# EXAMPLES OF PEIRCE DECOMPOSITION OF GENERALIZED JORDAN TRIPLE SYSTEMS OF SECOND ORDER II - BALANCED CLASSICAL CASES - 

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#### Abstract

In this paper, we consider examples of the Peirce decomposition of simple balanced generalized Jordan triple systems of second order associated with Lie algebras. By virtue of choice of a tripotent element for these triple systems, we can realize the decomposition without using the root systems of Lie algebras.


## 0. Introduction

One of the main object of study in this article is to provide examples of a Peirce decomposition of simple balanced generalized Jordan triple systems of second order.

It is known that the all simple Lie algebras $L$ have a decomposition of 5-graded Lie algebras as follows:

$$
L=L_{-2} \oplus L_{-1} \oplus L_{0} \oplus L_{1} \oplus L_{2},
$$

starting with a triple system, which has a triple product's structure into

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the subspace component $L_{1}$ of $L$. And if $\operatorname{dim} L_{-2}=\operatorname{dim} L_{2}=1$, then it is said to be a balanced triple system for $L_{1}$, furthermore, a property of 5 -grading of Lie algebras is reduced from that property of triple systems equipped with 2 nd order (to see, $[6,7,8,9,10]$ ). This is one of simple reasons for us to consider about the triple systems.

General speaking for our mathematical field (that is, nonassociative algebras), it seems that nonassociative algebras are rich in algebraic structures and mathematical physics. They provide an important common ground for various branches of mathematics, not only for pure algebra and differential geometry, but also for representation theory and algebraic geometry. That is, the concept of nonassociative algebras which contain Jordan algebras (superalgebras) and Lie algebras (superalgebras) plays an important role in many mathematical and physical subjects (for example, [4], [8], [17], [25], [26], [29], [30], etc.). We have determined that the construction and characterization of these algebras can be expressed in terms of the notion of triple systems ([22], [9], [10], [27]), in particular, by using the standard embedding method ([23], [24], [11], [13], [28]).

Describing our recent results in brief, we find the following:

* For the construction of simple Lie algebras, the generalized Jordan triple system of second order (that is, the $(-1,1)$-Freudenthal-Kantor triple system) is a useful concept ([6], [7], [8], [9], [10], [11], [20]).
* For the construction of simple Lie superalgebras, the $(-1,-1)$ -Freudenthal-Kantor triple system is a useful concept ([13], [16], [2], [3], [18]).
* For the construction of Jordan superalgebras, the $\delta$-Jordan-Lie triple system is a useful concept ([27], [14], [15]).
* For the characterization and representation of mathematical physics, the triple system is useful concept, in particular, Yang-Baxter equations, generalized Zorn vector matrix, etc., ([26], [28], [17], [19]).

Our purpose is to propose a unified structural theory for triple systems. In previous work [22], we have studied the Peirce decomposition
of the generalized Jordan triple system $U$ of second order by employing a tripotent element $e$ of $U$, (tripotent element means $\{e e e\}=e$ ). The Peirce decomposition of $U$ is described as follows:

$$
U=U_{00} \oplus U_{\frac{1}{2} \frac{1}{2}} \oplus U_{11} \otimes U_{\frac{3}{2} \frac{3}{2}} \oplus U_{-\frac{1}{2} 0} \oplus U_{01} \oplus U_{\frac{1}{2} 2} \oplus U_{13},
$$

where $L(a)=\{e e a\}=\lambda a$ and $R(a)=\{a e e\}=\mu \alpha$ if $a \in U_{\lambda \mu}$.
In particular, if the tripotent element is the left unit (left unit element $e$ means eex $=x, \forall x \in U$ ), then we have

$$
U=U_{11}^{+} \oplus U_{11}^{-} \oplus U_{13}^{+} \oplus U_{13}^{-},
$$

where $Q(x)= \pm x$ if $x \in U_{11}^{ \pm}$, and $Q(x)= \pm 3 x$ if $x \in U_{13}^{ \pm}$.
On the other hand, for the Peirce decomposition of a Jordan triple system $U$, it is well known that

$$
U=U_{00} \oplus U_{\frac{1}{2} \frac{1}{2}} \oplus U_{11} \text {, (only 3-component's decomposition). }
$$

In the present article, we shall investigate examples of the Peirce decomposition of simple balanced generalized Jordan triple systems of second order. And only consider classical type cases, for exceptional cases, we shall deal with it in forthcoming paper [12].

We are concerned with triple systems which have finite dimensionality over a field $\Phi$ of characteristic $\neq 2$ or 3 , unless otherwise specified.

## 1. Definitions and Preamble

In order to render this paper as self-contained as possible, we first recall the definition of a generalized Jordan triple system of second order (hereafter, referred to as GJTS of 2nd order), and the construction of Lie algebras associated with GJTS of 2nd order.

A vector space $V$ over a field $\Phi$, endowed with a trilinear operation $V \times V \times V \rightarrow V,(x, y, z) \mapsto\{x y z\}$, is said to be a GJTS of 2nd order if
the following two conditions are satisfied:
(J1) $\{a b\{x y z\}\}=\{\{a b x\} y z\}-\{x\{b a y\} z\}+\{x y\{a b z\}\},(G J T S)$
(K1) $K(K(a, b) x, y)-L(y, x) K(a, b)-K(a, b) L(x, y)=0$, (2nd order)
where $L(a, b) c=\{a b c\}$ and $K(a, b) c=\{a c b\}-\{b c a\}$.
Furthermore, if the GJTS of 2nd order satisfies

$$
\operatorname{dim}_{\Phi}\{K(a, b)\}_{\text {span }}=1
$$

then it is said to be balanced.
On the other hand, we can generalize the concept of GJTS of 2 nd order as follows (see [6], [7], [10], [13] and the references therein).

For $\varepsilon= \pm 1$ and $\delta= \pm 1$, if the triple product satisfies

$$
\begin{aligned}
& (a b(x y z))=((a b x) y z)+\varepsilon(x(b a y) z)+(x y(a b z)), \\
& K(K(a, b) c, d)-L(d, c) K(a, b)+\varepsilon K(a, b) L(c, d)=0,
\end{aligned}
$$

where $L(x, y) z=(x y z)$ and $K(a, b) c=(a c b)-\delta(b c a)$, then it is said to be an $(\varepsilon, \delta)$-Freudenthal-Kantor triple system (hereafter abbreviated as $(\varepsilon, \delta)$-F.-K.t.s.).

The triple products are generally denoted by $\{x y z\},(x y z),[x y z]$, and $\langle x y z\rangle$, as is our convention.

Remark. We note that the concept of GJTS of 2nd order coincides with that of $(-1,1)$-F.-K.t.s. Thus we can construct the simple Lie algebras or superalgebras by means of the standard embedding method ([20], [6, 7, 8, 9, 10], [2], [13], [16], [18]).

Proposition 1.1 ([8], [13]). Let $U(\varepsilon, \delta)$ be an ( $\varepsilon, \delta)$-F.-K.t.s. If $J$ is an endomorphism of $U(\varepsilon, \delta)$ such that $J\langle x y z\rangle=\langle J x J y J J\rangle$ and $J^{2}=-\varepsilon \delta I d$, then $(U(\varepsilon, \delta),[x y z])$ is a Lie triple system (the case of $\delta=1$ ) or an anti-Lie triple system (the case of $\delta=-1$ ) with respect to the product

$$
[x y z]:=\langle x J y z\rangle-\delta\langle y J x z\rangle+\delta\langle x J z y\rangle-\langle y J z x\rangle .
$$

Corollary. Let $U(\varepsilon, \delta)$ be an $(\varepsilon, \delta)$-F.-K.t.s. Then the vector space $T(\varepsilon, \delta)=U(\varepsilon, \delta) \oplus U(\varepsilon, \delta)$ becomes a Lie triple system (the case of $\delta=1$ ) or an anti-Lie triple system (the case of $\delta=-1$ ) with respect to the triple product defined by

$$
\left[\binom{a}{b}\binom{c}{d}\binom{e}{f}\right]=\left(\begin{array}{cc}
L(a, d)-\delta L(c, b) & \delta K(a, c) \\
-\varepsilon K(b, d) & \varepsilon(L(d, a)-\delta L(b, c))
\end{array}\right)\binom{e}{f} .
$$

Thus we can obtain the standard embedding Lie algebra (the case of $\delta=1$ ) or Lie superalgebra (the case of $\delta=-1), L(\varepsilon, \delta)=D(T(\varepsilon, \delta), T(\varepsilon, \delta))$ $\oplus T(\varepsilon, \delta)$, associated with $T(\varepsilon, \delta)$, where $D(T(\varepsilon, \delta), T(\varepsilon, \delta))$ is the set of inner derivations of $T(\varepsilon, \delta)$. That is, these vector spaces $D(T(\varepsilon, \delta), T(\varepsilon, \delta))$ and $T(\varepsilon, \delta)$ mean

$$
D(T(\varepsilon, \delta), T(\varepsilon, \delta)):=\left\{\left(\begin{array}{ll}
L(a, b) & K(c, d) \\
K(e, f) & \varepsilon L(b, a)
\end{array}\right)\right\}_{\text {span }}
$$

and

$$
T(\varepsilon, \delta):=\left\{\left.\binom{x}{y} \right\rvert\, x, y \in U(\varepsilon, \delta)\right\}_{\text {span }}
$$

Remark. We note that $L(\varepsilon, \delta):=L_{-2} \oplus L_{-1} \oplus L_{0} \oplus L_{-1} \oplus L_{-2}$ is the 5 -graded Lie algebra or Lie superalgebra, such that $L_{-1}=U(\varepsilon, \delta)$, $D(T(\varepsilon, \delta), T(\varepsilon, \delta))=L_{-2} \oplus L_{0} \oplus L_{-2}$ with $\left[L_{i}, L_{j}\right] \subseteq L_{i+j}$.

By straightforward calculations for the correspondence of the $(1,1)$ balanced F.-K.t.s. with the $(-1,1)$ balanced F.-K.t.s., we obtain the following.

Proposition 1.2. Let $(U,\langle x y z\rangle)$ be a $(1,1)$ F-K.t.s. If there is an endomorphism $J$ of $U$ such that $J\langle x y z\rangle=\langle J x J y J z\rangle$ and $J^{2}=-I d$, then $(U,\{x y z\})$ is a GJTS of 2 nd order with respect to the product defined by $\{x y z\}:=\langle x J y z\rangle$.

In [9], we obtained all simple $(1,1)$-balanced F.-K.t.s. over the complex number field. Thus, these results (by the special case of above Proposition 1.2 ) give us a list of the simple balanced GJTSs of 2 nd order.

In the next section, we will discuss the explicit forms of this list and investigate examples of the Peirce decomposition by providing a tripotent element of the simple balanced GJTSs of 2nd order.

## 2. Main Results (Classical Types)

On the basis of the results presented in Section 1 and [9], in order to make this section as comprehensive as possible, we first summarize the classical types of simple balanced GJTSs of 2nd order as follows:
$A_{n}$-type. Let $M_{A}(n)$ be a set of the matrix

$$
\left\{\left.\left(\begin{array}{ll}
0 & x \\
y & 0
\end{array}\right) \right\rvert\, x, y \in \operatorname{Mat}(1, n ; \mathbf{C})\right\}
$$

For $M_{A}(n)$, we can define a triple product by

$$
\{x y z\}=x \circ(P J y \circ z)+z \circ(P J y \circ x)-P J y \circ(x \circ z),
$$

where

$$
x \circ y=\left(\begin{array}{cc}
0 & x_{1} \\
x_{2} & 0
\end{array}\right) \circ\left(\begin{array}{cc}
0 & y_{1} \\
y_{2} & 0
\end{array}\right)=\left(\begin{array}{cc}
B\left(x_{1}, y_{2}\right) & 0 \\
0 & B\left(y_{1}, x_{2}\right)
\end{array}\right)
$$

$B(x, y)=x y^{T} \quad\left(y^{T}\right.$ is the transpose matrix of $\left.y\right)$, and furthermore

$$
P:\left(\begin{array}{ll}
0 & x \\
y & 0
\end{array}\right) \rightarrow\left(\begin{array}{cc}
0 & x \\
-y & 0
\end{array}\right) \text { and } J:\left(\begin{array}{cc}
0 & x \\
y & 0
\end{array}\right) \rightarrow\left(\begin{array}{cc}
0 & y \\
-x & 0
\end{array}\right)
$$

That is, if we set

$$
a=B\left(z_{1}, y_{1}\right) x_{1}+B\left(x_{1}, y_{1}\right) z_{1}-B\left(z_{1}, x_{2}\right) y_{2}
$$

and

$$
b=B\left(y_{2}, z_{2}\right) x_{2}+B\left(y_{2}, x_{2}\right) z_{2}-B\left(x_{1}, z_{2}\right) y_{1}
$$

then by straightforward calculations,

$$
\{x y z\}=\left(\begin{array}{ll}
0 & a \\
b & 0
\end{array}\right)
$$

$C_{n}$-type. We identify the vector space $\{x \mid x \in \operatorname{Mat}(1,2 n ; \mathbf{C})\}$ with

$$
M_{c}(n)=\left\{\left.\left(\begin{array}{ll}
0 & x \\
x & 0
\end{array}\right) \right\rvert\, x \in \operatorname{Mat}(1,2 n ; \mathbf{C})\right\}
$$

For $M_{c}(n)$, we can define a triple product by

$$
\{x y z\}=\frac{1}{2}\{\langle J y \mid x\rangle z+\langle J y \mid z\rangle x+\langle x \mid z\rangle J y\}
$$

where $J$ is an endomorphism of $M_{c}(n)$ such that $J^{2}=-I d$ and $\langle x \mid y\rangle$ is an anti-symmetric bilinear form satisfying the relation $\langle J x \mid y\rangle=\langle J y \mid x\rangle$ $=-\langle x \mid J y\rangle$.

Remark. For the $C_{n}$-type of simple balanced GJTS of 2 nd order, there exist an endomorphism and a bilinear form such that

$$
J:\left(x_{1}, \ldots, x_{n}, x_{n+1}, \ldots, x_{2 n}\right) \rightarrow\left(-x_{n+1}, \ldots,-x_{2 n}, x_{1}, \ldots, x_{n}\right)
$$

and

$$
\langle x \mid y\rangle=x_{1} y_{n+1}+\cdots+x_{n} y_{2 n}-x_{n+1} y_{1}-\cdots-x_{2 n} y_{n}
$$

for $x=\left(x_{1}, \ldots, x_{n}, x_{n+1}, \ldots, x_{2 n}\right)$ and $y=\left(y_{1}, \ldots, y_{n}, y_{n+1}, \ldots, y_{2 n}\right)$.
$B_{n}, D_{n}$-types. We identify the space $\{x \mid x \in \operatorname{Mat}(2, p: \mathbf{C})\}$ with

$$
M_{B, D}(p)=\left\{\left.\left(\begin{array}{ll}
0 & x \\
x & 0
\end{array}\right) \right\rvert\, x \in \operatorname{Mat}(2, p ; \mathbf{C})\right\}
$$

For $M_{B, D}(p)$, we can define a triple product by

$$
\{x y z\}=x \circ(P J y \circ z)+z \circ(P J y \circ x)-P J y \circ(x \circ z),
$$

where

$$
\begin{gathered}
x \circ y=\left(\begin{array}{ll}
0 & x \\
x & 0
\end{array}\right) \circ\left(\begin{array}{ll}
0 & y \\
y & 0
\end{array}\right)=\left(\begin{array}{cc}
\left(\sigma_{0} \circ B(x, y)\right)^{T} & 0 \\
0 & B(y, x) \sigma_{0}
\end{array}\right), \\
B(x, y)=x y^{T}(2 \text { by } 2 \text { matrix }), \sigma_{0}=\left(\begin{array}{cc}
0 & -1 \\
1 & 0
\end{array}\right), \text { and } J=\sigma_{0} .
\end{gathered}
$$

That is,

$$
\{x y z\}=\left(\begin{array}{cc}
0 & -z y^{T} x-x y^{T} z+z x^{T} y \\
-z y^{T} x-x y^{T} z+z x^{T} y & 0
\end{array}\right)
$$

Remark. The standard embedding Lie algebras, which are obtained from the types of the triple systems $A_{n-1}, \quad B_{n}(p=2 n-3), C_{n}$ and $D_{n}(p=2 n-4)$ correspond to the types of the classical simple Lie algebras, respectively, ([9], [10]).

In the $A_{n}$-type balanced GJTS of 2nd order:
if we set $e=\left(\begin{array}{rr}0 & e_{1} \\ e_{1} & 0\end{array}\right)$, where $e_{1}$ is a $(1,0, \ldots, 0): 1 \times n$ matrix, then by straightforward calculations, we obtain $\{e e e\}=e$ and $\{e e x\}=x, \forall x \in U$.

On the other hand, we have
$R(x)=\{x e e\}=x$ and $x=\left(\begin{array}{cc}0 & x_{1} \\ x_{2} & 0\end{array}\right)$
$\left\langle\Rightarrow\left\{\begin{array}{l}B\left(e_{1}, e_{1}\right) x_{1}+B\left(x_{1}, e_{1}\right) e_{1}-B\left(e_{1}, x_{2}\right) e_{1}=x_{1} \\ B\left(e_{1}, e_{1}\right) x_{2}+B\left(e_{1}, x_{2}\right) e_{1}-B\left(x_{1}, e_{1}\right) e_{1}=x_{2}\end{array}\right.\right.$
$\left\langle\Rightarrow B\left(e_{1}, x_{2}\right)=B\left(x_{1}, e_{1}\right)\right.$
$\langle=\rangle$ if $x_{1}=\left(a_{1}, \ldots, a_{n}\right)$ and $x_{2}=\left(b_{1}, \ldots, b_{n}\right)$, then $a_{1}=b_{1}$.
Similarly, we have
$R(x)=\{$ xee $\}=3 x$ and $x=\left(\begin{array}{cc}0 & x_{1} \\ x_{2} & 0\end{array}\right)\langle=\rangle$
if $x_{1}=\left(a_{1}, \ldots, a_{n}\right)$ and $x_{2}=\left(b_{1}, \ldots, b_{n}\right)$, then $a_{1}=-b_{1}, a_{i}=b_{i}=0$ $(2 \leq i)$.

Furthermore, we have

$$
\begin{aligned}
& Q(x)=\{\text { exe }\}=x\langle=\rangle a_{2}=-b_{2}, \ldots, a_{n}=-b_{n} \\
& Q(x)=-x\langle=\rangle a_{1}=b_{1}=0, a_{i}=b_{i}(2 \leq i), \\
& Q(x)=3 x\langle=\rangle a_{1}=-b_{1}, a_{i}=b_{i}=0(2 \leq i), \\
& Q(x)=-3 x\langle=\rangle x=0 .
\end{aligned}
$$

Hence, we obtain a Peirce decomposition with respect to the above tripotent $e$ as follows:

$$
\begin{aligned}
& x=\left(\begin{array}{cc}
0 & x_{1} \\
x_{2} & 0
\end{array}\right)=\left(\begin{array}{cc}
0 & \left(a_{1}, \ldots, a_{n}\right) \\
\left(b_{1}, \ldots, b_{n}\right) & 0
\end{array}\right) \\
& =\left(\begin{array}{cc}
0 \\
\left(\frac{a_{1}+b_{1}}{2},-\frac{a_{2}-b_{2}}{2}, \ldots,-\frac{a_{n}-b_{n}}{2}\right) & \left(\frac{a_{1}+b_{1}}{2}, \frac{a_{2}-b_{2}}{2}, \ldots, \frac{a_{n}-b_{n}}{2}\right) \\
0
\end{array}\right) \\
& +\left(\begin{array}{cc}
0 & \left(0, \frac{a_{2}+b_{2}}{2}, \ldots, \frac{a_{n}+b_{n}}{2}\right) \\
\left(0, \frac{a_{2}+b_{2}}{2}, \ldots, \frac{a_{n}+b_{n}}{2}\right) & 0
\end{array}\right) \\
& +\left(\begin{array}{cc}
0 \\
\left(-\frac{a_{1}-b_{1}}{2}, 0, \ldots, 0\right) & \left(\frac{a_{1}-b_{1}}{2}, 0, \ldots, 0\right) \\
0
\end{array}\right) \\
& \in U_{11}^{+} \oplus U_{11}^{-} \oplus U_{13}^{+}=U .
\end{aligned}
$$

In the $B_{n}$ - and $D_{n}$-types of balanced GJTS $U$ of 2 nd order:
if we set $i=\sqrt{-1}$, and $e$ is an $\left(\begin{array}{lll}i 0 & \cdots & 0 \\ 0 i \cdots & i\end{array}\right), \ldots, 2 \times p$ matrix, then by straightforward calculations, we obtain

$$
\{e e e\}=e \text { and }\{e e x\}=x, \forall x \in U .
$$

On the other hand, we have

$$
\begin{aligned}
& R(x)=\{x e e\}=x \\
& \left\langle\Leftrightarrow\left(\begin{array}{cc}
0 & -e e^{T} x-x e^{T} e+e x^{T} e \\
-e e^{T} x-x e^{T} e+e x^{T} e & 0
\end{array}\right)=\left(\begin{array}{ll}
0 & x \\
x & 0
\end{array}\right)\right. \\
& \left\langle\Leftrightarrow x e^{T} e=e x^{T} e\left\langle\Rightarrow x x e^{T}=e x^{T}, \text { by } e e^{T}=\left(\begin{array}{cc}
-1 & 0 \\
0 & -1
\end{array}\right) .\right.\right.
\end{aligned}
$$

Similarly, we have

$$
R(x)=\{x e e\}=3 x\langle=\rangle x e^{T} e=-e x^{T} e\langle=\rangle x e^{T}=-e x^{T} .
$$

Furthermore, we obtain

$$
\begin{aligned}
& Q(x)=\{e x e\}=x\langle=\rangle\{e x e\}=\left(\begin{array}{cc}
0 & -2 e x^{T} e-x \\
-2 e x^{T} e+x & 0
\end{array}\right)=x \\
& \langle=\rangle x=-e x^{T} e\langle=\rangle x e^{T}=-e x^{T} . \\
& Q(x)=\{e x e\}=-x\langle=\rangle x e^{T}=0 . \\
& Q(x)=3 x\langle=\rangle e x^{T} e=-2 x\langle=\rangle 2 x e^{T}=e x^{T} . \\
& Q(x)=-3 x\langle=\rangle x=e x^{T} e\langle=\rangle x e^{T}=-e x^{T} .
\end{aligned}
$$

Hence, we obtain a Peirce decomposition with respect to the tripotent defined by using the above $e$,

$$
x=\frac{x+e x^{T} e}{2}+\frac{x-e x^{T} e}{2} \in U_{13}^{-} \oplus U_{11}^{+}=U
$$

In the $C_{n}$-type balanced GJTS $U$ of 2 nd order:
if we set $e$ as an $(i, 0 \cdots 0,0 \cdots 0) \cdots 1 \times 2 n$ matrix, then we obtain

$$
\{e e e\}=e \text { and }\langle J e \mid e\rangle=I d
$$

By straightforward calculations, we have

$$
\begin{aligned}
& \{e e x\}=\frac{1}{2}(\langle J e \mid x\rangle e+\langle e \mid x\rangle J e+x) \\
& \{x e e\}=\frac{1}{2}(x+\langle J e \mid x\rangle e+\langle x \mid e\rangle J e) \\
& \{e x e\}=\langle J x \mid e\rangle e .
\end{aligned}
$$

On the other hand, by the relation $\langle J x \mid y\rangle=-\langle x \mid J y\rangle$, we have

$$
\{e x e\}=\langle J x \mid e\rangle e=-\langle x \mid J e\rangle e=\langle J e \mid x\rangle e .
$$

Hence, we obtain

$$
\begin{aligned}
& \{\text { eex }\}=x\langle=\rangle x=\left(x_{1}, 0 \cdots 0\right) \text { for } x=\left(x_{1}, x_{2}, \ldots, x_{2 n}\right), \\
& \{\text { eex }\}=\frac{1}{2} x\langle=\rangle x=\left(0, x_{2}, \ldots, x_{n}, 0, x_{n+2}, \ldots, x_{2 n}\right) \text { for } x=\left(x_{1}, \ldots, x_{2 n}\right), \\
& \{\text { eex }\}=0\langle=\rangle x=\left(0 \cdots 0, x_{n+1}, 0 \cdots 0\right) \text { for } x=\left(x_{1}, \ldots, x_{2 n}\right), \\
& \{\text { eex }\}=\frac{3}{2} x\langle=\rangle x=0,\{\text { eex }\}=-\frac{1}{2} x\langle=\rangle x=0,\{\text { xee }\}=3 x\langle=\rangle x=0, \\
& \{\text { xee }\}=\frac{1}{2} x\langle=\rangle x=\left(0, x_{2}, \ldots, x_{n}, 0, x_{n+2}, \ldots, x_{2 n}\right), \\
& \{\text { xee }\}=x\langle=\rangle x=\left(x_{1}, 0, \ldots, 0, x_{n+1}, 0, \ldots, 0\right) .
\end{aligned}
$$

Therefore, we obtain a Peirce decomposition with respect to the tripotent element $e$ as follows:

$$
U=U_{\frac{1}{2} \frac{1}{2}} \oplus U_{11} \oplus U_{01}
$$

where

$$
\begin{aligned}
U_{\frac{1}{2}} \frac{1}{2} & =\left\{\left(0, x_{2}, \ldots, x_{n}, 0, x_{n+2}, \ldots, x_{2 n}\right)\right\}_{\text {span }} \\
U_{11} & =\left\{\left(x_{1}, 0, \ldots, 0\right)\right\}_{\text {span }}
\end{aligned}
$$

and

$$
U_{01}=\left\{\left(0 \cdots 0, x_{n+1}, 0 \cdots 0\right)\right\}_{\text {span }}
$$

These imply the relation:

$$
L(x)(2 L(x)-I d)(L(x)-I d)=0, \text { for } L(x)=\{e e x\} .
$$

From these results, we note that there are several Peirce decompositions by virtue of choice of tripotent elements.

Remark. For the balanced GJTSs of 2nd order of exceptional types $G_{2}, F_{4}, E_{6}, E_{7}$ and $E_{8}$ associated with exceptional simple Lie algebras, we will consider their Peirce decompositions in forthcoming paper [12].

Remark. For the balanced GJTSs of 2nd order, a study has been considered from a geometrical approach (see [1]), that is, he conducted the correspondence of quaternionic structures on symmetric spaces with balanced Freudenthal-Kantor triple systems. Thus it seems that our decompositions are useful in the detail's characterization.

Remark. It seems that this field in nonassociative algebras is very important subject in mathematical physics and differential geometry as well as a characterization and construction of Lie algebras, Lie superalgebras and Yang-Baxter equations. Also, it seems that these triple systems will become useful tools and concept to characterize about infinite dimensional Lie algebras and superalgebras.

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