



## QUANTUM COVARIANCES AND SCHRÖDINGER TYPE OF UNCERTAINTY RELATION

**Eunsang Kim and Tae Ryong Park\***

Department of Applied Mathematics

Hanyang University

Ansan Kyunggi-do, Korea

Department of Computer Engineering

Seokyeong University

Seoul, Korea

### Abstract

In this paper, we study relations between quantum covariances, anti-symmetric covariance and symmetric covariance. From the relation, we derive a type of Schrödinger uncertainty relation and this can be seen as a refinement of the relation, which is given in [5].

### 1. Introduction

Heisenberg uncertainty relation and Schrödinger uncertainty relation have been reinterpreted using quantum covariances as studied in [3-5] and many other papers. In this paper, we first review the various definitions of covariances given in [6]. Using the properties of operator monotone functions, we study relations between those covariances such as covariance,

---

Received: October 18, 2017; Accepted: November 22, 2017

2010 Mathematics Subject Classification: 62B10.

Keywords and phrases: quantum covariances, uncertainty relations.

This work was supported by Seokyeong University in 2015.

\*Corresponding author

quantum covariance, antisymmetric covariance and symmetric covariance. Such relations will give us a useful inequality which leads to a refinement of Schrödinger uncertainty relation which is given in [5] and [2].

## 2. Operator Monotone Functions

Let  $M_n = M_n(\mathbb{C})$  be the set of all  $n \times n$  complex matrices and let  $M_n^{\text{sa}} = \{A \in M_n \mid A^* = A\}$  be the set of all self-adjoint matrices, endowed with the Hilbert-Schmidt scalar product  $\langle A, B \rangle_{\text{HS}} = \text{Tr}(A^* B)$ ,  $A, B \in M_n$ . Let  $\mathcal{D}_n$  be the set of strictly positive matrices in  $M_n$  and let  $\mathcal{D}_n^1 \subset \mathcal{D}_n$  be the set of positive density matrices;  $\mathcal{D}_n^1 = \{\rho \in \mathcal{D}_n \mid \text{Tr } \rho = 1\}$ . Note that  $\mathcal{D}_n$  and  $\mathcal{D}_n^1$  are differentiable manifolds and the tangent space of  $\mathcal{D}_n$  at  $\rho$  can be identified with  $M_n^{\text{sa}}$  and the tangent space of  $\mathcal{D}_n^1$  at  $\rho$  is  $M_n^{\text{sa},0} = \{A \in M_n^{\text{sa}} \mid \text{Tr } A = 0\}$ .

A function  $f : (0, +\infty) \rightarrow \mathbb{R}^+$  is said to be *operator monotone* if, for any natural number  $n$  and  $A, B \in M_n^{\text{sa}}$  such that  $0 \leq A \leq B$ , the inequalities  $0 \leq f(A) \leq f(B)$  hold. An operator monotone function  $f$  is called *normalized* if  $f(1) = 1$  and *symmetric* if  $f(x) = xf\left(\frac{1}{x}\right)$ . Let  $\mathcal{F}_{\text{op}}$  be the set of symmetric, normalized operator monotone functions  $f : (0, +\infty) \rightarrow \mathbb{R}^+$ . Examples of elements in  $\mathcal{F}_{\text{op}}$  are the following:

$$f_{\text{rd}}(x) := \frac{2x}{1+x} \quad \text{and} \quad f_{\text{sd}}(x) := \frac{1+x}{2}.$$

For any  $f \in \mathcal{F}_{\text{op}}$ , for all  $x > 0$ ,

$$f_{\text{rd}}(x) \leq f(x) \leq f_{\text{sd}}(x). \quad (1)$$

For  $f \in \mathcal{F}_{\text{op}}$ , define  $f(0) = \lim_{x \rightarrow 0} f(x)$ . Then for any  $f \in \mathcal{F}_{\text{op}}$  and  $x \geq 0$ , we have

$$f(0)(1+x) \leq f(x) \leq \frac{1}{2}(1+x). \quad (2)$$

Define

$$\mathcal{F}_{\text{op}}^r := \{f \in \mathcal{F}_{\text{op}} \mid f(0) \neq 0\}, \quad \mathcal{F}_{\text{op}}^n := \{f \in \mathcal{F}_{\text{op}} \mid f(0) = 0\}.$$

Obviously one has  $\mathcal{F}_{\text{op}} = \mathcal{F}_{\text{op}}^r \cup \mathcal{F}_{\text{op}}^n$  and  $\mathcal{F}_{\text{op}}^r \cap \mathcal{F}_{\text{op}}^n = \emptyset$ .

For  $f \in \mathcal{F}_{\text{op}}^r$  and  $x > 0$ , let

$$\tilde{f}(x) = \frac{1}{2} \left[ (x+1) - (x-1)^2 \frac{f(0)}{f(x)} \right].$$

Then  $\tilde{f} \in \mathcal{F}_{\text{op}}^n$  and this gives the bijection between  $\mathcal{F}_{\text{op}}^r$  and  $\mathcal{F}_{\text{op}}^n$ . For example,  $\tilde{f}_{\text{sd}}(x) = f_{\text{rd}}(x)$  and hence

$$\tilde{f}_{\text{sd}}(x) \leq f(x) \leq f_{\text{sd}}(x).$$

For  $f, g \in \mathcal{F}_{\text{op}}^r$ ,

$$\begin{aligned} \tilde{f} \leq \tilde{g} &\Rightarrow \frac{1}{2} \left[ (x+1) - (x-1)^2 \frac{f(0)}{f(x)} \right] \leq \frac{1}{2} \left[ (x+1) - (x-1)^2 \frac{g(0)}{g(x)} \right] \\ &\Rightarrow \frac{f(0)}{f(x)} \geq \frac{g(0)}{g(x)} \\ &\Rightarrow \frac{f(x)}{f(0)} \leq \frac{g(x)}{g(0)}. \end{aligned} \quad (3)$$

For each  $f \in \mathcal{F}_{\text{op}}$ , we define the *mean function*  $m_f : \mathbb{R}^+ \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$  by

$$m_f(x, y) = yf(xy^{-1}) \text{ for } x, y \in \mathbb{R}^+.$$

For example, if  $f(x) = f_{\text{rd}}(x) = \frac{2x}{1+x}$ , then  $m_f(x, y) = \frac{2xy}{x+y}$  and if  $f(x) = \frac{1+x}{2}$ , then  $m_f(x, y) = \frac{x+y}{2}$ . By definition, for all  $f, g \in \mathcal{F}_{\text{op}}$  and  $x, y \in \mathbb{R}^+$ ,

$$f \leq g \Rightarrow m_f(x, y) \leq m_g(x, y).$$

Thus, by (1), (2), we have for each  $f \in \mathcal{F}_{\text{op}}$ ,

$$\frac{2xy}{x+y} \leq m_f(x, y) \leq \frac{x+y}{2}, \quad (4)$$

$$f(0)(x+y) \leq m_f(x, y) \leq \frac{x+y}{2}. \quad (5)$$

We may extend the mean function to  $\mathbb{R}^+ \cup \{0\}$  and we have for  $f \in \mathcal{F}_{\text{op}}^r$ ,

$$\begin{aligned} m_{\tilde{f}}(x, y) &= y\tilde{f}(xy^{-1}) \\ &= \frac{y}{2} \left[ \frac{x}{y} + 1 - \left( \frac{x}{y} - 1 \right)^2 \frac{f(0)}{f(x)} \right] \\ &= \frac{x+y}{2} - \frac{f(0)(x-y)^2}{2m_f(x, y)}. \end{aligned} \quad (6)$$

**Proposition 1.** *Let  $f \in \mathcal{F}_{\text{op}}$ . Then for each  $x, y \in \mathbb{R}^+$  such that  $x - y \geq 0$ , we have*

$$\frac{x+y}{2} - m_{\tilde{f}}(x, y) \leq \frac{1}{2}(x-y). \quad (7)$$

**Proof.** By (6),  $\frac{x+y}{2} - m_{\tilde{f}}(x, y) = \frac{f(0)(x-y)^2}{2m_f(x, y)}$  and by (2), we have

$f(0)(x+y) \leq m_f(x, y)$ . Thus,

$$\begin{aligned} \frac{1}{m_f(x, y)} &\leq \frac{1}{f(0)(x+y)} \Rightarrow \frac{f(0)}{2m_f(x, y)} \leq \frac{1}{2(x+y)} \\ &\Rightarrow \frac{f(0)(x-y)}{2m_f(x, y)} \leq \frac{x-y}{2(x+y)} \leq \frac{1}{2} \end{aligned}$$

and hence

$$\frac{f(0)(x-y)^2}{2m_f(x, y)} \leq \frac{1}{2}(x-y). \quad \square$$

**Proposition 2.** For  $f \in \mathcal{F}_{op}$ , we have the following inequality:

$$f(0)^2(x-y)^2 \leq \frac{f(0)(x-y)^2}{2m_f(x, y)} \frac{f(0)(x+y)^2}{2m_f(x, y)}. \quad (8)$$

**Proof.** By (4),  $\frac{1}{x+y} \leq \frac{1}{m_f(x, y)}$ . Thus,

$$f(0)(x+y) \leq \frac{f(0)(x+y)^2}{2m_f(x, y)}$$

and

$$\begin{aligned} \frac{f(0)(x-y)^2}{2m_f(x, y)} \frac{f(0)(x+y)^2}{2m_f(x, y)} &\geq \frac{f(0)(x-y)^2}{2m_f(x, y)} \cdot f(0)(x+y) \\ &\geq f(0)^2(x-y)^2. \end{aligned} \quad \square$$

### 3. Monotone Metrics and Covariances

For each  $f \in \mathcal{F}_{op}$ , one may associate the *monotone family of metrics* on the manifold  $\mathcal{D}_n$  [7, 8]. For  $A, B \in M_n^{\text{sa}}$  and  $\rho \in \mathcal{D}_n^1$ , the metric is defined by

$$\langle A, B \rangle_{\rho, f} = \text{Tr}(A m_f(L_\rho, R_\rho)(B)),$$

where  $L_\rho(A) = \rho A$  and  $R_\rho(A) = A\rho$ .

By extending operator monotone functions to complex analytic functions on a neighborhood of  $\mathbb{R}^+$ , one may have the Riesz-Dunford operator calculus (cf. [1]):

$$f(\rho) = \frac{1}{2\pi i} \int_C f(\xi) (\xi - \rho)^{-1} d\xi,$$

where the spectrum of  $\rho$  is contained in  $C$ . The operators  $L_\rho$  and  $R_\rho$  are positive definite with respect to the Hilbert-Schmidt inner product on  $M_n$ . Then

$$f(L_\rho) = \int_C f(\xi) (\xi \text{Id} - L_\rho)^{-1} d\xi$$

and

$$m_f(L_\rho, R_\rho)(B) = \frac{1}{(2\pi i)^2} \iint_C m_f(\xi, \eta) (\xi - \rho)^{-1} B (\eta - \rho)^{-1} d\xi d\eta.$$

Along the lines of [6], we have

**Proposition 3.** *Let  $\rho = \text{Diag}(\lambda_1, \lambda_2, \dots, \lambda_n) \in \mathcal{D}_n^1$  and  $A, B \in M_n^{\text{sa}}$ . Then for all  $f \in \mathcal{F}_{op}$ , we have*

$$\langle A, B \rangle_{\rho, f} = \sum_{k, l=1}^n m_f(\lambda_k, \lambda_l)^{-1} A_{lk} B_{kl}. \quad (9)$$

**Proof.** For  $A \in M_n$ , we can write

$$A = \sum_{i, j=1}^n A_{ij} E_{ij},$$

where  $E_{ij}$  is the  $n \times n$  matrix which is all entries except  $(ij)$ -entry are zero.

First we have

$$\begin{aligned}
\langle E_{ij}, E_{kl} \rangle_{\rho, f} &= \text{Tr}(E_{ij} m_f(L_\rho, R_\rho)^{-1}(E_{kl})) \\
&= \frac{1}{(2\pi i)^2} \text{Tr} \iint_C \frac{1}{m_f(\xi, \eta)} E_{ij}(\xi - \rho)^{-1} E_{kl}(\eta - \rho)^{-1} d\xi d\eta \\
&= \delta_{kj} \delta_{li} \frac{1}{m_f(\xi, \eta)}. \tag{10}
\end{aligned}$$

Since  $A = \sum_{i,j=1}^n A_{ij} E_{ij}$  and  $B = \sum_{k,l=1}^n B_{kl} E_{kl}$ , we have

$$\begin{aligned}
\langle A, B \rangle_{\rho, f} &= \sum_{i,j,k,l=1}^n \delta_{kj} \delta_{li} \frac{1}{m_f(\xi, \eta)} A_{ij} B_{kl} \\
&= \sum_{k,l=1}^n A_{lk} B_{kl} m_f(\lambda_k, \lambda_l)^{-1}. \quad \square
\end{aligned}$$

For  $A, B \in M_n^{\text{sa}}$  and  $\rho = \text{Diag}(\lambda_1, \dots, \lambda_n)$ , the *covariance* of  $A$  and  $B$  is defined by

$$\begin{aligned}
\text{Cov}_\rho(A, B) &= \frac{1}{2} \text{Tr}(\rho AB + \rho BA) - \text{Tr}(\rho A) \text{Tr}(\rho B) \\
&= \sum_{k,l=1}^n \frac{\lambda_k + \lambda_l}{2} A_{lk} B_{kl} - \text{Tr}(\rho A) \text{Tr}(\rho B) \\
&= \sum_{k,l=1}^n \frac{\lambda_k + \lambda_l}{2} [A_0]_{lk} [B_0]_{kl}, \tag{11}
\end{aligned}$$

where  $A_0 = A - \text{Tr}(\rho A)I$ . In what follows, we only consider the matrices satisfying  $\text{Tr}(\rho A) = 0$ . Let  $\text{Cov}_\rho(A, A) = V_\rho(A)$ . Then by the Cauchy-Schwarz inequality, we get

$$V_\rho(A) V_\rho(B) \geq |\text{Cov}_\rho(A, B)|^2.$$

The Heisenberg uncertainty relation is given by

$$V_{\rho}(A)V_{\rho}(B) \geq \frac{1}{4} |\text{Tr}(\rho[A, B])|^2$$

and the Schrödinger uncertainty relation is then

$$V_{\rho}(A)V_{\rho}(B) - |\text{Cov}_{\rho}(A, B)|^2 \geq \frac{1}{4} |\text{Tr}(\rho[A, B])|^2,$$

where  $[A, B] = AB - BA$ .

For  $f \in \mathcal{F}_{\text{op}}$ , the *quantum  $f$ -covariance* of  $A$  and  $B$ , introduced in [5], is

$$\begin{aligned} \text{Cov}_{\rho}^f(A, B) &= \text{Tr}(A m_f(L_{\rho}, R_{\rho})(B)) \\ &= \sum_{k, l=1}^n m_f(\lambda_k, \lambda_l) A_{lk} B_{kl}, \end{aligned} \quad (12)$$

where the local form of the quantum covariance can be obtained as in the proof of Proposition 2.

The *antisymmetric  $f$ -covariance*, which was given in [6], is defined as

$$I_{\rho}^f(A, B) = \frac{f(0)}{2} \langle i[\rho, A], i[\rho, B] \rangle_{\rho, f}. \quad (13)$$

**Proposition 4.** For  $A, B \in \mathbf{M}_n^{\text{sa}}$  and  $\rho = \text{Diag}(\lambda_1, \lambda_2, \dots, \lambda_n) \in \mathcal{D}_n^1$ ,

$$I_{\rho}^f(A, B) = \text{Cov}_{\rho}(A, B) - \text{Cov}_{\rho}^{\tilde{f}}(A, B). \quad (14)$$

**Proof.** Since  $\rho = \text{Diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$ , we have

$$\begin{aligned} I_{\rho}^f(A, B) &= \frac{f(0)}{2} \langle i[\rho, A], i[\rho, B] \rangle_{\rho, f} \\ &= \frac{f(0)}{2} \text{Tr}([\rho, A] m_f(L_{\rho}, R_{\rho})([\rho, B])) \\ &= \frac{f(0)}{2} \sum_{k, l=1}^n [\rho, A]_{kl} [\rho, B]_{lk} m_f(\lambda_k, \lambda_l) \end{aligned}$$



$$\begin{aligned}
&= \frac{f(0)}{2} \sum_{k,l=1}^n \frac{(\lambda_k - \lambda_l)^2}{m_f(\lambda_k, \lambda_l)} A_{lk} B_{kl} \\
&= \sum_{k,l=1}^n \frac{f(0)(\lambda_k - \lambda_l)^2}{2m_f(\lambda_k, \lambda_l)} A_{lk} B_{kl} \\
&= \sum_{k,l=1}^n \left[ \frac{\lambda_k + \lambda_l}{2} - m_{\tilde{f}}(\lambda_k, \lambda_l) \right] A_{lk} B_{kl} \\
&= \text{Cov}_{\rho}(A, B) - \text{Cov}_{\rho}^{\tilde{f}}(A, B). \quad \square
\end{aligned}$$

By Proposition 1, we get

$$\begin{aligned}
|I_{\rho}^f(A, B)| &= \left| \sum_{k,l=1}^n \frac{\lambda_k + \lambda_l}{2} - m_{\tilde{f}}(\lambda_k, \lambda_l) \right| |A_{lk}| |B_{kl}| \\
&\leq \frac{1}{2} \left| \sum_{k,l=1}^n |\lambda_k - \lambda_l| |A_{lk}| |B_{kl}| \right| = \frac{1}{2} |\text{Tr}(\rho[A, B])|. \quad (15)
\end{aligned}$$

Finally, we improve the inequality given in [5].

**Theorem 1.** Let  $A, B \in M_n^{\text{sa}}$  and  $\rho = \text{Diag}(\lambda_1, \lambda_2, \dots, \lambda_n) \in \mathcal{D}_n^1$ .

Suppose that  $f, g \in \mathcal{F}_{op}^r$  such that  $\tilde{f} \leq \tilde{g}$ . Then

$$\text{Cov}_{\rho}(A, B) \leq \frac{1}{2f(0)} \text{Cov}_{\rho}^f(A, B) \leq \frac{1}{2g(0)} \text{Cov}_{\rho}^g(A, B).$$

**Proof.** By (3), we have  $\frac{f(x)}{f(0)} \leq \frac{g(x)}{g(0)}$  and by the property of mean function

$$\frac{1}{f(0)} m_f(x, y) \leq \frac{1}{g(0)} m_g(x, y).$$

Thus, the second equality follows. By (2),  $f(0)(1+x) \leq f(x)$ . Thus,

$$\frac{f(0)(1+x)}{2} \leq \frac{f(x)}{2} \Rightarrow \frac{(1+x)}{2} \leq \frac{f(x)}{2f(0)}$$

and hence the first inequality follows from

$$\frac{x+y}{2} \leq \frac{m_f(x, y)}{2f(0)}. \quad \square$$

The *symmetric  $f$ -covariance*, which was introduced in [6], is given as

$$J_{\rho}^f(A, B) = \frac{f(0)}{2} \langle \{\rho, A\}, \{\rho, B\} \rangle_{\rho, f}, \quad (16)$$

where  $\{A, B\} = AB + BA$ . The local form of the symmetric  $f$ -covariance can written as

$$J_{\rho}^f(A, B) = \frac{f(0)}{2} \sum_{k,l=1}^n \frac{(\lambda_k + \lambda_l)^2}{m_f(\lambda_k, \lambda_l)} A_{lk} B_{kl}. \quad (17)$$

Now we prove the main theorem which can be seen as a Schrödinger type of uncertainty relation.

**Theorem 2.** Let  $A, B \in M_n^{\text{sa}}$  and  $\rho = \text{Diag}(\lambda_1, \lambda_2, \dots, \lambda_n) \in \mathcal{D}_n^1$ . For all  $f \in \mathcal{F}_{op}^r$ , we have

$$f(0)^2 |I_{\rho}^f(A, B)|^2 \leq \frac{1}{4} I_{\rho}^f(A) J_{\rho}^f(B).$$

**Proof.** By (15) and Proposition 2,

$$\begin{aligned} & f(0)^2 |I_{\rho}^f(A, B)|^2 \\ & \leq \frac{1}{4} \sum_{k,l=1}^n f(0)^2 |\lambda_k - \lambda_l|^2 |A_{lk}|^2 |B_{kl}|^2 \\ & \leq \frac{1}{4} \sum_{k,l=1}^n \frac{f(0)(\lambda_k - \lambda_l)^2}{2m_f(\lambda_k, \lambda_l)} \frac{f(0)(\lambda_k + \lambda_l)^2}{2m_f(\lambda_k, \lambda_l)} |A_{lk}|^2 |B_{kl}|^2 \end{aligned}$$

$$\begin{aligned}
&\leq \frac{1}{4} \sum_{k,l=1} \frac{f(0)(\lambda_k - \lambda_l)^2}{2m_f(\lambda_k, \lambda_l)} |A_{lk}|^2 \frac{1}{4} \sum_{k,l=1} \frac{f(0)(\lambda_k + \lambda_l)^2}{2m_f(\lambda_k, \lambda_l)} |B_{kl}|^2 \\
&\leq \frac{1}{4} I_{\rho}^f(A) J_{\rho}^f(B). \quad \square
\end{aligned}$$

### References

- [1] J. Dittmann, On the curvature of monotone metrics and a conjecture concerning the Kubo-Mori metric, *Linear Algebra Appl.* 315 (2000), 83-112.
- [2] S. Furuichi and K. Yanagi, Schrödinger uncertainty relation, Wigner-Yanase-Dyson skew information and metric adjusted correlation measure, *J. Math. Anal. Appl.* 388 (2012), 1147-1156.
- [3] P. Gibilisco, D. Imparato and T. Isola, Uncertainty principle and quantum Fisher information II, *J. Math. Phys.* 59 (2007), 147-159.
- [4] P. Gibilisco and T. Isola, Uncertainty principle and quantum Fisher information, *Ann. Inst. Statist. Math.* 48 (2007), 072109.
- [5] P. Gibilisco and T. Isola, How to distinguish quantum covariances using uncertainty relations, *J. Math. Anal. Appl.* 384 (2011), 670-676.
- [6] A. Lovas and A. Andai, Refinement of Robertson-type uncertainty principles with geometric interpretation, *Int. J. Quantum Inf.* 14 (2016), 1650013, 15 pp.
- [7] D. Petz, Monotone metrics on matrix spaces, *Linear Algebra Appl.* 244 (1996), 81-96.
- [8] D. Petz and Cs. Sudár, Geometries of quantum states, *J. Math. Phys.* 37 (1996), 2662-2673.