iii) and 4.10 yields

$$
\left|\Delta_{3}^{6}(a)\right|=\frac{2^{6} \cdot 7 \cdot 11 \cdot 23 \cdot 2 \cdot 80}{4}=2^{9} \cdot 5 \cdot 7 \cdot 11.23
$$

Hence $\left|G_{a x}\right|=2^{9} 3^{2}$ by Lemma 4.4,so proving (ii).

From our knowledge of the sizes of $\Delta_{3}^{i}(a)(i \in\{1, \ldots, 6\})$ in Lemmas 4.8 and 4.11, together with Lemma 4.7, we deduce the following useful fact.

Lemma 4.12. For $i \in\{1, \ldots, 6\}$, if $x \in \Delta_{3}^{i}(a)$, then $a \in \Delta_{3}^{i}(x)$.

Theorem 17. (i) Let $x \in \Delta_{2}^{1}(a)$. Then $G_{x a}^{* x}\left(\sim 2^{4} S_{5} 3\right)$ is the stabilizer in $G_{x}^{* x}$ of the triad $T(x, a)$ in $\Omega$ and for all five points $b \in\{a, x\}^{\perp}, x+b$ contains $T(x, a)$.
(ii) Let $x \in \Delta_{2}^{2}(a)$. Then $G_{x a}^{* x}\left(\sim 2^{4} A_{6}\right)$ is the stabilizer in $G_{x}^{* x}$ of the heptad $x+b$ and the element $X(x, a)$ of $\Omega_{x}$ where $\{b\}=\{a, x\}^{\perp}$.
(iii) Let $x \in \Delta_{3}^{1}(a)$. Then $G_{x a}^{* x}\left(\sim L_{3}(4) 2\right)$ is the stabilizer in $G_{x}^{* x}$ of the duad $D(x, a)$. Furthermore, for all 21 points $c \in \Delta_{2}^{1}(a) \cap \Delta_{1}(x)$, the heptad $x+c$ contains $D(x, a)$ in $\Omega_{x}$ and $D(a, x) \subseteq T(a, c)$ in $\Omega_{a}$.
(iv) Let $x \in \Delta_{3}^{2}(a)$. Then $G_{x a}^{* x}\left(\sim 2^{3} L_{3}(2)\right)$ is the stabilizer in $G_{x}^{* x}$ of an octad $O(x, a)$ and the element $X(x, a)$ of $\Omega_{x}$ where $O(x, a)$ has the following properties:-
(a) $(x+c) \cap O(x, a)=\emptyset$ and $X(x, a) \in x+c$ in $\Omega_{x}$ for each of the 7 points $c \in \Delta_{2}^{1}(a) \cap \Delta_{1}(x)$;
(b) $|(x+c) \cap O(x, a)|=4$ and $X(x, a) \in x+c$ in $\Omega_{x}$ for each of the 14 points $c \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$;
(c) $X(x, a) \notin O(x, a)$ in $\Omega_{x}$; and
(d) $T(x, b) \cap O(x, a)=\emptyset$ in $\Omega_{x}$ for each $b \in \Delta_{1}(a) \cap \Delta_{2}^{1}(x)$.
item Let $x \in \Delta_{3}^{3}(a)$. Then $G_{x a}^{* x}\left(\sim 2^{4} A_{6}\right)$ is the stabilizer in $G_{x}^{* x}$ of the heptad $x+c$ and the element $X(x, a)$ of $\Omega_{x}$ where $\{c\}=$ $\Delta_{2}^{2}(a) \cap \Delta_{1}(x)$. Furthermore, $\Gamma_{0}(x+c) \backslash\{x, c\} \subseteq \Delta_{3}^{4}(a)$.
(v) Let $x \in \Delta_{3}^{4}(a)$. Then $G_{x a}^{* x}\left(\cong M_{22}\right)$ is the stabilizer in $G_{x}^{* x}$ of the element $X(x, a)$ of $\Omega_{x}$ and $x+c$ contains $X(x, a)$ for all the 77 points $c \in \Delta_{2}^{2}(a) \cap \Delta_{1}(x)$.
(vi) Let $x \in \Delta_{3}^{5}(a)$. Then $G_{x a}^{* x}\left(\sim 2^{4} A_{5}\right)$ stabilizes the heptad $x+c$ and the element $X(x, b)$ of $x+c$ in $\Omega_{x}$ where $\{c\}=\Delta_{2}^{2}(a) \cap \Delta_{1}(x)$ and $\{b\}=\Delta_{1}(a) \cap \Delta_{2}^{2}(x)$.
(vii) Let $x \in \Delta_{3}^{6}(a)$. Then $G_{x a} \sim\left[2^{9}\right] 3^{2}$ stabilizes the triad $T(x, b)$ and the heptad $x+c$ which contains $T(x, b)$, where $\{b\}=\Delta_{1}(a) \cap \Delta_{2}^{1}(x)$ and $\{c\}=\Delta_{2}^{1}(a) \cap \Delta_{1}(x)$.

Proof. For parts (i) and (ii) see Lemmas 3.7(i),(ii) and 3.8(i),(ii) respectively. Parts (iii)-(vi) follow from Lemma 4.8 and [5; Lemmas 6.7, 6.16, 7.8 and Proposition 7.13]. Finally parts (vii) and (viii) can be deduced from Lemmas 4.5, 4.9 and 4.11(i),(ii).

Lemma 4.13. Let $x \in \Delta_{3}(a)$, with $c \in \Delta_{2}^{1}(a) \cap \Delta_{1}(x)$ and $b \in$ $\{a, c\}^{\perp} \cap \Delta_{2}^{1}(x)$. Then,
(i) $x \in \Delta_{3}^{1}(a)$ if and only if $|T(b, x) \cap T(c, a)|=2$ in $\Omega_{c}$; and
(ii) $x \in \Delta_{3}^{2}(a)$ if and only if $|T(b, x) \cap T(c, a)|=1$ in $\Omega_{c}$; and
(iii) $x \in \Delta_{3}^{6}(a)$ if and only if $|T(b, x) \cap T(c, a)|=0$ in $\Omega_{c}$.

Proof. If $x \in \Delta_{3}^{6}(a)$, then $\Gamma_{3}(a, x)=\emptyset$ implies that $T(b, x) \cap$ $T(c, a)=\emptyset$ in $\Omega_{c}$. Conversely, if $T(b, x) \cap T(c, a)=\emptyset$, then $\Gamma_{3}(a, x)=\emptyset$ and hence $x \in \Delta_{3}^{6}(a)$, which proves (iii).

Since $\Delta_{2}^{2}(a) \cap \Delta_{1}(x)=\emptyset$ for all $x \in \Delta_{3}^{1}(a)$, we must have $x \in \Delta_{3}^{1}(a)$ if and only if $|T(b, x) \cap T(c, a)|=2$ in $\Omega_{c}$. So (i) is proved. Part (ii) now follows using parts (i) and (iii) and (2.15).

Between them, the last two results of this section settle the question of adjacency within $\Delta_{3}(a)$, with the exception of edges between two points which are either both in $\Delta_{3}^{5}(a)$ or both in $\Delta_{3}^{6}(a)$.

Lemma 4.14. Let $1 \leq i<j \leq 6$ and suppose that $x \in \Delta_{3}^{i}(a)$ and $y \in \Delta_{3}^{j}(a)$ with $d(x, y)=1$. Then $x, y \in \Delta_{3}^{1}(a) \cup \Delta_{3}^{2}(a) \cup \Delta_{3}^{3}(a) \cup \Delta_{3}^{4}(a)$. Further, $X(a, y) \in D(a, x)$ (when $i=1$ ) and $X(a, x)=X(a, y)$ (when $i \neq 1)$, and exactly one of the following three possibilities hold.
(i) $i=1, j=3$ with $x+y \in \alpha_{1}(x, D(x, a))$ and $y+x \in \alpha_{1,1}(y, y+$ $b, X(y, a))\left(\{b\}=\Delta_{1}(y) \cap \Delta_{2}^{2}(a)\right)$. Furthermore $\Gamma_{0}(y+x) \backslash\{x, y\} \subseteq$ $\Delta_{3}^{3}(a)$.
(ii) $i=2, j=3$ with $x+y \in \alpha_{2,1}(x, O(x, a), X(x, a))$ and $y+x \in$ $\alpha_{3,1}(y, y+b, X(y, a))\left(\{b\}=\Delta_{1}(y) \cap \Delta_{2}^{2}(a)\right)$. Furthermore $\Gamma_{0}(y+$ $x) \backslash\{x, y\} \subseteq \Delta_{3}^{3}(a)$.
(iii) $i=3, j=4$ with $x+y=x+b$ (where $\{b\}=\Delta_{1}(x) \cap \Delta_{2}^{2}(a)$ ) and $y+x \in \alpha_{1}(y, X(y, a))$.

Proof. We begin by establishing that
(4.14.1) $i \in\{1,2,3,4\}$ and $j \in\{5,6\}$ cannot hold.

Suppose (4.15.1) is false. Then we have $x \in \bigcup_{l=1}^{4} \Delta_{3}^{l}(a)$ and $y \in$ $\Delta_{3}^{5}(a) \cup \Delta_{3}^{6}(a)$ with $d(x, y)=1$. By (2.15)(vii), (viii) we may choose $c \in \Delta_{1}(y) \cap \Delta_{2}^{2}(a)$. Let $\{b\}=\{a, c\}^{\perp}$. From Lemma 3.8(i) we have $\Gamma_{3}(a, c)=\{X(a, c)\}$ and, by Lemma 4.3(ii), $\Gamma_{3}(a, x) \neq \emptyset$. Let $X \in$ $\Gamma_{3}(a, x)$, and set $X(a, c)=Y$.

Since $\Gamma_{3}(a, y)=\emptyset, y \notin \Gamma_{0}(X)$ and consequently $y^{\tau(X)} \neq y$. Also we have $b \notin \Gamma_{0}(X)$, for otherwise an appeal to Lemma 4.1 gives either $y \in$ $\Gamma_{0}(X)$ or $d(b, x)=1$, which cannot hold as $d(a, x)=3$. Thus $b^{\tau(X)} \neq b$. Note that, as $\tau(X) \in Q(a), c^{\tau(X)} \in \Gamma_{0}(Y)$. Because $y \notin \Gamma_{0}(Y)$ we have that $y^{\tau(X)} \notin \Gamma_{0}(Y)$. Therefore $y^{\tau(X)} \neq y$ and $y^{\tau(X) \tau(Y)} \neq y$. So the state of play is as follows.


Observe that $y+c \neq y+x \neq y^{\tau(X)}+c^{\tau(X)}\left(\right.$ as $\Gamma_{0}(y+c) \cap \Delta_{2}(a) \neq$ $\left.\emptyset \neq \Gamma_{0}\left(y^{\tau(X)}+c^{\tau(X)}\right) \cap \Delta_{2}(a)\right)$. Also, $d\left(y^{\tau(X)}, y^{\tau(Y)}\right)=1$ yields, by Lemma 3.4, the impossible $c \in \Gamma_{0}(y+x)$. Hence we deduce that $y^{\tau(Y)} \in$ $\Delta_{2}^{1}\left(y^{\tau(X)}\right)$ with $y, y^{\tau(X) \tau(Y)} \in\left\{y^{\tau(Y)}, y^{\tau(X)}\right\}^{\perp}$ and $y \neq y^{\tau(X) \tau(Y)}$. Calling upon Lemma 3.10 gives $d\left(c, c^{\tau(X)}\right)=1$. This in turn implies that $c \in \Delta_{2}^{1}\left(b^{\tau(X)}\right)$. But then $b+c \in \alpha_{3}(b, b+a)$ which contradicts Lemma 3.8(i) and the fact that $c \in \Delta_{2}^{2}(a)$. This completes the proof of (4.15.1).
(4.14.2) $i=5$ and $j=6$ cannot hold.

Again we suppose this statement is false. So we have $x \in \Delta_{3}^{5}(a)$, $y \in \Delta_{3}^{6}(a)$ with $d(x, y)=1$. Putting $m=\left|\Delta_{1}(x) \cap \Delta_{3}^{6}(a)\right|$ and $n=$ $\left|\Delta_{1}(y) \cap \Delta_{3}^{5}(a)\right|$ we obtain $m\left|\Delta_{3}^{5}(a)\right|=n\left|\Delta_{3}^{6}(a)\right|$. Hence $24 m=5 n$, using Lemma 4.11. Therefore $5 \mid m$. Now $\Delta_{1}(x) \cap \Delta_{3}^{6}(a)$ must be a union of $G_{a x}$-orbits, and so, by (2.7) and Lemma 4.11(i), we deduce that $m \geq 40$. Hence $24.40 \leq 5 n$, which gives $n \geq 192$. Let $b \in \Delta_{2}^{1}(y) \cap \Delta_{1}(a)$ - by Lemma 4.5 (iii) such a point $b$ exists. From Lemma $4.12 a \in \Delta_{3}^{5}(x)$. In view of (4.15.1) (with $x$ playing the role of $a, a$ the role of $y$ and $b$ the role of $x) b \notin \Delta_{3}^{1}(x) \cup \Delta_{3}^{2}(x)$. Using Lemma 4.12 again gives $x \notin \Delta_{3}^{1}(b) \cup \Delta_{3}^{2}(b)$. Hence $(y+x) \cap T(y, b)=\emptyset$ and therefore $y+x \in$ $\alpha_{0}(y, T(y, b))$. This shows that $n \leq 80.2=160$, contrary to the earlier prediction of $n \geq 192$. Thus we have verified (4.15.2).

By (4.15.1) and (4.15.2) we have that $x, y \in \bigcup_{l=1}^{4} \Delta_{3}^{l}(a)$. Now we prove that
(4.14.3) $X(a, y) \in D(a, x)$ (when $i=1)$ and $X(a, x)=X(a, y)$ (when $i \neq 1$ ).

If (4.15.3) is false, then we may find $X \in \Gamma_{3}(a, x)$ and $Y \in \Gamma_{3}(a, y)$ for which $y \notin \Gamma_{0}(X)$ and $x \notin \Gamma_{0}(Y)$. Then employing Lemma 3.2, $y^{\tau(X)}=x^{\tau(Y)}$, which, by Lemma 4.4, forces $\Delta_{3}^{i}(a)=\Delta_{3}^{j}(a)$. This, by Lemma 4.8, is clearly impossible.

From (4.15.3) we get that $x+y \in \Gamma_{1}(X)$ for some $X \in \Gamma_{3}(a, y, x)$ and then, consulting [5], we obtain one of the three listed possibilities, so proving the lemma.

Lemma 4.15. Suppose $x, y \in \Delta_{3}^{i}(a)$ where $i \in\{1,2,3,4\}$. If $d(x, y)=1$, then $D(a, x)=D(a, y)($ for $i=1)$ and $X(a, x)=X(a, y)$ (for $i \neq 1$ ).

Proof. Suppose the lemma is false. Then we must have $X \in$ $\Gamma_{0}(a, x)$ and $Y \in \Gamma_{0}(a, y)$ such that $X \notin D(a, y)$ and $Y \notin D(a, x)$
(if $i=1$ ), $X \neq X(a, y)$ and $Y \neq X(a, x)$ (if $i \neq 1)$. So $y \notin \Gamma_{0}(X)$ and $x \notin \Gamma_{0}(Y)$. Therefore, by Lemma 3.2, $y \neq y^{\tau(X)} \in \Gamma_{0}(x+y)$, in addition to $y^{\tau(X)} \in \Gamma_{0}(Y)$. Hence $x+y \in \Gamma_{1}(Y)$ and then $x \in \Gamma_{0}(Y)$, a contradiction.

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