



INFINITESIMAL HOLOMORPHICALLY PROJECTIVE TRANSFORMATIONS ON TANGENT BUNDLES WITH RESPECT TO THE SYNECTIC METRIC TENSOR

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Abstract

In this paper, we find solutions of a system of partial differential equations which characterize infinitesimal holomorphically projective transformation on TM with Levi-Civita connection of the synectic metric and an adapted almost complex structure. Further, we investigate necessary conditions in order that TM admits a non-affine infinitesimal holomorphically projective transformation.

1. Introduction

Let M be an n -dimensional connected manifold and TM its tangent bundle. In the present paper, everything will be discussed in the C^∞ -category. We denote by $\mathfrak{Z}_s^r(M)$ the set of all tensor fields of type (r, s) on M , and by $\mathfrak{Z}_s^r(TM)$ the corresponding set on TM .

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Let ∇ be an affine connection on M . Then a vector field V on M is called an *infinitesimal projective transformation* if there exists a 1-form Ω on M such that

$$(L_V \nabla)(X, Y) = \Omega(X)Y + \Omega(Y)X,$$

for any $X, Y \in \mathfrak{X}_0^1(M)$, where L_V is the Lie derivation with respect to V . In this case, Ω is called the *associated 1-form* of V . Especially, if $\Omega = 0$, then the vector field V is called an *infinitesimal affine transformation*.

Next, let (M, J) be an almost complex manifold with an affine connection ∇ . Then a vector field V on M is called an *infinitesimal holomorphically projective transformation* if there exists a 1-form Ω on M such that

$$(L_V \nabla)(X, Y) = \Omega(X)Y + \Omega(Y)X - \Omega(JX)JY - \Omega(JY)JX,$$

for any $X, Y \in \mathfrak{X}_0^1(M)$. In this case, Ω is also called the *associated 1-form* of V , and if $\Omega = 0$, then V is an infinitesimal affine transformation, too.

The problems of determining infinitesimal holomorphically projective transformation on M and on TM have been considered by several authors. In 1957, Ishihara [5] has introduced the notion of infinitesimal holomorphically projective transformation, and Tachibana and Ishihara [7] investigated infinitesimal holomorphically transformation on Kählerian manifolds. In [1], Aminova and Kalinin studied the Lie algebras of infinitesimal H -projective (holomorphically-projective) transformation of $2n$ -dimensional Kähler manifolds with constant holomorphic sectional curvature. In [2, 4], Hasegawa and Yamauchi investigated infinitesimal holomorphically projective transformation on TM with respect to the horizontal and complete lift connections. Recently, Tarakci et al. [9] have studied a similar problem on TM with respect to the metric $II + III$. Therefore, in this paper, we use the method of adapted frames to investigate the case of the Levi-Civita connection of the symplectic metric on TM , introduced by Talantova and Shirokov [8], and prove the following two theorems:

Theorem 1. *Let (M, g) be a Riemannian manifold and TM its tangent bundle with the Levi-Civita connection of the symplectic metric and an adapted almost complex structure. Then A vector field \tilde{V} is an infinitesimal holomorphically projective transformation with associated 1-form $\tilde{\Omega}$ on TM if and only if there*

exist $\varphi, \psi \in \mathfrak{S}_0^0(M)$, $B = (B^h)$, $D = (D^h) \in \mathfrak{S}_0^1(M)$, $A = (A_i^h)$, $C = (C_i^h) \in \mathfrak{S}_1^1(M)$ satisfying

1. $(\tilde{V}^h, \tilde{V}^{\bar{h}}) = (B^h + y^a A_a^h + 2\varphi y^h - y^a \Psi_a y^h, D^h + y^a C_a^h + 2\psi y^h + y^a \Phi_a y^h)$,
2. $(\tilde{\Omega}_i, \tilde{\Omega}_{\bar{i}}) = (\partial_i \psi, \partial_{\bar{i}} \varphi) = (\Psi_i, \Phi_i)$,
3. $\nabla_i \Phi_j = 0, \quad \nabla_{\bar{i}} \Psi_j = 0$,
4. $\nabla_i A_j^a = \Phi_j \delta_i^a - \Phi_i \delta_j^a$,
5. $\nabla_i C_j^a = \Psi_j \delta_i^a - \Psi_i \delta_j^a - B^h R_{hij}^a - H_{hi}^a A_j^h - 2\varphi H_{ji}^a$,
6. $L_B \Gamma_{ji}^a = \nabla_j \nabla_i B^a + B^h R_{hji}^a = \Psi_j \delta_i^a + \Psi_i \delta_j^a + H_{ji}^h A_h^a + 2\varphi H_{ji}^a$,
7. $L_D \nabla = \nabla_j \nabla_i D^a + D^h R_{hji}^a = -\Phi_j \delta_i^a - \Phi_i \delta_j^a - B^h \nabla_h H_{ji}^a + H_{ji}^h C_h^a$
 $+ 2\psi H_{ji}^a - H_{jh}^a \nabla_i B^h - H_{hi}^a \nabla_j B^h$,
8. $B^h \nabla_h R_{bji}^a = R_{bji}^h C_h^a - C_b^h R_{hji}^a - R_{bjh}^a \nabla_i B^h - R_{bhi}^a \nabla_j B^h$
 $- A_b^h (\nabla_h H_{ji}^a - \nabla_j H_{hi}^a) - 2\varphi \nabla_b H_{ji}^a$,
9. $A_b^h R_{hij}^a + 2\varphi R_{bij}^a = 0$,
10. $\Psi_l H_{ji}^a = 0, \Phi_l H_{ji}^a = 0$,
11. $\Phi_l R_{kji}^a = 0, \Psi_l R_{kji}^a = 0$,

where $\tilde{V} = (\tilde{V}^h, \tilde{V}^{\bar{h}}) = \tilde{V}^a E_a + \tilde{V}^{\bar{a}} E_{\bar{a}}$ and $\tilde{\Omega} = (\tilde{\Omega}_i, \tilde{\Omega}_{\bar{i}}) = \tilde{\Omega}_a dx^a + \tilde{\Omega}_{\bar{a}} d\bar{y}^{\bar{a}}$.

Theorem 2. Let (M, g) be a Riemannian manifold and TM its tangent bundle with Levi-Civita connection of the symplectic metric and an adapted almost complex structure. If TM admits non-affine infinitesimal holomorphically projective transformation, then the covariant derivative of symmetric tensor field (a_{ji}) of type $(0, 2)$ is zero and M is locally flat.

2. Preliminaries

In this section, we shall summarize all the basic definitions and results on TM that are needed later. Most of them are well-known and details can be found in [11, 12]. Indices a, b, c, i, j, h, \dots have range in $\{1, \dots, n\}$ while indices $\alpha, \beta, \lambda, \mu, \dots$ have range in $\{1, \dots, n; n+1, \dots, 2n\}$. We put $\bar{i} = n + i$. Summation over repeated indices is always implied.

Coordinate systems on M are denoted by (U, x^h) , where U is the coordinate neighborhood and x^h are the coordinate functions. Components in (U, x^h) of geometric objects on M will be referred to simply as components. We denote partial differentiation $\frac{\partial}{\partial x^h}$ by ∂_h .

Let (M, g) be a Riemannian manifold, ∇ be the Riemannian connection of g and Γ_{ji}^a be the coefficients of ∇ , i.e., $\nabla_{\partial_j} \partial_i = \Gamma_{ji}^a \partial_a$ with respect to natural frame $\{\partial_h\}$. Then the curvature tensor R of ∇ has components R_{kji}^h . With the Riemannian connection ∇ given on M , we can introduce on each induced coordinate neighborhood $\pi^{-1}(U)$ of TM a frame field which is very useful in our computation. In each local chart $U(x^h)$ of M , we put

$$X_{(j)} = \frac{\partial}{\partial x^j} = \delta_j^h \frac{\partial}{\partial x^h} \in \mathfrak{S}_0^1(M).$$

Then $2n$ local vector fields ${}^H X_{(j)}$ and ${}^V X_{(j)}$ form a basis of the tangent space $T_P(TM)$ at each point $\tilde{P} = \pi^{-1}(P)$ and their components are given respectively by

$${}^H X_{(j)} = \delta_j^h \partial_h - y^s \Gamma_{sj}^h \partial_{\bar{h}}, \quad (2.1)$$

$${}^V X_{(\bar{j})} = \delta_j^h \partial_{\bar{h}} \quad (2.2)$$

with respect to the natural frame $\left\{ \frac{\partial}{\partial x^H} \right\} = \left\{ \frac{\partial}{\partial x^h}, \frac{\partial}{\partial x^{\bar{h}}} \right\}$ on TM , where δ_i^j -Kronecker delta. These $2n$ vector fields are linear independent and generate,

respectively, the horizontal distribution of ∇ and the vertical distribution of TM . We have called the set $\{ {}^H X_{(j)}, {}^V X_{(\bar{j})} \}$ the frame adapted to the affine connection ∇ in $\pi^{-1}(U) \subset TM$. On putting $E_j = {}^H X_{(j)}$, $E_{\bar{j}} = {}^V X_{(\bar{j})}$, we write the adapted frame as $\{E_\beta\} = \{E_j, E_{\bar{j}}\}$.

By the straightforward calculation, we have the following:

Lemma 1 [11, p. 159]. *The Lie brackets of the adapted frame of TM satisfy the following identities:*

$$[E_j, E_i] = y^b R_{ijb}^a E_{\bar{a}}, \quad [E_j, E_{\bar{i}}] = \Gamma_{ji}^a E_{\bar{a}}, \quad [E_{\bar{j}}, E_{\bar{i}}] = 0. \quad (2.3)$$

Lemma 2 [3]. *Let \tilde{V} be a vector field on TM . Then*

$$\begin{cases} [\tilde{V}, E_i] = -(E_i \tilde{V}^a) E_a + (\tilde{V}^c y^b R_{icb}^a - \tilde{V}^{\bar{b}} \Gamma_{bi}^a - E_i \tilde{V}^{\bar{a}}) E_{\bar{a}}, \\ [\tilde{V}, E_{\bar{i}}] = -(E_{\bar{i}} \tilde{V}^a) E_a + (\tilde{V}^b \Gamma_{bi}^a - E_{\bar{i}} \tilde{V}^{\bar{a}}) E_{\bar{a}}, \end{cases} \quad (2.4)$$

where $(\tilde{V}^h \quad \tilde{V}^{\bar{h}}) = \tilde{V}^a E_a + \tilde{V}^{\bar{a}} E_{\bar{a}}$.

Let g be a Riemannian metric with components g_{ji} . Then we see that

$$\tilde{g} = a_{ji} dx^j dx^i + 2g_{ji} dx^j \delta y^i \quad (2.5)$$

is non-singular and can be regarded as pseudo-Riemannian metric on TM , where $a = (a_{ji})$ is a symmetric tensor field of the type $(0, 2)$ on M and $\delta y^i = dy^i + \Gamma_{lk}^i dx^l y^k$, Γ_{lk}^i being Christoffel symbols formed with g . The metric (2.5) has components

$$\tilde{g} = (\tilde{g}_{\beta\gamma}) = \begin{pmatrix} a_{ji} & g_{ji} \\ g_{ji} & 0 \end{pmatrix}$$

with respect to the adapted frame on TM , that is, it coincides with $\tilde{g} = {}^C g + {}^V a$, where ${}^C g$ and ${}^V a$ denote the complete and vertical lifts of g and a to TM , respectively. The synectic metric \tilde{g} was determined by Talantova and Shirokov [8] to study the differential geometry of tangent bundles of Riemannian manifolds. Their paper is related to the geometry of the space of n dual variables. The concept of a

dual number is the analogue of a complex number: $x + jy$ with $j^2 = 0$. Since the set of dual numbers is represented geometrically by R^2 , the set of n dual variables is represented by $R^{2n} = R^n \times R^n = TR^n$. They showed that the space TR^n with a certain metric represents a space of n dual variables with purely dual constant curvature. This special metric on TR^n is related projectively to the complete lift of the standard metric on R^n . Afterwards, Pavlov [6] studied the tangent bundles with a metric $\lambda^C g + \nu a$ and also proved that the substitution of the metric ${}^C g \rightarrow \lambda^C g + \nu a$ is a necessary and sufficient condition on preserving the “angles” between holomorphic planes.

Remark. In the case of $a = g$, the synectic metric \tilde{g} on TM coincides with the lift metric $I + II$ on TM , where $a = (a_{ji})$ is a symmetric tensor field of the type $(0, 2)$ on M and $g = (g_{ij})$ is a Riemannian metric on M . The metric $I + II$ is introduced by Yano and Ishihara [11, p. 147-155]. Also, they proved that the tangent bundle TM with the metric $I + II$ has vanishing scalar curvature.

We now consider local 1-forms ω^α defined by $\omega^\alpha = \tilde{\mathcal{A}}_B^\alpha dx^B$ in $\pi^{-1}(U)$, where

$$\tilde{\mathcal{A}}_B^\alpha = \begin{pmatrix} \tilde{\mathcal{A}}_j^h & \tilde{\mathcal{A}}_{\bar{j}}^h \\ \tilde{\mathcal{A}}_j^{\bar{h}} & \tilde{\mathcal{A}}_{\bar{j}}^{\bar{h}} \end{pmatrix} = \begin{pmatrix} \delta_j^h & 0 \\ y^s \Gamma_{sj}^h & \delta_j^h \end{pmatrix} \quad (2.6)$$

is the inverse matrix of the matrix

$$\mathcal{A}_\beta^A = \begin{pmatrix} \mathcal{A}_j^h & \mathcal{A}_{\bar{j}}^h \\ \mathcal{A}_j^{\bar{h}} & \mathcal{A}_{\bar{j}}^{\bar{h}} \end{pmatrix} = \begin{pmatrix} \delta_j^h & 0 \\ -y^s \Gamma_{sj}^h & \delta_j^h \end{pmatrix} \quad (2.7)$$

of frames changes $E_\beta = \mathcal{A}_\beta^A \partial_A$. These $2n$ 1-forms ω^α are linearly independent on TM . We call the set $\{\omega^\alpha\}$ the *dual adapted coframe*.

For various types of indices, we have

$$\begin{cases} E_j = \mathcal{A}_j^A \partial_A = \partial_j - y^s \Gamma_{sj}^h \partial_{\bar{h}}, \\ E_{\bar{j}} = \mathcal{A}_{\bar{j}}^A \partial_A = \partial_{\bar{j}}, \end{cases} \quad (2.8)$$

and

$$\begin{cases} \omega^j = \tilde{\mathcal{A}}_B^j dx^B = dx^j, \\ \omega^{\bar{j}} = \tilde{\mathcal{A}}_B^{\bar{j}} dx^B = \delta y^h, \end{cases} \quad (2.9)$$

where $\delta y^h = dy^h + y^b \Gamma_{ba}^h dx^a$.

Since the adapted frame field $\{E_\beta\}$ is non-holonomic, we put

$$[E_\alpha, E_\beta] = \Omega_{\alpha\beta}^\gamma E_\gamma$$

from which we have

$$\Omega_{\gamma\beta}^\alpha = (E_\gamma \mathcal{A}_\beta^A - E_\beta \mathcal{A}_\gamma^A) \tilde{\mathcal{A}}_A^\alpha.$$

Thus, according to equations (2.6), (2.7) and (2.8), the components of non-holonomic object $\Omega_{\gamma\beta}^\alpha$ are given by

$$\begin{cases} \Omega_{ij}^{\bar{r}} = -\Omega_{jl}^{\bar{r}} = \Gamma_{jl}^r, \\ \Omega_{ij}^{\bar{r}} = -\Omega_{jl}^{\bar{r}} = -R_{ljk}^r, \end{cases} \quad (2.10)$$

all the others being zero, with respect to the adapted frame.

If $\tilde{\nabla}$ denote the Levi-Civita connection of \tilde{g} from $\tilde{T}(\tilde{X}, \tilde{Y}) = \tilde{\nabla}_{\tilde{X}} \tilde{Y} - \tilde{\nabla}_{\tilde{Y}} \tilde{X} - [\tilde{X}, \tilde{Y}] = 0$, $\forall \tilde{X}, \tilde{Y} \in \mathfrak{S}_0^1(TM)$, then we have

$$\tilde{\Gamma}_{\gamma\beta}^\alpha - \tilde{\Gamma}_{\beta\gamma}^\alpha = \Omega_{\gamma\beta}^\alpha \quad (2.11)$$

with respect to the adapted frame, where $\tilde{\Gamma}_{\gamma\beta}^\alpha$ are components of the Levi-Civita connection $\tilde{\nabla}$.

The equation $(\tilde{\nabla}_{\tilde{X}} \tilde{g})(\tilde{Y}, \tilde{Z}) = 0$, $\forall \tilde{X}, \tilde{Y}, \tilde{Z} \in \mathfrak{S}_0^l(TM)$ has form

$$E_\delta \tilde{g}_{\gamma\beta} - \tilde{\Gamma}_{\delta\gamma}^\varepsilon \tilde{g}_{\varepsilon\beta} - \tilde{\Gamma}_{\delta\beta}^\varepsilon \tilde{g}_{\gamma\varepsilon} = 0 \quad (2.12)$$

with respect to the adapted frame. Thus, we have from equations (2.11) and (2.12)

$$\tilde{\Gamma}_{\beta\gamma}^\alpha = \frac{1}{2} \tilde{g}^{\alpha\varepsilon} (E_\beta \tilde{g}_{\varepsilon\gamma} + E_\gamma \tilde{g}_{\beta\varepsilon} - E_\varepsilon \tilde{g}_{\beta\gamma}) + \frac{1}{2} (\Omega_{\beta\gamma}^\alpha + \Omega_{\beta\gamma}^\alpha + \Omega_{\gamma\beta}^\alpha), \quad (2.13)$$

where $\Omega_{\gamma\beta}^\alpha = \tilde{g}^{\alpha\varepsilon} \tilde{g}_{\delta\beta} \Omega_{\varepsilon\gamma}^\delta$, $\tilde{g}^{\alpha\varepsilon}$ are the contravariant components of the metric \tilde{g} with respect to the adapted frame:

$$(\tilde{g}^{\alpha\varepsilon}) = \begin{pmatrix} 0 & g^{hr} \\ g^{hr} & -a^{hr} \end{pmatrix}. \quad (2.14)$$

Taking account of equations (2.10), (2.13) and (2.14), for various types of indices, we find

$$\begin{aligned} \tilde{\Gamma}_{ji}^h &= \Gamma_{ji}^h, & \tilde{\Gamma}_{ji}^{\bar{h}} &= y^b R_{bji}^h + H_{ji}^h, & \tilde{\Gamma}_{ji}^{\bar{h}} &= 0, \\ \tilde{\Gamma}_{ji}^h &= 0, & \tilde{\Gamma}_{ji}^{\bar{h}} &= \Gamma_{ji}^h, & \tilde{\Gamma}_{ji}^h &= 0, & \tilde{\Gamma}_{ji}^{\bar{h}} &= 0, & \tilde{\Gamma}_{ji}^h &= 0 \end{aligned} \quad (2.15)$$

with respect to the adapted frame, where Γ_{ji}^h denote the Levi-Civita connection components constructed with g on M with respect to the natural frame $\{\partial_i\}$ and H_{ji}^h is a tensor field of type (1, 2) defined by $H_{ji}^h = \frac{1}{2} g^{hr} (\nabla_j a_{ri} + \nabla_i a_{jr} - \nabla_r a_{ji})$ [8] (see [10, p. 166]).

If \tilde{X} is a vector field on TM with frame components \tilde{X}^α , then it can be written that the frame components

$$\tilde{\nabla}_\lambda \tilde{X}_\alpha = E_\lambda(\tilde{X}_\alpha) - \tilde{\Gamma}_{\lambda\alpha}^\mu \tilde{X}_\mu, \quad (2.16)$$

where $\tilde{\Gamma}_{\lambda\mu}^\alpha$ being given by equation (2.15).

From equations (2.15) and (2.16), we have

Lemma 3. *Let $\tilde{\nabla}$ be a Levi-Civita connection of the symplectic metric on TM defined as follows:*

$$\begin{cases} \tilde{\nabla}_{E_j} E_i = \Gamma_{ji}^a E_a + (y^b R_{bji}^a + H_{ji}^a) E_{\bar{a}}, \\ \tilde{\nabla}_{E_j} E_{\bar{i}} = \Gamma_{ji}^a E_{\bar{a}}, \\ \tilde{\nabla}_{E_j} E_i = 0, \quad \tilde{\nabla}_{E_{\bar{j}}} E_{\bar{i}} = 0. \end{cases} \quad (2.17)$$

Let us consider a tensor field \tilde{J} of type (1, 1) on TM by

$$\tilde{J}^H X = {}^V X, \quad \tilde{J}^V X = -{}^H X,$$

for any $X \in \mathfrak{S}_0^1(M)$, i.e., $\tilde{J}E_i = E_{\bar{i}}$, $\tilde{J}E_{\bar{i}} = -E_i$. Then we obtain $\tilde{J}^2 = -I$. Therefore, \tilde{J} is an almost complex structure on TM . This almost complex structure is called the *adapted almost complex structure*. It is known that \tilde{J} is integrable if and only if M is locally flat [11, p. 118].

3. Proofs of the Theorems

Proof of Theorem 1. Here we prove only the necessary condition because it is easy to prove the sufficient condition. Let \tilde{V} be an infinitesimal holomorphically projective transformation with the associated 1-form $\tilde{\Omega}$ on TM

$$(L_{\tilde{V}}\tilde{\nabla})(\tilde{X}, \tilde{Y}) = \tilde{\Omega}(\tilde{X})\tilde{Y} + \tilde{\Omega}(\tilde{Y})\tilde{X} - \tilde{\Omega}(\tilde{J}\tilde{X})\tilde{J}\tilde{Y} - \tilde{\Omega}(\tilde{J}\tilde{Y})\tilde{J}\tilde{X}, \quad (3.1)$$

for any $\tilde{X}, \tilde{Y} \in \mathfrak{S}_0^1(M)$.

From $(L_{\tilde{V}}\tilde{\nabla})(E_{\bar{j}}, E_{\bar{i}}) = \tilde{\Omega}_{\bar{j}}E_{\bar{i}} + \tilde{\Omega}_{\bar{i}}E_{\bar{j}} - \tilde{\Omega}_{\bar{j}}E_i - \tilde{\Omega}_iE_{\bar{j}}$, we obtain

$$\partial_{\bar{j}}\partial_{\bar{i}}\tilde{V}^h = -\tilde{\Omega}_{\bar{j}}\delta_i^h - \tilde{\Omega}_i\delta_{\bar{j}}^h \quad (3.2)$$

and

$$\partial_{\bar{j}}\partial_{\bar{i}}\tilde{V}^{\bar{h}} = \tilde{\Omega}_{\bar{j}}\delta_i^{\bar{h}} + \tilde{\Omega}_i\delta_{\bar{j}}^{\bar{h}}. \quad (3.3)$$

Contracting i and h in equation (3.2), we have

$$\tilde{\Omega}_{\bar{j}} = \partial_{\bar{j}}\tilde{\Psi}, \quad (3.4)$$

where $\tilde{\Psi} = -\frac{1}{n+1}\partial_{\bar{a}}\tilde{V}^a$. Hence equation (3.2) is rewritten as follows:

$$\partial_{\bar{j}}\partial_{\bar{i}}\tilde{V}^h = -(\partial_{\bar{j}}\tilde{\Psi})\delta_i^h - (\partial_{\bar{i}}\tilde{\Psi})\delta_{\bar{j}}^h. \quad (3.5)$$

Differentiating equation (3.5) partially, we have

$$\begin{aligned} \partial_{\bar{k}}\partial_{\bar{j}}\partial_{\bar{i}}\tilde{V}^h &= -(\partial_{\bar{k}}\partial_{\bar{j}}\tilde{\Psi})\delta_i^h - (\partial_{\bar{k}}\partial_{\bar{i}}\tilde{\Psi})\delta_{\bar{j}}^h \\ &= -(\partial_{\bar{j}}\partial_{\bar{i}}\tilde{\Psi})\delta_{\bar{k}}^h - (\partial_{\bar{i}}\partial_{\bar{k}}\tilde{\Psi})\delta_j^h \\ &= -(\partial_{\bar{i}}\partial_{\bar{k}}\tilde{\Psi})\delta_j^h - (\partial_{\bar{i}}\partial_{\bar{j}}\tilde{\Psi})\delta_k^h, \end{aligned} \quad (3.6)$$

from which we obtain

$$\partial_{\bar{k}}\partial_{\bar{j}}(\partial_{\bar{i}}\tilde{V}^h + 2\tilde{\Psi}\delta_i^h) = 0. \quad (3.7)$$

Therefore, we can put

$$P_{ji}^h = \partial_{\bar{j}}(\partial_{\bar{i}}\tilde{V}^h + 2\tilde{\Psi}\delta_i^h) \quad (3.8)$$

and

$$A_i^h + y^a P_{ai}^h = \partial_{\bar{i}}\tilde{V}^h + 2\tilde{\Psi}\delta_i^h, \quad (3.9)$$

where A_i^h and P_{ji}^h are certain functions which depend only on the variables (x^h) .

The coordinate transformation rule implies that $A = (A_i^h) \in \mathfrak{S}_1^1(M)$ and $P = (P_{ji}^h) \in \mathfrak{S}_2^1(M)$.

Using equation (3.5), we have

$$P_{ji}^h + P_{ij}^h = 2\{\partial_{\bar{j}}\partial_{\bar{i}}\tilde{V}^h + (\partial_{\bar{j}}\tilde{\Psi})\delta_i^h + (\partial_{\bar{i}}\tilde{\Psi})\delta_j^h\} = 0 \quad (3.10)$$

from which, using equation (3.8), we obtain

$$P_{ji}^h = \frac{1}{2}(P_{ji}^h - P_{ij}^h) = (\partial_{\bar{j}}\tilde{\Psi})\delta_i^h - (\partial_{\bar{i}}\tilde{\Psi})\delta_j^h. \quad (3.11)$$

On the other hand, using equation (3.9), we have

$$\tilde{\Psi} = -\varphi + y^a \Psi_a, \quad (3.12)$$

where $\varphi = -\frac{1}{n-1}A_a^a$ and $\Psi_i = \frac{1}{n-1}P_{ia}^a$, from which

$$\tilde{\Omega}_i = \partial_{\bar{i}}\tilde{\Psi} = \Psi_i. \quad (3.13)$$

Using equations (3.9), (3.11) and (3.13), we obtain

$$\partial_{\bar{i}}\tilde{V}^h = A_i^h + 2\varphi\delta_i^h - y^h\Psi_i - y^a\Psi_a\delta_i^h,$$

from which

$$\tilde{V}^h = B^h + y^a A_a^h + 2\varphi y^h - y^a \Psi_a y^h, \quad (3.14)$$

where B^h are certain functions which depend only on (x^h) . The coordinate transformation rule implies that $B = (B^h) \in \mathfrak{S}_0^1(M)$.

Similarly, from equation (3.3), there exist $\psi \in \mathfrak{S}_0^0(M)$, $\Phi = (\Phi_i) \in \mathfrak{S}_1^0(M_n)$, $D = (D^h) \in \mathfrak{S}_0^1(M)$ and $C = (C_i^h) \in \mathfrak{S}_1^1(M)$ satisfying

$$\tilde{\varphi} = \psi + y^a \Phi_a, \quad (3.15)$$

$$\tilde{\Omega}_{\bar{i}} = \partial_{\bar{i}} \tilde{\varphi} = \Phi_{\bar{i}} \quad (3.16)$$

and

$$\tilde{V}^{\bar{h}} = D^h + y^a C_a^h + 2\psi y^h + y^a \Phi_a y^h, \quad (3.17)$$

where $\tilde{\varphi} = \frac{1}{n+1} \partial_{\bar{a}} \tilde{V}^{\bar{a}}$ and $\psi = -\frac{1}{n-1} C_a^a$.

Next, from equation (3.1), we have

$$(L_{\tilde{V}} \tilde{\nabla})(E_{\bar{j}}, E_i) = \Phi_j E_i + \Phi_i E_j + \Psi_j E_{\bar{i}} + \Psi_i E_{\bar{j}} \quad (3.18)$$

or

$$(L_{\tilde{V}} \tilde{\nabla})(E_j, E_{\bar{i}}) = \Phi_j E_i + \Phi_i E_j + \Psi_j E_{\bar{i}} + \Psi_i E_{\bar{j}}.$$

From equation (3.18), we get

$$\begin{aligned} & (\Phi_j \delta_i^a + \Phi_i \delta_j^a) E_a + (\Psi_j \delta_i^a + \Psi_i \delta_j^a) E_{\bar{a}} \\ &= \{(\nabla_i A_j^a + 2\delta_j^a \partial_i \varphi) - y^b (\delta_b^a \nabla_i \Psi_j + \delta_j^a \nabla_i \Psi_b)\} E_a \\ &+ \{(\nabla_i C_j^a + 2\delta_j^a \partial_i \psi + B^h R_{hij}^a + H_{hi}^a A_j^h + 2\varphi H_{ji}^a) + y^b (A_b^h R_{hij}^a + A_j^h R_{bih}^a + 4\varphi R_{bij}^a \\ &+ \delta_a^b \nabla_i \Phi_j + \delta_j^a \nabla_i \Phi_b - H_{bi}^a \Psi_j - H_{ji}^a \Psi_b) + y^b y^c (\Psi_j R_{icb}^a - 2\Psi_c R_{bij}^a)\} E_{\bar{a}}. \end{aligned} \quad (3.19)$$

Comparing both hands of the above equation, we obtain

$$\begin{aligned} \Phi_j &= \partial_j \varphi, \quad \nabla_i \Phi_j = 0, \\ \Psi_j &= \partial_j \psi, \quad \nabla_i \Psi_j = 0, \\ \nabla_i A_j^a &= \Phi_j \delta_i^a - \Phi_i \delta_j^a, \\ \nabla_i C_j^a &= \Psi_j \delta_i^a - \Psi_i \delta_j^a - B^h R_{hij}^a - H_{hi}^a A_j^h - 2\varphi H_{ji}^a, \\ A_b^h R_{hij}^a &= -2\varphi R_{bij}^a, \quad \Psi_l R_{kji}^a = 0, \quad \Psi_l H_{ji}^a = 0. \end{aligned} \quad (3.20)$$

Lastly, from $(L_{\tilde{V}}\tilde{\nabla})(E_j, E_i) = \Psi_j E_i + \Psi_i E_j - \Phi_j E_{\bar{i}} - \Phi_i E_{\bar{j}}$, we obtain

$$\begin{aligned}
& (\Psi_j \delta_i^a + \Psi_i \delta_j^a) E_a - (\Phi_j \delta_i^a + \Phi_i \delta_j^a) E_{\bar{a}} \\
&= \{L_B \Gamma_{ji}^a - H_{ji}^h A_h^a - 2\varphi H_{ji}^a\} E_a \\
&+ \{(L_D \Gamma_{ji}^a + B^h \nabla_h H_{ji}^a - H_{ji}^h C_h^a - 2\psi H_{ji}^a + H_{jh}^a \nabla_i B^h + H_{hi}^a \nabla_j B^h) \\
&+ y^b (C_b^h R_{hji}^a + B^h \nabla_h R_{bji}^a - R_{bji}^h C_h^a + R_{bjh}^a \nabla_i B^h + R_{bhi}^a \nabla_j B^h + A_b^h (\nabla_h H_{ji}^a \\
&- \nabla_j H_{hi}^a) + 2\varphi \nabla_b H_{ji}^a - \Phi_i H_{jb}^a - 3\Phi_j H_{bi}^a) + y^b y^c (\Phi_c R_{bji}^a + \Phi_c R_{bij}^a - \Phi_j R_{cib}^a \\
&- \Phi_i R_{cjb}^a + 2\varphi \nabla_c R_{bji}^a + 2\varphi \nabla_j R_{cib}^a + A_c^h \nabla_h R_{bji}^a + A_c^h \nabla_j R_{hib}^a)\} E_{\bar{a}}, \quad (3.21)
\end{aligned}$$

from which, we get the following important information:

$$L_B \Gamma_{ji}^a = \nabla_j \nabla_i B^a + R_{hji}^a B^h = \Psi_j \delta_i^a + \Psi_i \delta_j^a + H_{ji}^h A_h^a + 2\varphi H_{ji}^a, \quad (3.22)$$

$$\begin{aligned}
L_D \nabla &= \nabla_j \nabla_i D^a + D^h R_{hji}^a \\
&= -\Phi_j \delta_i^a - \Phi_i \delta_j^a - B^h \nabla_h H_{ji}^a + H_{ji}^h C_h^a \\
&+ 2\psi H_{ji}^a - H_{jh}^a \nabla_i B^h - H_{hi}^a \nabla_j B^h, \quad (3.23)
\end{aligned}$$

$$\begin{aligned}
B^h \nabla_h R_{bji}^a &= R_{bji}^h C_h^a - C_b^h R_{hji}^a - R_{bjh}^a \nabla_i B^h - R_{bhi}^a \nabla_j B^h \\
&- A_b^h (\nabla_h H_{ji}^a - \nabla_j H_{hi}^a) - 2\varphi \nabla_b H_{ji}^a, \quad (3.24)
\end{aligned}$$

$$\Phi_l R_{bji}^a = 0, \quad \Phi_l H_{ji}^a = 0. \quad (3.25)$$

This completes the proof.

Using this Theorem 1, we at last come to the following:

Proof of Theorem 2. Let \tilde{V} be a non-affine infinitesimal holomorphically projective transformation on M . Using equation (3) in Theorem 1, we have $\nabla_i \|\Phi\|^2 = \nabla_i \|\Psi\|^2 = 0$. Hence, $\|\Phi\|$ and $\|\Psi\|$ are constants on M . Suppose that M is not locally flat and the covariant derivative of symmetric tensor field (a_{ji}) of

type $(0, 2)$ is non-zero, then $\Phi = \Psi = 0$ by virtue of equations (10) and (11) in Theorem 1, that is, \tilde{V} is an infinitesimal affine transformation. This is a contradiction. Therefore, M is locally flat and the covariant derivative of symmetric tensor field (a_{ji}) of type $(0, 2)$ is zero. In this case, TM is also locally flat [8, 10].

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