POSITIVE SOLUTIONS OF SINGULAR nth ORDER BOUNDARY VALUE PROBLEMS WITH NONLOCAL CONDITIONS

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Abstract

We discuss the existence of positive solutions of the following singular *n*th order three point boundary value problem

$$\begin{cases} u^{(n)}(t) + g(t)f(u) = 0, & t \in (0, 1), \\ u(0) = u'(0) = \dots = u^{(n-2)}(0) = 0, \\ \alpha u(\eta) = u(1), \end{cases}$$

where $0 < \eta < 1$, $0 < \alpha \eta^{n-1} < 1$ and g is allowed to have finitely many singularities. The existence of positive solutions of the problem is established by applying the fixed point index theorem under suitable conditions.

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1. Introduction

Investigation of positive solutions of nonlocal boundary value problems, initiated by II'in and Moiseev [7, 8], has recently been addressed by various authors, for instance, [2, 3, 4, 6, 9, 10, 11]. Nonlocal boundary value problems are also referred as multi-point nonlinear boundary value problems in the study of disconjugacy theory [1]. This work is motivated by Eloe and Ahmad [2] who addressed a nonlinear nth order BVP with nonlocal conditions. In fact, we extend the results of [2] by allowing g to have finitely many singularities.

In this paper, we shall establish some existence results for the following *n*th order singular differential equation

$$u^{(n)}(t) + g(t)f(u) = 0, \quad t \in (0, 1),$$
 (1.1)

subject to the boundary conditions

$$u(0) = u'(0) = \dots = u^{(n-2)}(0) = 0, \quad \alpha u(\eta) = u(1),$$
 (1.2)

where $0 < \eta < 1$, $0 < \alpha \eta^{n-1} < 1$.

Throughout this paper, we assume that

 (A_1) $f:[0,\infty) \to [0,\infty)$ is continuous;

(A₂) $g \in L^1(0,1)$, $g(s) \ge 0$, a.e., and there exist $a,b \in [\eta,1]$ with a < b such that $\int_a^b g(s)ds > 0$.

It is clear that the following condition is a special case of the condition (A_2) :

 $(\mathrm{A}_2') \text{ For given points } t_1, \, ..., \, t_m, \quad g:E=[0,1] \backslash \{t_i:i=1,\,...,\,m\} \rightarrow \\ [0,\,\infty) \text{ is continuous and the integral } \int_0^1 g(s)ds \text{ exists, and there exist} \\ a,\,b\in[\eta,\,1] \text{ with } a< b \text{ such that } \int_a^b g(s)ds>0.$

We emphasize that the condition (A'_2) allows g to have finitely many singularities at $t_1, ..., t_m$.

(A₃)
$$0 \le f^0 < M_1$$
, and $m_1 < f_{\infty} \le \infty$.

$$(A_4)$$
 $0 \le f^{\infty} < M_1$ and $m_1 < f_0 \le \infty$, where

$$M_1 = \left(\max_{0 \le t \le 1} \int_0^1 -G(t, s) g(s) ds \right)^{-1}, \quad m_1 = \left(\min_{a \le t \le b} \int_a^b -G(t, s) g(s) ds \right)^{-1},$$

$$G(\eta; t, s) = \begin{cases} \frac{a(\eta; s)t^{n-1}}{(n-1)!}, & 0 \le t \le s \le 1, \\ \frac{a(\eta; s)t^{n-1} + (t-s)^{n-1}}{(n-1)!}, & 0 \le s \le t \le 1, \end{cases}$$

$$a(\eta(s); s) = \begin{cases} -\frac{(1-s)^{n-1}}{1-\alpha\eta^{n-1}}, & \eta \le s, \\ -\frac{(1-s)^{n-1} - (\eta-s)^{n-1}}{1-\alpha\eta^{n-1}}, & s \le \eta. \end{cases}$$
(1.3)

Here $G(\eta; t, s)$ is the Green's function for the BVP (1.1)-(1.2).

Notation. $f^{\beta} = \lim_{x \to \beta} \sup \frac{f(x)}{x}$, $f_{\beta} = \lim_{x \to \beta} \inf \frac{f(x)}{x}$, where β denotes either 0 or ∞ .

By a solution to (1.1)-(1.2) we mean a function $u \in C^{n-2}[0, 1]$, $u^{(n-1)}(t) \in AC[0, 1]$ and u satisfies (1.1)-(1.2), where AC[0, 1] denotes the space of absolutely continuous functions defined on [0, 1].

Evidently $u \in C[0, 1]$ is a positive solution of (1.1)-(1.2) if and only if $u \in C[0, 1]$ is a positive solution of the following integral equation:

$$u(t) = -\int_{0}^{1} G(t, s)g(s)f(u(s))ds.$$
 (1.4)

Remark 1.1. We allow f to satisfy either $0 \le \lim_{x \to 0} \sup \frac{f(x)}{x} < a$ and $b < \lim_{x \to \infty} \inf \frac{f(x)}{x} \le \infty$ or $0 \le \lim_{x \to \infty} \sup \frac{f(x)}{x} \le a$ and $b < \lim_{x \to 0} \inf \frac{f(x)}{x} \le \infty$ for suitable a and b, which implies that f is not necessary superlinear or

sublinear. This relaxation on f improves the results of [2] even if we require g to be a continuous function.

Let K be a cone in a Banach space X and let $K_r = \{x \in K : \|x\| < r\}$, $\partial K_r = \{x \in K : \|x\| = r\}$ and $\overline{K}_{\rho, r} = \{x \in K : \rho \le \|x\| \le r\}$, where $0 < \rho < r < \infty$.

Lemma 1.1 [5]. Let K be a cone in a Banach space X and $A: K_r \to K$ be a compact map. Assume that the following conditions hold.

- (i) $||Ax|| \le ||x||$ for $x \in \partial K_r$.
- (ii) There exists an $e \in \partial K_1$ such that $x \neq Ax + \lambda e$ for $x \in \partial K_{\rho}$ and $\lambda > 0$.

Then A has a fixed point in $\overline{K}_{\rho,r}$. The same condition remains valid if (i) holds on ∂K_{ρ} and (ii) holds on ∂K_{r} .

We shall need the following well-known results.

Lemma 1.2 [2]. Let $u \in C[0, 1]$ satisfy the differential inequality $u^{(n)}(t) < 0$, together with the boundary conditions (1.2) and $0 < \alpha \eta^{n-1} < 1$. Then $u \ge 0$ on [0, 1].

Lemma 1.3 [2]. Let $0 < \alpha \eta^{n-1} < 1$. Let u satisfy $u^{(n)}(t) \le 0$, 0 < t < 1 with the nonlocal conditions (1.2). Then $\inf_{t \in [\eta, 1]} u(t) \ge \gamma ||u||$, where $\gamma = \min\{\alpha \eta^{n-1}, \alpha(1-\eta)(1-\alpha\eta)^{-1}, \eta^{n-1}\}$.

Lemma 1.4 [2]. For each $s \in (0, 1)$, set $|G(\tau(s), s)| = \max_{t \in [0, 1]} |G(t, s)|$. Then $|G(t, s)| \ge \gamma |G(\tau(s), s)|$, $\forall 0 \le s \le 1$.

2. Main Results

Theorem 2.1. Assume that conditions (A_1) , (A_2) and (A_3) hold. Then BVP (1.1)-(1.2) has at least one positive solution u(t) with $u(t) \neq 0$ for $t \in [0, 1]$. **Proof.** Let K be a cone in C[0, 1] given by

$$K = \{u : u \in C[0, 1], u \ge 0, \min_{t \in [\eta, 1]} u(t) \ge \gamma ||u|| \}.$$

Define an operator as follows:

$$(Au)(t) = -\int_{0}^{1} G(t, s)g(s)f(u(s))ds.$$

Then from Lemma 1.3 we can get $A:K\to K$. Now, we prove that A is compact. We first prove that A is continuous. Let $M=\max\{-G(t,s):t,s\in[0,1]\}$. Assume that $u_n,\,u_0\in K$ and $u_n\to u_0$. Then $\|\,u_n\,\|\le L$ for every $n\ge 0$. Since f is continuous on [0,L], it is uniformly continuous. Therefore, for $\varepsilon>0$ there exists a $\delta>0$ such that $|z'-z''|<\delta$ implies that $|f(z')-f(z'')|<\varepsilon\Big(M\int_0^1g(s)ds\Big)^{-1}$. Since $u_n\to u_0$, there exists an $n_0\in \mathbf{N}$ such that $\|\,u_n-u_0\,\|<\delta$ for $n\ge n_0$. Thus we have

$$|f(u_n(t)) - f(u_0(t))| < \varepsilon \left(M \int_0^1 g(s) ds\right)^{-1}, \text{ for } n \ge n_0 \text{ and } t \in [0, 1].$$

This implies that

$$|Au_n(t) - Au_0(t)| \le \int_0^1 |G(t, s)| g(s) |f(u_n(t)) - f(u_0(t))| ds < \varepsilon,$$

for $t \in [0, 1]$ and $n \ge n_0$, and therefore $||Au_n(t) - Au_0(t)|| \le \varepsilon$ for $n \ge n_0$.

Next, let $B \in K$ be bounded, i.e., $\|x\| \le m$ for all $x \in B$ and some m > 0, and let $b = \max\{f(x): 0 \le x \le m\} \int_0^1 g(s) ds$. Then A(B) is uniformly bounded. Thus we have $\|Ax\| \le bM$ for $x \in B$. To see A(B) is compact, it is sufficient to prove that A(B) is equicontinuous. In fact, since G(t,s) is uniformly continuous for any $(t,s) \in [0,1] \times [0,1]$, for any $\varepsilon > 0$ there exists a $\delta > 0$ such that $|G(t_1,s) - G(t_2,s)| < \varepsilon b^{-1}$ for $|t_1 - t_2| < \delta$ and $s \in [0,1]$. This implies that $|Au(t_1) - Au(t_2)| \le \int_0^1 |G(t_1,s) - G(t_2,s)| g(s) f(u(s)) ds < \varepsilon$.

Assume that (A_3) holds, by the first part of (A_3) , there exists a $\rho > 0$ such that $f(x) \leq M_1 \rho$ for $0 \leq x \leq \rho$. So for every $u \in \partial K_{\rho}$, we have

$$Au(t) = -\int_{0}^{1} G(t, s)g(s)f(u(s))ds \le M_{1}\rho \int_{0}^{1} -G(t, s)g(s)ds \le \rho = ||u||.$$

This implies $||Au|| \le ||u||$ for every $u \in \partial K_{\rho}$.

By the second part of (A₃), there exists an $\eta > \gamma \rho$ such that $f(x) \ge m_1 x$ for $x \ge \eta$. Let $r = \gamma^{-1} \eta$. Then we have

$$\min\{u(t): a \le t \le b\} \ge \gamma \|u\| = \eta$$
, for $u \in \partial K_r$.

Let $\phi(t) \equiv 1$, for $t \in [0, 1]$. Then $\phi \in \partial K_1$. We prove that

$$u \neq Au + \lambda \phi$$
, for $u \in \partial K_r$ and $\lambda > 0$.

In fact, if not, there exist $u_0 \in \partial K_r$ and $\lambda_0 > 0$ such that $u_0 = Au_0 + \lambda_0 \phi$. Let $\mu = \min\{u_0(t) : a \le t \le b\} \ge \eta$. Then we have, for $a \le t \le b$,

$$u_0(t) = -\int_0^1 G(t, s)g(s)f(u_0(s))ds + \lambda_0\phi(t)$$

$$\geq m_1 \int_a^b -G(t, s)g(s)u_0(s)ds + \lambda_0$$

$$\geq m_1 \mu \int_a^b -G(t, s)g(s)ds + \lambda_0$$

$$\geq \mu + \lambda_0.$$

This implies $\mu \ge \mu + \lambda_0 > \mu$, a contradiction. It follows from Lemma 1.1 that A has a fixed point $u \in \overline{K}_{\rho, r}$.

Theorem 2.2. Assume that conditions (A_1) , (A_2) and (A_4) hold. Then BVP (1.1)-(1.2) has at least one positive solution u(t) with $u(t) \neq 0$ for $t \in [0, 1]$.

Proof. Assume that (A_4) holds. Choose some $\beta \in (f^{\infty}, M_1)$. By the first part of (A_4) there exists an $r_1 > 0$ such that $f(x) \leq \beta x$ for $x \geq r_1$. Since

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f is continuous, we have $c = \max\{f(x) : 0 \le x \le r_1\} < \infty$. Hence $0 \le f(x) \le c + \beta x$ for $0 \le x < \infty$. Let $r = c(M_1 - \beta)^{-1}$ and $P_r = \{x \in K \mid ||x|| < r\}$. Then we have for $z \in \partial P_r$,

$$|Az(t)| \le (c + \beta ||z||) \int_0^1 |G(t, s)| g(s) ds \le \frac{c + \beta ||z||}{M_1} = r = ||z||.$$

This implies $\|Az\| \le \|z\|$ for every $z \in \partial P_r$. On the other hand, by the last part of (A_4) there exists a $\rho \in (0, r)$ such that $f(x) \ge m_1 x$ for $0 \le x \le \rho$. By a similar argument to that used in Theorem 2.1 we have $z \ne Az + \lambda \phi$ for $z \in \partial P_\rho$ and $\lambda > 0$. The result follows from Lemma 1.1.

Remark 2.1. In the proof of Theorem 2.1 and also of Theorem 2.2 one of the key steps is to find the function ϕ , which is difficult to obtain by using norm-type cone expansion and compression theorem.

Remark 2.2. In Theorem 2.1 or Theorem 2.2 if g satisfies the condition (A'_2) , then we have for any $u \in K$,

$$(R_1) (Au)^{(n)}(t) = -g(t) f(u(t)) \text{ for } t \in E,$$

$$(R_2)$$
 $Au(t) \in C^n(E) \cap C^{n-2}[0, 1].$

3. Application

As an application of Theorem 2.1 or Theorem 2.2, we consider the following eigenvalue problem

$$u^{(n)}(t) + \lambda g(t)f(u(t)) = 0, \tag{3.1}$$

with the boundary condition (1.2). We list the following conditions:

(P)
$$\int_{\eta}^{1} g(s) ds > 0;$$

(P₁)
$$f_{\infty} > 0$$
, $f^{0} \neq \infty$ and $m_{1}/f_{\infty} < M_{1}/f^{0}$;

(P2)
$$f^{\infty} \neq \infty$$
, $f_0 > 0$ and $m_1/f_0 < M_1/f^{\infty}$.

We write $m_1/f_{\beta}=0$ if $f_{\beta}=\infty$ and $M_1/f^{\beta}=\infty$ if $f^{\beta}=0$, where $\beta=0,\infty$.

We have the following new result on existence for the eigenvalue problem (3.1).

Theorem 3.1. Assume that (P) and (P₁) hold. Then for every $\lambda \in (m_1/f_\infty, M_1/f^0)$, equation (3.1) with (1.2) has a solution u with $u \ge 0$ for $t \in [0, 1]$ and $u(t) \ne 0$ on [0, 1]. The same result remains valid for every $\lambda \in (m_1/f_0, M_1/f^\infty)$, if (P) and (P₂) hold.

Proof. If (P_1) holds, $0 < \lambda f^0 < M_1$ and $\lambda f_{\infty} > m_1$, then similar to the proof of Theorem 2.1, it is easy to prove Theorem 3.1.

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