### 1. Personal Particulars

Mouquan Shen received the Ph.D. degree in Control Theory and Control Engineering from the College of Information Science and Engineering, Northeastern University, Shenyang, China, in 2011. From 2012, he was with the College of Electrical Engineering and Control of Science of Nanjing Technology University, Nanjing, China. From 2015 to 2017, he was an visiting scholar with The Yeungnam University, The University of Hong Kong, HongKong, and The University of Adelaide, respectively. Since 2018, he has been a full Professor with the Nanjing Tech University, China.

He is a member of Chinese Association of Automation and research interests cover Markov jump systems, adaptive control, data-driven-based control, robust control, and interactive learning control. He has published over 60 international journal papers and received over 1000 citations with h-index of 21. He is currently the Associate Editors of Mathematical Problems in Engineering and International Journal of Robotics and Control Systems, Editorial Board Members of International Journal of Sensors, Wireless Communications and Control, and International Journal of Control, Automation, Communication and Systems, Journal of Electrical and Electronic Engineering, and Advances in International Applied Mathematics (Chinese).

## 2. Research Interests/Experiences

#### 1). Research Interests

- Iterative learning control
- Adaptive control
- Markov jump linear systems
- Switched systems
- Networked control systems
- Quantized control
- Sliding mode control
- Event-triggered control
- Model free control

#### 2). Research Experiences

- Dec. 2014-Jan. 2015, Yeungnam University, Korea, J.H Park.
- Nov. 2015-Mar. 2016, The University of HongKong, HongKong, James Lam.
- May 2016-May 2017, The University of Adelaide, Australia, Peng Shi.
- Aug. 2012- , Nanjing Technology University, China.

# 3. Professional activities

### 1). Editorial experiences

- Mathematical Problems in Engineering, Associate Editor
- International Journal of Robotics and Control Systems, Associate Editor
- International Journal of Sensors, Wireless Communications and Control, Editorial Board Member
- International Journal of Control, Automation, Communication and Systems, Editorial Board Member
- Journal of Electrical and Electronic Engineering, Editorial Board Member
- Advances in International Applied Mathematics (Chinese), Editorial Board Member

### 2). Review panels

- Automatica
- IEEE Transactions on Automatic Control
- IEEE Transactions on Systems, Man and Cybernetics: Systems
- IEEE Transactions on Neural Networks and Learning Systems
- IEEE Transactions on Industrial Informatics
- IEEE Transactions on Circuits and Systems I: Regular Papers
- IEEE Transactions on Circuits and Systems II: Express Briefs
- IEEE Transactions on Cybernetics
- Fuzzy set and systems
- IET Control Theory and Application
- Nonlinear Dynamics
- International Journal of Systems Science
- Journal of the Franklin Institute
- Applied Mathematics and Computation
- Optimal Control, Applications and Methods
- Asian Journal of Control
- Peer-to-Peer Networking and Applications

- International Journal of Robust and Nonlinear Control
- Circuit System & Signal Processing
- Neurocomputing
- Nonlinear Analysis: Hybrid Systems
- International Journal of Control, Automation and Systems
- Transactions of the Institute of Measurement and Control
- ISA Transactions
- Information Technology and Control

# 4. Publication List

- [1] Mouquan Shen<sup>\*</sup>, Yang Gu, Ju Η Park, Yang Yi, Wei-Wei of Che. Composite control linear systems with event-triggered inputand IEEE Transactions on Circuits and Systems II: Express Briefs.  $\mathbf{S}$ outputs. DOI:10.1109/TCSII.2021.3098820, 2021.
- [2] Mouquan Shen\*, Yongsheng Ma, Ju H. Park, Qing-Guo Wang. Fuzzy tracking control for Markov jump systems with mismatched faults by iterative proportional-integral observers. *IEEE Transactions on Fuzzy Systems*, DOI:10.1109/TFUZZ.2020.3041589, 2020.
- [3] Mouquan Shen<sup>\*</sup>, Yang Gu, Ju H. Park, Qing-Guo Wang, Sing Kiong Nguang. H<sub>∞</sub> control of uncertain linear systems with a triggering threshold dependent approach. <u>Information Sciences</u>, vol. 540, pp. 278 - 291, 2020.
- [4] Yang Gu, **Mouquan Shen**<sup>\*</sup>, Yuesheng Ren, Hongxia Liu.  $H_{\infty}$  finite-time control of unknown uncertain systems with actuator failure. <u>Applied Mathematics and Computation</u>, DOI:10.1016/j.amc.2020.125375, 2020.
- [5] Yongsheng Ma, Mouquan Shen<sup>\*</sup>, Haiping Du, Yuesheng Ren, Guangrui Bian. An iterative observer-based fault estimation for discrete-time TSfuzzy systems. International Journal of Systems Science, vol. 51, pp. 1007 - 1018, 2020.
- Shen<sup>\*</sup>, [6] Mouquan Hainan Zhang, Sing Kiong Nguang, Choon Ki Ahn.  $H_{\infty}$ output anti-disturbance control of stochastic Markov jump systems with multiple disturbances. IEEE Transactions on Systems, Man, and Cybernetics: Systems, DOI:10.1109/TSMC.2020.2981112, 2020.
- [7] Shen Yan, **Mouquan Shen**<sup>\*</sup>, Sing Kiong Nguang, Guangming Zhang. Eventtriggered  $H_{\infty}$  control of networked control systems with distributed transmission delay. <u>IEEE Transactions on Automatic Control</u>, vol. 65, pp. 4295 - 4301, 2020.
- [8] Zhong Zhen<sup>\*</sup>, **Mouquan Shen**. Inertial vector measurements based attitude synchronization control for multiple spacecraft formation. <u>Aerospace Science and Technology</u>, DOI:10.1016/j.ast.2019.105309, 2019.
- [9] Xuanxuan Shi, Mouquan Shen\*. A new approach to feedback feed-forward iterative learning control with random packet dropouts. <u>Applied Mathematics and Computation</u>, vol. 348, pp. 399-412, 2019.

- [10] Hainan Zhang, **Mouquan Shen**<sup>\*</sup>. Sliding mode control of time?varying delay Markov jump with quantized output. *Optimal Control Applications and Methods*, vol. 40, pp. 226 240, 2019.
- [11] Aihua Chen, Mouquan Shen<sup>\*</sup>. A new method to reliable  $H_{\infty}$  control of nonlinear stochastic systems with actuator faults. *International Journal of Fuzzy Systems*, vol. 21, pp. 60 71, 2019.
- [12] Shen Yan, Mouquan Shen, Sing Kiong Nguang, Guangming Zhang\*, Liruo Zhang. A distributed delay method for event-triggered control of TS fuzzy networked systems with transmission delay. *IEEE Transactions on Fuzzy Systems*, vol. 27, pp. 1963 - 1973, 2019.
- [13] Shen Yan, **Mouquan Shen**, Guangming Zhang<sup>\*</sup>, Sing Kiong Nguang. Reliable  $H_{\infty}$  output control of nonlinear systems with dynamic event-triggered scheme. Journal of the Franklin Institute, vol. 356, pp. 58-79, 2019.
- [14] Mouquan Shen<sup>\*</sup>, Shen Yan, Yonghui Sun, Guangming Zhang. Nonfragile  $H_{\infty}$  output feedback control of linear systems with an event-triggered scheme against unreliable communication links. *ISA Transactions*, vol. 84, pp. 96 - 103, 2019.
- [15] Li-Wei Li, Mouquan Shen<sup>\*</sup>, Wen Qin. Simultaneous fault detection and control for Markovian jump systems with general uncertain transition rates. International Journal of Control, Automation and Systems, vol. 16 pp. 2074 - 2081, 2018.
- [16] Mouquan Shen, Ju H.Park<sup>\*</sup>, ShuminFei. Event-triggered nonfragile  $H_{\infty}$  filtering of Markov jump systems with imperfect transmissions. *Signal Processing*, vol. 149, pp. 204-213, 2018.
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- Cheng-Chew Shi<sup>\*</sup>.  $H_{\infty}$ [22] Mouquan Shen, Lim, Peng Reliable  $\operatorname{static}$ outlinear time-varving delay put control of systems against sensor failures. International Journal of Robust and Nonlinear Control, vol. 27, pp. 3109 - 3123, 2017.
- [23] Song Zhu\*, Mouquan Shen, Cheng-Chew Lim. Robust input-to-state stability of neural networks with Markovian switching in presence of random disturbances or time delays. *Neurocomputing*, vol. 249, pp. 245 - 252, 2017.
- [24] Lingchun Li, **Mouquan Shen**<sup>\*</sup>, Guangming Zhang, Shen Yan.  $H_{\infty}$  control of Markov jump systems with time-varying delay and incomplete transition probabilities. *Applied Mathematics and Computation*, vol. 301, pp. 95 106, 2017.

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- [28] Shen Yan, Mouquan Shen\*, Guangming Zhang\*. Extended event-driven observer-based output control of networked control systems. *Nonlinear Dynamics*, vol. 86, pp. 1639 - 1648, 2016.
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