



## ON THE NICHOLS ALGEBRA ASSOCIATED

$$\text{TO } (q_{ij}) = \begin{pmatrix} -i & i & 1 \\ 1 & -1 & -i \\ 1 & 1 & i \end{pmatrix}, \text{ OF RANK 3}$$

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### Abstract

We examine the defining relations of the Nichols algebra associated to

$$(q_{ij}) = \begin{pmatrix} -i & i & 1 \\ 1 & -1 & -i \\ 1 & 1 & i \end{pmatrix} \text{ of rank 3 by using the results by Angiono}$$

[2] and the method by Nichols [1].

### 1. Introduction

Nichols algebras are graded braided Hopf algebras with the base field in degree 0 and which are coradically graded and generated by its primitive elements ([3], [4], [5], [6], [7]). Let  $V$  be a vector space and  $c : V \otimes V \rightarrow V \otimes V$  be a linear isomorphism. Then  $(V, c)$  is called a *braided vector space*, if  $c$  is a solution of the braid equation, that is,  $(c \otimes id)(id \otimes c)(c \otimes id) = (id \otimes c)(c \otimes id)(id \otimes c)$ . The

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pair  $(V, c)$  determines the Nichols algebras up to isomorphism. Let  $G$  be a group. Then a Yetter-Drinfeld module  $V$  over  $\mathbb{K}G$  is a  $G$ -graded vector space  $V = \bigoplus_{g \in G} V_g$ , which is a  $G$ -module such that  $g \cdot V_h \subset V_{ghg^{-1}}$  for all  $g, h \in G$ . The category  ${}^G_G YD$  of  $\mathbb{K}G$ -Yetter-Drinfeld module is braided. For  $V, W \in {}^G_G YD$ , the braiding  $c: V \otimes W \rightarrow W \otimes V$  is defined by  $c(v \otimes w) = (g \cdot w) \otimes v$ ,  $v \in V_g$ ,  $w \in W$ . Let  $V$  be a Yetter-Drinfeld module over  $G$  and let  $T(V) = \bigoplus_{n \geq 0} T(V)(n)$  denote the tensor algebra of the vector space  $V$ . Let  $S$  be the set of all ideals and coideals  $I$  of  $T(V)$  which are generated as ideals by  $\mathbb{N}$ -homogeneous elements of degree  $\geq 2$ , and which are Yetter-Drinfeld submodule of  $T(V)$ . Let  $I(V) = \sum_{I \in S} I$ . Then  $B(V) := T(V)/I(V)$  is called the *Nichols algebra* of  $V \in {}^G_G YD$ . In this article, we examine the defining relations of the Nichols algebra  $B(V)$  associate to  $(q_{ij}) =$

$$\begin{pmatrix} -1 & i & 1 \\ 1 & -1 & -i \\ 1 & 1 & i \end{pmatrix}, \text{ of rank 3.}$$

## 2. Nichols Algebras of Cartan Type

Let  $\mathbb{K}$  be an algebraically closed field of characteristic 0. Let  $G$  an abelian group and  $V$  be a finite dimensional Yetter-Drinfeld module. Then the braiding is given by a non zero scalar  $q_{ij} \in \mathbb{K}$ ,  $1 \leq i, j \leq \theta$ , in the form  $c(x_i \otimes x_j) = q_{ij} x_j \otimes x_i$ , where  $x_1, \dots, x_\theta$  is a basis of  $V$ . If there is a basis such that  $g \cdot x_i = \chi_i(g) x_i$  and  $x_i \in V_{g_i}$ , then  $V$  is called *diagonal type*. For the braiding, we have  $c(x_i \otimes x_j) = \chi_j(g_i) x_j \otimes x_i$  for  $1 \leq i, j \leq \theta$ . Hence we have  $(q_{ij})_{1 \leq i, j \leq \theta} = (\chi_j(g_i))_{1 \leq i, j \leq \theta}$ . Let  $B(V)$  be the Nichols algebra of  $V$ . Then we can construct the Nichols algebra by  $B(V) \cong T(V)/I$ , where  $I$  denotes the sum of all ideals of  $T(V)$  that are generated by homogeneous elements of degree  $\geq 2$  and that are coideals. If  $B(V)$  is finite-dimensional, then the matrix  $(a_{ij})$  defined by for all  $1 \leq i \neq j \leq \theta$  by  $a_{ii} := 2$  and  $a_{ij} := -\min\{r \in \mathbb{N} \mid q_{ij} q_{ji} q_{ii}^r = 1 \text{ or } (r+1)_{q_{ii}} = 0\}$  is a generalized Cartan matrix fulfilling  $q_{ij} q_{ji} = q_{ii}^{a_{ij}}$  or  $\text{ord } q_{ii} = 1 - a_{ij}$ .  $(a_{ij})$  is called *Cartan*

matrix associated to  $B(V)$ . To examine the defining relations of  $B(V)$ , we use the results [2] and [3].

**Proposition 2.1** [3]. (1) For all  $1 \leq i \leq \theta$ , there exists a uniquely determined  $(id, \sigma)$ -derivation  $D_i : B(V) \rightarrow B(V)$  with  $D_i(x_j) = \delta_{ij}$  (Kronecker  $\delta$ ) for all  $j$ .

$$(2) \bigcap_{i=1}^{\theta} \ker(D_i) = \mathbb{K}1.$$

**Proposition 2.2** [2]. Let  $(V, c)$  be a braided vector space that  $\dim V = 3$ , and

the corresponding generalized Dynkin diagram is  $\overset{q}{\circ} \overset{q^{-1}}{\text{---}} \overset{-1}{\circ} \overset{r^{-1}}{\text{---}} \overset{r}{\circ}$ . Then  $B(V)$  is presented by generators  $x_1, x_2, x_3$ , and relations

$$(2.2.1) \quad x_1^M = x_2^2 = x_3^N = x_{\alpha_1+2\alpha_2+\alpha_3=0}^P = 0,$$

$$(2.2.2) \quad (ad_c x_1)^2 x_2 = (ad_c x_3)^2 x_2 = (ad_c x_1) x_3 = 0,$$

$$(2.2.3) \quad [x_{\alpha_1+\alpha_2}, x_{\alpha_1+\alpha_2+\alpha_3}]_c = [x_{\alpha_1+\alpha_2+\alpha_3}, x_{\alpha_2+\alpha_3}]_c = 0.$$

If  $M, N, P < \infty$ , then  $\dim B(V) = 16MNP$ .

Using these, we obtain the following:

**Proposition 2.3.** Let  $(q_{ij}) = \begin{pmatrix} -i & i & 1 \\ 1 & -1 & -i \\ 1 & 1 & i \end{pmatrix}$ ,  $(\overset{-i}{\circ} \overset{i}{\text{---}} \overset{-1}{\circ} \overset{-i}{\text{---}} \overset{i}{\circ})$  (where

$\omega$  is a primitive cube root of unity.). Then the Nichols algebra  $B(V)$  is described as follows:

Generators :  $x_1, x_2, x_3$ .

$$\text{Relations : } x_1^4 = 0, \quad x_2^2 = 0, \quad x_3^4 = 0, \quad x_1^2 x_2 - (i+1)x_1 x_2 x_1 + i x_2 x_1^2 = 0,$$

$$x_3^2 x_2 - (i+1)x_3 x_2 x_3 + i x_2 x_3^2 = 0,$$

$$(x_1 x_2)^2 = i(x_2 x_1)^2, \quad x_1 x_3 = x_3 x_1, \quad (x_3 x_2)^2 = i(x_2 x_3)^2,$$

$$x_2 x_1 x_2 x_3 + (i-1)x_2 x_1 x_3 x_2 + x_2 x_3 x_2 x_1 - i x_1 x_2 x_3 x_2 - i x_3 x_2 x_1 x_2 = 0.$$

*Its basis is given as follows:*

$$\begin{aligned}
& \{1, x_1, x_2, x_3, x_1^2, x_1x_2, x_1x_3, x_2x_1, x_2x_3, x_3^2, x_3x_2, x_1^3, x_2x_1^2, x_3x_1^2, x_1x_2x_1, \\
& x_1x_2x_3, x_2x_1x_2, x_2x_1x_3, x_2x_3x_2, x_3^3, x_1x_3^2, x_2x_3^2, x_3x_2x_1, \\
& x_3x_2x_3, x_2x_1^3, x_3x_1^3, x_1x_2x_1^2, (x_1x_2)^2, x_1x_2x_1x_3, x_1x_2x_3x_2, x_1x_3x_2x_3 \\
& x_1x_3x_2x_1, x_2x_1x_2x_3, x_3x_2x_1^2, x_2x_3x_1^2, x_2x_3x_2x_1, \\
& (x_2x_3)^2, x_3x_2x_3x_1, x_2x_3x_1x_2, x_2x_3^3, x_1x_3^3, \\
& x_1x_2x_3^2, x_2x_1x_3^2, x_1^2x_3^2, x_3x_2x_3^2, x_1x_2x_1^3, x_2x_3x_1^3, \\
& x_3x_2x_1^3, x_2x_1x_2x_1^2, x_3x_1x_2x_1^2, x_2x_3x_2x_1^2, x_3x_2x_3x_1^2, x_1x_2x_3x_1^2, (x_1x_2)^2x_3, \\
& x_1x_2x_3x_2x_1, x_1(x_2x_3)^2, x_1x_3x_2x_3x_1, x_3(x_1x_2)^2, x_2x_1x_2x_3x_2, (x_2x_3)^2x_1, \\
& x_2x_3x_1x_2x_1, x_2x_3x_1x_2x_3, x_3x_2x_3x_1x_2, x_1x_2x_3x_1x_2, x_1x_2x_3^3, x_2x_1x_3^3, x_3x_2x_3^3, \\
& x_1x_2x_1x_3^2, x_2x_1x_2x_3^2, x_3x_1x_2x_3^2, x_2x_3x_2x_3^2, x_3x_2x_1x_3^2, x_2x_1^2x_3^2, x_1^2x_3^3, x_1^3x_3^2, \\
& x_2x_1x_2x_1^3, x_3x_1x_2x_1^3, x_1x_2x_3x_1^3, x_2x_3x_2x_1^3, x_3x_2x_3x_1^3, x_1x_2x_3x_2x_1^2, \\
& (x_2x_3)^2x_1^2, x_2x_1x_2x_3x_1^2, x_3x_1x_2x_3x_1^2, (x_1x_2)^2x_3x_2, x_1(x_2x_3)^2x_1, \\
& x_2x_1(x_2x_3)^2, x_3(x_1x_2)^2x_3, x_2x_1x_2x_3x_2x_1, x_2x_3(x_1x_2)^2, (x_2x_3x_1)^2, \\
& (x_2x_3)^2x_1x_2, (x_3x_2x_1)^2, x_2x_1x_3x_2x_1^2, (x_1x_2x_3)^2, x_2x_3x_2x_3^3, \\
& x_1x_3x_2x_3^3, x_3x_2x_1x_3^3, x_2x_1x_2x_3^3, x_1x_2x_1x_3^3, x_3x_2x_1x_2x_3^2, (x_2x_1)^2x_3^2, \\
& x_2x_3x_2x_1x_3^2, x_1x_3x_2x_1x_3^2, x_2x_3x_1x_2x_3^2, x_3x_2x_1^2x_3^2, x_1x_2x_1^2x_3^2, x_1^3x_3^3, x_2x_1^2x_3^3, \\
& x_2x_1^3x_3^2, x_2x_3x_1x_2x_1^3, x_2x_1x_2x_3x_1^3, x_3x_1x_2x_3x_1^3, x_1x_2x_3x_2x_1^3, \\
& (x_2x_3)^2x_1^3, x_3x_2x_1x_2x_3x_1^2, x_1(x_2x_3)^2x_1^2, x_2x_1x_2x_3x_2x_1^2, (x_1x_2)^2x_3x_2x_1, \\
& (x_1x_2)^2x_3x_2x_3, x_2x_1(x_2x_3)^2x_1, x_2x_3(x_1x_2)^2x_3, (x_2x_3x_1)^2x_2,
\end{aligned}$$

$$\begin{aligned}
& (x_2x_3)^2x_1x_2x_1, x_1x_2x_1x_3x_2x_1^2, (x_3x_2x_1)^2x_2, (x_3x_2x_1)^2x_1, (x_1x_2x_3)^2x_1, \\
& x_1(x_2x_3)^2x_1x_2, x_2x_1x_3x_2x_3^3, x_2x_3x_2x_1x_3^3, x_1x_3x_2x_1x_3^3, x_3x_2x_1x_2x_3^3, \\
& (x_2x_1)^2x_3^3, x_1x_2x_3x_2x_1x_3^2, x_3(x_2x_1)^2x_3^2, x_2x_3x_2x_1x_2x_3^2, x_3x_2x_3x_1x_2x_3^2, \\
& x_1x_2x_3x_1x_2x_3^2, x_2x_3x_2x_1^2x_3^2, x_2x_1x_2x_1^2x_3^2, x_2x_1^3x_3^3, x_3x_2x_1^2x_3^3, \\
& x_3x_2x_1^3x_2^2, x_1x_2x_1^2x_3^3, x_1x_2x_1^3x_2^2, (x_1x_2x_3)^2x_1^2, (x_2x_3)^2x_1x_2x_1^2, \\
& x_3x_2x_3x_1x_2x_1^3, x_2x_3x_1x_2x_3x_1^3, x_2x_1x_2x_3x_2x_1^3, x_1(x_2x_3)^2x_1^3, x_2x_1(x_2x_3)^2x_1^2, \\
& (x_1x_2)^2x_3x_2x_3x_1, x_3(x_1x_2)^2x_3x_2x_1, (x_2x_3x_1)^2x_2x_1, (x_1x_2x_3)^2x_1x_2, \\
& (x_1x_2)^2x_3x_2x_1^2, x_2x_1(x_2x_3)^2x_1x_2, x_1x_2x_3(x_1x_2)^2x_3, (x_1x_3x_2)^2x_1^2, \\
& (x_3x_2x_1)^2x_3^2, (x_2x_1)^2x_3x_2x_3^2, x_1x_2x_1x_3x_2x_3^3, x_2x_1x_3x_2x_1x_3^3 \\
& x_2x_3x_2x_1x_2x_3^3, x_3(x_2x_1)^2x_3^3, x_2x_3(x_2x_1)^2x_3^2, (x_3x_2)^2x_1x_2x_3^2, \\
& (x_3x_1x_2)^2x_3^2, x_1x_2x_3x_2x_1x_1^2x_3^2, (x_2x_3)^2x_1^2x_3^2, x_2x_3x_1x_2x_1^2x_3^2, x_1x_2x_1^3x_3^3, \\
& x_3x_2x_1^3x_3^3, x_1x_3x_2x_1^2x_3^3, x_2x_3x_2x_1^3x_2^2, x_1x_3x_2x_1^3x_2^2, x_2x_1x_2x_1^3x_2^2, \\
& (x_3x_2)^2x_1x_2x_1x_3, (x_2x_3)^2x_1x_2x_1^3, x_1(x_2x_3)^2x_1x_2x_1^2, (x_1x_2x_3)^2x_1^3, (x_1x_2)^2x_3x_2x_1^3, \\
& x_3x_2x_1(x_2x_3)^2x_1^2, x_1x_2x_1(x_2x_3)^2x_1^2, (x_1x_2x_3)^2x_1x_2x_1, x_3(x_1x_2)^2x_3x_2x_1^2, \\
& x_2x_1(x_2x_3)^2x_1x_2x_1, (x_2x_1x_3)^2x_2x_1^2, x_2x_1x_2x_3x_2x_1^2x_3^2, x_3x_2x_3x_1x_2x_1^2x_3^2, \\
& x_1x_2x_3x_1x_2x_1^2x_3^2, x_2x_1x_2x_1^3x_3^3, x_3x_1x_2x_1^3x_3^3, x_2x_3x_2x_1^3x_3^3, \\
& x_1x_2x_3x_1x_2x_1^2x_3^3, x_2x_3x_1x_2x_1^2x_3^3, x_1x_2x_3x_2x_1^3x_3^2, x_2x_3x_1x_2x_1^3x_3^2, \\
& (x_2x_1)^2x_3x_2x_3^3, x_3(x_2x_1)^2x_3x_2x_3^2, (x_3x_2x_1)^2x_3^3, (x_3x_2)^2x_1x_2x_3^3, \\
& x_1x_2x_3(x_2x_1)^2x_3^2, x_3x_2x_3(x_2x_1)^2x_3^2, x_1(x_3x_2)^2x_1x_2x_3^2, (x_2x_3x_1)^2x_2x_3^2, \\
& (x_3x_2x_1)^2x_3x_2x_3, x_2x_3(x_2x_1)^2x_3x_2x_3, x_1(x_2x_3)^2x_1x_2x_1^3, (x_2x_1x_3)^2x_2x_1^3,
\end{aligned}$$

$$\begin{aligned}
& (x_2x_1)^2x_3x_2x_3x_1^3, x_2x_3(x_1x_2)^2x_3x_2x_1^2, x_1x_2x_3(x_1x_2)^2x_3x_2x_1, (x_1x_2x_3)^2(x_1x_2)^2 \\
& x_3(x_2x_1)^2x_3x_2x_3^3, (x_2x_3x_1)^2x_2x_3^3, (x_2x_3)^2x_1x_2x_1x_3^3, x_2x_1(x_3x_2)^2x_1x_2x_3^2, \\
& (x_1x_2x_3)^2x_1x_2x_3^2, (x_1x_2x_3)^2x_1x_2x_3^2, (x_1x_2)^2x_3x_2x_1^2x_3^2, (x_2x_3)^2x_1x_2x_1^2x_3^2, \\
& x_1x_2x_3x_2x_1^3x_3^3, x_2x_3x_1x_2x_1^3x_3^3, x_2x_1x_2x_3x_2x_1^2x_3^3, x_3x_2x_3x_1x_2x_1^2x_3^3, \\
& x_1x_2x_3x_1x_2x_1^2x_3^3, x_2x_1x_2x_3x_2x_1^3x_3^2, x_3x_2x_3x_1x_2x_1^3x_3^2, x_1x_2x_3x_1x_2x_1^3x_3^2, \\
& x_2x_1(x_2x_3)^2x_1x_2x_1^3, x_1x_2x_3(x_1x_2)^2x_3x_2x_1^2, (x_1x_2x_3)^2(x_1x_2)^2x_1, \\
& x_2x_3(x_2x_1)^2x_3x_2x_3^3, x_3x_2x_1(x_3x_2)^2x_1x_2x_3^2, (x_3x_2x_1)^2(x_3x_2)^2x_3, \\
& (x_2x_3x_1)^2x_2x_1^2x_3^2, (x_3x_2x_1)^2x_2x_1^2x_3^2, x_1(x_2x_3)^2x_1x_2x_1^2x_3^2, \\
& x_2x_1x_2x_3x_2x_1^3x_3^3, x_1x_2x_3x_1x_2x_1^3x_3^3, (x_1x_2)^3x_3x_2x_1^2x_3^3, (x_2x_3)^2x_1x_2x_1^3x_3^2, \\
& (x_1x_2x_3)^2(x_1x_2)^2x_1^2, (x_3x_2x_1)^2(x_3x_2)^2x_3^2, (x_1x_2x_3)^2x_1x_2x_1^2x_3^2, \\
& (x_3x_2x_1)^2x_3x_2x_1^2x_3^2, x_2x_3(x_2x_1)^2x_3x_2x_1^2x_3^2, x_1(x_2x_3)^2x_1x_2x_1^3x_3^2, \\
& x_3(x_2x_1)^2x_3x_2x_1^2x_3^3, x_2(x_1x_2x_3)^2x_1x_2x_1^2x_3^3, x_2(x_3x_2x_1)^2x_3x_2x_1^2x_3^2, \\
& x_2x_3(x_1x_2)^2(x_3x_2x_1)^2x_3, x_3x_2(x_1x_2x_3)^2x_1x_2x_1^2x_3^2\}.
\end{aligned}$$

Hence the Hilbert polynomial of  $B(V)$  is given as follows:

$$\begin{aligned}
P(t) = & 1 + 3t + 7t^2 + 13t^3 + 21t^4 + 30t^5 + 35t^6 + 36t^7 + 35t^8 + 30t^9 \\
& + 21t^{10} + 13t^{11} + 7t^{12} + 3t^{13} + t^{14}.
\end{aligned}$$

**Proof.** They are directly calculated. □

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